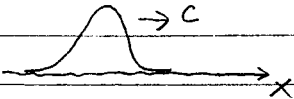


• $u = A e^{i(\omega t - kx)}$ satisfies the kinematic equ

$u_t + c u_x = 0$ $c = \frac{\omega}{k} = \omega t = \text{"wave speed"}$

this is an example of solutions (waves) that satisfy some equations.
In general,

$u = f(x - ct)$  bump/perturbation that propagates at speed c

Generalizations of the previous equation:

$u_t + c(u) u_x = 0$

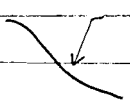
- $c(u) = u \Rightarrow u_t + u u_x = 0$
- $u_t + u u_x = \nu u_{xx}$ Burgers' equ.


the common concept is a wave-like solution.

February 9, 2004 Lecture 2

Optional Reading Kevorkian § 5.1, 5.2
Debnath § 3.2-3.5

Review of Lec. 1:

IVP data on \mathcal{L}
 \mathcal{L} : smooth, open

BVP data on C
 C : closed curve

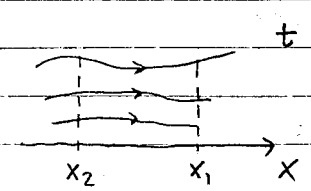
Well-posed problem: ① Solution exists
 and ② " is unique
 and ③ " depends continuously on data } \neq Ill-posed problem

THEME : PDE \Rightarrow ODE both for linear and nonlinear PDE

Useful concept: Wave Simplest PDE: $u_t + c u_x = 0$ $c = \frac{\omega}{k}$ frequency
(help understand Modify \downarrow speed. wave #
the solution before actually find it) $u_t + c(u) u_x = 0$

PDE's describe natural phenomena, or rather, our understanding of them
 -11- are based on principles (physical principles)

Ex.: Conservation law (principle)
 (of "mass")



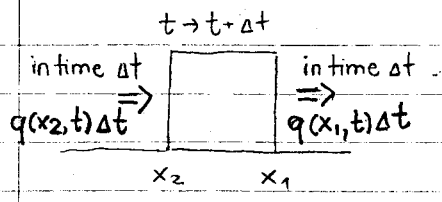
material (fluid) moves
 its mass should be conserved

useful quantities:

- $\rho(x,t)$: density [mass/length]
- $q(x,t)$: flux [mass/time]

Principle of conservation of mass

we can relate these two quantities using the PCM.



(i) Total mass that remains in
 in time Δt :

$$[q(x_2, t) - q(x_1, t)] \Delta t$$

(ii) Mass inside the box at instant t : $-\int_{x_1}^{x_2} \rho(x, t) dx = \int_{x_2}^{x_1} \rho(x, t) dx$

↳ change with time for Δt : $\int_{x_1}^{x_2} dx [\rho(x, t + \Delta t) - \rho(x, t)]$

Conservation of mass: $\int_{x_1}^{x_2} dx [\rho(x, t + \Delta t) - \rho(x, t)] + [q(x_1, t) - q(x_2, t)] \Delta t = 0$

$$\int_{x_2}^{x_1} dx \frac{\rho(x, t + \Delta t) - \rho(x, t)}{\Delta t} + q(x_1, t) - q(x_2, t) = 0 \quad (\Delta t \rightarrow 0)$$

$$\Rightarrow \int_{x_2}^{x_1} dx \frac{\partial \rho(x, t)}{\partial t} + q(x_1, t) - q(x_2, t) = 0$$

under some conditions
 of integrability
 (weak conditions)

$$\frac{d}{dt} \int_{x_2}^{x_1} dx \rho(x, t) + q(x_1, t) - q(x_2, t) = 0$$

integral-form of conservation law

In order to get a PDE, $x_2 - x_1 \rightarrow 0$

$$\Delta x = x_1 - x_2 > 0, \Delta x \rightarrow 0 \quad : \quad \int_{x_2}^{x_1} dx \rho(x, t) \approx \rho(\bar{x}, t) \Delta x \quad x_2 < \bar{x} < x_1$$

$$\Rightarrow \Delta x \frac{\partial \rho}{\partial t} + q(x_1, t) - q(x_2, t) = 0 \Rightarrow \frac{\partial \rho}{\partial t} + \frac{q(x_1, t) - q(x_2, t)}{\Delta x} = 0 \quad (\Delta x \rightarrow 0)$$

$$\Rightarrow \boxed{\frac{\partial \rho}{\partial t} + \frac{\partial q}{\partial x} = 0} \quad \text{differential form of conservation law}$$

(suppose ρ, ρ_x, ρ_t are continuous)

