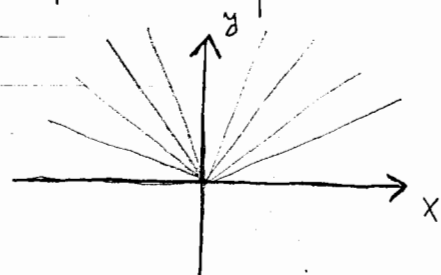


Suppose our equation is for $y \geq 0$



all CHAR cross at the origin
 u : singular at $(0,0)$

(singular solution expresses as a weird behavior of the CHAR)

example with e^{-x} - not defined at origine
(identity crisis : value at origine depends on which CHAR we take.)

Generalization:

$$a(x,y,z)u_x + b(x,y,z)u_y + d(x,y,z)u_z = 0$$

$u = u(x,y,z)$ linear, homogeneous

CHAR: $\frac{dx}{a} = \frac{dy}{b} = \frac{dz}{d} \Rightarrow u = \text{const along CHAR}$

$f(x,y,z) = K_1$ $g(x,y,z) = K_2$
 \hookrightarrow surface \cap \hookrightarrow surface = curve in 3D space

Case 2 $a(x,y)u_x + b(x,y)u_y = d(x,y)$
 linear, non-homogeneous

same concept: $\Delta x, \Delta y \begin{cases} \Delta x = a \cdot \epsilon \\ \Delta y = b \cdot \epsilon \end{cases}$
 $\Rightarrow \Delta u \approx u_x \Delta x + u_y \Delta y = (a u_x + b u_y) \epsilon = d \epsilon$

$$\epsilon = \frac{dx}{a(x,y)} = \frac{dy}{b(x,y)} = \frac{du}{d(x,y)}$$

February 11, 2004 Lecture 3

Review of ODEs: Friday 5-6 pm

Review of Lecture 2 1st order PDE's

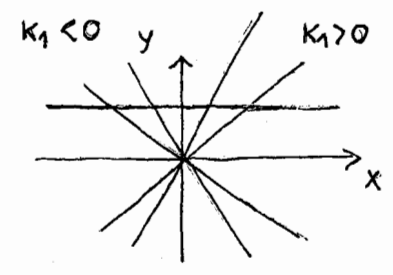
Case 1 $a(x,y)u_x + b(x,y)u_y = 0$ linear, homogeneous

- (i) CHAR: $\frac{dx}{a} = \frac{dy}{b} \Rightarrow h(x,y) = K_1 = \text{const}$ } $\Rightarrow u = F(h(x,y))$ - arbitrary
- (ii) $u = K_2 = \text{const}$ along CHAR - general solution
- (iii) Find F by initial data on curve \mathcal{Q} \leftarrow should intersect each CHAR once; (some exceptions)

Case 2 $a(x,y)u_x + b(x,y)u_y = c(x,y)$ linear, non-homogeneous

- (i) CHAR: $\frac{dx}{a(x,y)} = \frac{dy}{b(x,y)} \Rightarrow h(x,y) = K_1$
- (ii) $\frac{du}{c(x,y)} = \frac{dx}{a} = \frac{dy}{b} \Rightarrow f(x,y,u) = K_2$ along CHAR
 \uparrow solve by combining the difference with Case 1 is that u is not any more a constant along the CHAR
- (iii) Apply initial data

Ex. 1 IVP $\begin{cases} xu_x + yu_y = 1+y^2 \\ u(x,1) = 1+x \end{cases}$



- (i) CHAR: $\frac{dx}{x} = \frac{dy}{y} \Rightarrow y = K_1 x$
- (ii) $\frac{du}{1+y^2} = \frac{dx}{x} = \frac{dy}{y}$ combine (1) and (3) $\frac{du}{dy} = \frac{1+y^2}{y} = \frac{1}{y} + y$
- $\Rightarrow u = \ln y + \frac{y^2}{2} + K_2$ (this is true along the characteristics!)