• the integral form is more general (weaker conditions on ρ); allows for example jumps in ρ

PDE for ρ : We must relate q and ρ . This is what models are about. If the model is not adequate shocks may appear in the solution (non-physical phenomena)

Assumption: $q = Q(\rho)$ known function (constitutive relation)

Conservative law \Rightarrow $\boxed{\frac{\partial \rho}{\partial t} + Q'(\rho) \frac{\partial \rho}{\partial x} = 0}$ PDE for ρ

(because of the assumption, ρ do not appear in the PDE, only ρ_t, ρ_x - sometimes this is not a good assumption)

($\rho \leftrightarrow u$) $u_t + c(u) u_x = 0$ $c(u) \leftrightarrow Q'(\rho)$
 "waves propagating with speed $Q'(\rho)$ waves in mass conserv."
 \hookrightarrow the deriv. of the function rel. q and ρ

Another way to bring this equation:
 $\frac{d\rho}{dt} = 0$, $\frac{dx}{dt} = Q'(\rho)$ total derivative of ρ is zero if you move at speed $Q'(\rho)$

$$\frac{\partial \rho}{\partial t} + \frac{dx}{dt} \frac{\partial \rho}{\partial x} = 0 \Leftrightarrow \frac{\partial \rho}{\partial t} + Q'(\rho) \frac{\partial \rho}{\partial x} = 0$$

$x = x(t)$: characteristics (CHAR)

Theory of 1st order PDE

! can always be converted to ODE \Rightarrow they are always solvable
 \rightarrow what helps is the concept of CHAR

Case 1 $\begin{matrix} \leftarrow \text{known} & & \leftarrow \text{known} \\ a(x,y) u_x + b(x,y) u_y = 0, & u = u(x,y) \end{matrix}$
 linear, homogeneous PDE
 ($\Leftrightarrow u \rightarrow \lambda u$ satisfies same PDE)

Suppose we vary x and y by Δx et Δy : $\begin{cases} x \rightarrow x + \Delta x \\ y \rightarrow y + \Delta y \end{cases}$
How does the function vary?

$$\Delta u = u(x + \Delta x, y + \Delta y) - u(x, y) \approx u_x \Delta x + u_y \Delta y$$

(u is differentiable)

We want to find specific $\Delta x, \Delta y$ such that $\Delta u = 0 \Leftrightarrow u = \text{const}$
for these variations

let $\begin{cases} \Delta x = a \cdot \epsilon \\ \Delta y = b \cdot \epsilon \end{cases}$ $\Rightarrow \Delta u \approx (au_x + bu_y) \epsilon = 0$
by using the PDE

What this means?

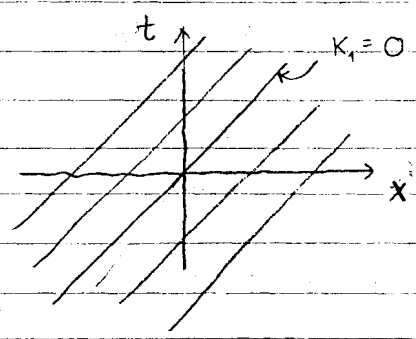
$$\Delta x \rightarrow dx, \Delta y \rightarrow dy \quad \epsilon = \frac{dx}{a(x,y)} = \frac{dy}{b(x,y)} \Rightarrow \Delta u = 0 \Rightarrow \boxed{u = \text{const}}$$

when (x,y) satisfy this ODE, $u = \text{const}$ along this curve.
 $\frac{dx}{a(x,y)} = \frac{dy}{b(x,y)} \Rightarrow$ solution $h(x,y) = \text{const}$ (a curve)
this is the CHAR

Ex.1 kinematic eq. $u_t + cu_x = 0$ c : constant
Find CHAR? $u = u(x,t)$

$$a(x,t) = 1, b(x,t) = c \Rightarrow \frac{dt}{1} = \frac{dx}{c} \Rightarrow x(t) = ct + \text{const}$$
$$x - ct = \text{const} = K_1$$

\Rightarrow the CHAR are lines $x - ct = K_1$



slope of the lines : $\frac{1}{c}$

Ex.2 Find the general solution of $u_t + cu_x = 0$

F : arbitrary

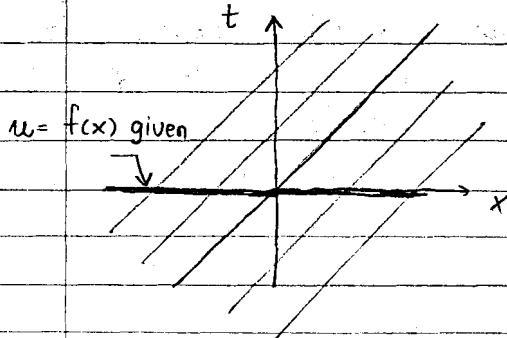
Along a specific CHAR, $K_1 \rightarrow u = G_1 = \text{const}$ i.e. $G_1 = F(K_1)$
to each K_1 , we map a const value G_1

Along a CHAR, $u = F(K_1) = F(x - ct)$
 \leftarrow arbitrary function of 1 var.

\Rightarrow the general solution $\boxed{u = F(x - ct)}$

△ along these lines u is const (we find a general solution) but we haven't shown these are the unique lines on which u is a const. (add. work → see reading...)

How to find the arbitrary function?



- initial data → the CHAR propagate it for further times
- how to find the solution at a point? find the CHAR that passes through follow the CHAR to $t=0$

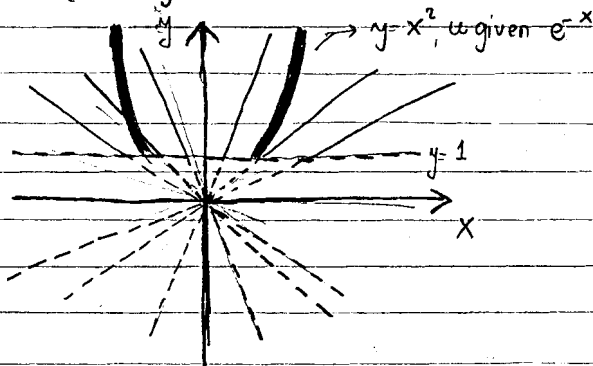
IVP $u(x,0) = f(x) = F(x) \rightarrow$ we find F
 $\Rightarrow u(x,t) = f(x-ct)$

Suppose we are given data on some $x-ct = K_0$ (on a CHAR) → this contradicts the structure of the PDE

An IVP is well-posed if data is given on curves \neq CHAR.

Ex.3 $xu_x + yu_y = 0, y > 1, -\infty < x < \infty$

$\Rightarrow \frac{dx}{x} = \frac{dy}{y} \Rightarrow \ln x = \ln y + \bar{K}_1 \Rightarrow \frac{y}{x} = K_1, y = K_1 x$ CHAR



Along CHAR, $u = C_1 = F(K_1)$

$u = F(y/x)$ general solution

$u(x, y=x^2) = e^{-x} = F(x)$

data is given on the parabola

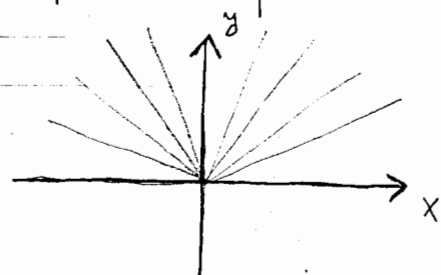
$y = x^2$ for $y > 1$

this curve cross each CHAR

only 1 → good initial data

$\Rightarrow u = e^{-y/x}$

Suppose our equation is for $y \geq 0$



all CHAR cross at the origin
 u : singular at $(0,0)$

(singular solution expresses as a weird behavior of the CHAR)

example with e^{-x} - not defined at origine
(identity crisis : value at origine depends on which CHAR we take.)

Generalization:

$$a(x,y,z)u_x + b(x,y,z)u_y + d(x,y,z)u_z = 0$$

$$u = u(x,y,z) \quad \text{linear, homogeneous}$$

CHAR: $\frac{dx}{a} = \frac{dy}{b} = \frac{dz}{d} \Rightarrow u = \text{const along CHAR}$

$f(x,y,z) = K_1 \quad g(x,y,z) = K_2$
 \hookrightarrow surface \cap \hookrightarrow surface = curve in 3D space

Case 2 $a(x,y)u_x + b(x,y)u_y = d(x,y)$
 linear, non-homogeneous

same concept: $\Delta x, \Delta y \quad \begin{cases} \Delta x = a \cdot \epsilon \\ \Delta y = b \cdot \epsilon \end{cases}$
 $\Rightarrow \Delta u \approx u_x \Delta x + u_y \Delta y = (a u_x + b u_y) \epsilon = d \epsilon$

$$\epsilon = \frac{dx}{a(x,y)} = \frac{dy}{b(x,y)} = \frac{du}{d(x,y)}$$

February 11, 2004 Lecture 3

Review of ODEs: Friday 5-6 pm

Review of Lecture 2 1st order PDE's

Case 1 $a(x,y)u_x + b(x,y)u_y = 0$ linear, homogeneous