$u - \ln y - \frac{y^2}{2} = K_2$
 $\downarrow \bar{u} = K_2$ along CHAR $\Rightarrow K_2 = \bar{u} = F(K_1) = F\left(\frac{y}{x}\right)$
 \downarrow
 $\bar{u} = F\left(\frac{y}{x}\right)$

$\Rightarrow u - \ln y - \frac{y^2}{2} = F\left(\frac{y}{x}\right)$
 $u = \ln y + \frac{y^2}{2} + F\left(\frac{y}{x}\right)$ General solution for u

- (iii) Apply data
 $y=1 \Rightarrow u(x,1) = \ln 1 + \frac{1}{2} + F\left(\frac{1}{x}\right) = 1+x \Rightarrow F\left(\frac{1}{x}\right) = \frac{1}{2} + x$
 $\Rightarrow F(x) = \frac{1}{2} + \frac{1}{x}$

$\Rightarrow u(x,y) = \ln y + \frac{y^2}{2} + \frac{1}{2} + \frac{x}{y}$ Solution that satisfies initial data

Case 3 $a(x,y,u)u_x + b(x,y,u)u_y = c(x,y,u)$ non-linear PDE
quasi-linear but linear in u_x, u_y

$\begin{cases} \Delta x = a \cdot \epsilon \\ \Delta y = b \cdot \epsilon \end{cases} \Rightarrow \Delta u = (au_x + bu_y) \epsilon = c \epsilon$

$\epsilon = \frac{dx}{a} = \frac{dy}{b} = \frac{du}{c}$

same equation but this time this is a coupled system of ODE's

solutions are $\begin{cases} f(x,y,u) = K_1 \\ g(x,y,u) = K_2 \end{cases}$ (2 eq. with 3 variables)

think of this as 3 independent variables: we have 2 surfaces \Rightarrow curve
 \Rightarrow the CHAR are 3D-curves in the $\{x,y,u\}$ -space
 before, it was curves in the xy -plane
 now, the CHAR depend on the form of the solution

Ex. 2 IVP: $\begin{cases} u_t + uu_x = 0 \\ u(x,0) = e^{-x^2} \end{cases}$ Traffic flow

CHAR: $\frac{dt}{1} = \frac{dx}{u} = \frac{du}{0}$ $\textcircled{1} \Rightarrow \frac{du}{dt} = 0 \Rightarrow u = K_1 = \text{const}$ along the CHAR

$\textcircled{2} \frac{dx}{u} = \frac{dt}{1}$ not an ODE, we have 3 variables but we know that $u = K_1$ along CHAR

$\Rightarrow \frac{dx}{K_1} = \frac{dt}{1} \Rightarrow x - K_1 t = K_2 = \text{const}$ (! we solve the ODE along CHAR)
 $x - ut = K_2 = \text{const}$

General solution: to every K_1 we map K_2 or vice versa

$K_2 \xrightarrow{F} K_1 \quad K_1 = F(K_2) \Rightarrow u = F(x-ut)$
 (arbitrary)

The form of the CHAR in the xy -plane depends on the solution difference: we have an implicit eqn. for u ! u , not known at this stage.

Apply initial data: $u(x,0) = e^{-x^2} = F(x-0) = F(x)$

$$\Rightarrow u = e^{-(x-ut)^2}$$

that is what we can make, no simpler form solve numerically (interesting phenomena shocks, etc.)

Case 4 $H(x,y,u, \underset{p}{u_x}, \underset{q}{u_y}) = 0$

more general case

here we have to view CHAR as curves in space (x,y,u,p,q) .

CHAR = a concept: a geometric view of the place where a PDE goes to ODE.

Def:

$$\begin{aligned} du &\approx u_x dx + u_y dy = p dx + q dy \\ dp &= p_x dx + p_y dy \quad (*) \\ dq &= q_x dx + q_y dy \quad (*) \end{aligned}$$

$$\begin{aligned} p &= u_x, \quad q = u_y \\ p_y &= q_x \end{aligned}$$

We want to find variations in x & y so that p_x, p_y, q_x, q_y are eliminated from all equations!

In this way, we will get equations only in the variables (x,y,u,p,q)

$$0 = \frac{dH}{dx} = H_x + H_y \frac{dy}{dx} + H_u \overset{p}{u_x} + H_p p_x + H_q q_x = 0$$

$$\Rightarrow H_p p_x + H_q p_y = -(H_x + H_u p) \quad (*) \quad \text{constraint to } p_x, p_y$$

$$0 = \frac{dH}{dy} = H_y + H_x \frac{dx}{dy} + H_u \overset{q}{u_y} + H_p p_y + H_q q_y = 0$$

$$\Rightarrow H_p q_x + H_q q_y = -(H_y + H_u q) \quad (*) \quad \text{constraint to } q_x, q_y$$

Let's eliminate p_x, p_y from 2(*), and q_x, q_y from 2(*) :

$$\begin{cases} dx = H_p \cdot \epsilon \Rightarrow du = (p H_p + q H_q) \cdot \epsilon \\ dy = H_q \cdot \epsilon \quad dp = (p_x H_p + p_y H_q) \cdot \epsilon = -(H_x + H_u p) \cdot \epsilon \end{cases}$$

$$dq = (q_x H_p + q_y H_q) \cdot \epsilon = -(H_y + H_u q) \cdot \epsilon$$

Charpit Eqns.

$$\epsilon = \frac{dx}{H_p} = \frac{dy}{H_q} = \frac{du}{p H_p + q H_q} = \frac{-dp}{H_x + H_u p} = \frac{-dq}{H_y + H_u q}$$

4 indep. ODE, 5 var. curve in space (x,y,u,p,q)

Ex. 3 $\begin{cases} H = p^2 + q + u = 0 \\ \text{IVP: } u(x,0) = x \end{cases} \quad \begin{matrix} p = u_x \\ q = u_y \end{matrix}$

$H_x = 0, H_y = 0, H_p = 2p, H_q = 1, H_u = 1$

Charpit equs:

$$\frac{dx}{2p} = \frac{dy}{1} = \frac{du}{2p^2 + q} = -\frac{dp}{p} = -\frac{dq}{q}$$

Choice from where to start

1) $\frac{dx}{2p} = -\frac{dp}{p} \Rightarrow x + 2p = K_1$

2) $-\frac{dp}{p} = -\frac{dq}{q} \Rightarrow (p = K_2 q) \quad q = K_2 p$

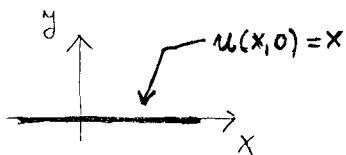
3) $\frac{dy}{1} = -\frac{dp}{p} \Rightarrow p e^y = K_3$

4) $\frac{du}{2p^2 + q} = -\frac{dp}{p} \Rightarrow \frac{du}{2p^2 + K_2 p} = -\frac{dp}{p} \Rightarrow \frac{du}{2p + K_2} = -dp$

$\Rightarrow u = -p^2 - K_2 p + K_4$

One way is to eliminate the constants.

Other way when data is available, use it right away.



parametrize the curve where data is given

$x = s \Rightarrow u(s,0) = s$

goal: express the const of integr. in terms of s

$\begin{cases} p = u_x = u_s = 1 & \text{(direct differentiation)} \\ q = u_y & \text{from the original equation } q = -u - p^2 = -s - 1 \end{cases}$

$\begin{cases} s + 2 \cdot 1 = K_1 \\ -s - 1 = K_2 \\ 1 = K_3 \\ s + 1 + K_2 = K_4 \end{cases} \Rightarrow \begin{cases} K_1 = s + 2 \\ K_2 = -s - 1 \\ K_3 = 1 \\ K_4 = s + 1 - s - 1 = 0 \end{cases}$ influence of data on the const of the solution

$2p = -x + 2 + s$

$q = (-s - 1)p$

$p = e^{-y}$

$u = -p^2 + (s+1)p$

$p = e^{-y}, s = 2e^{-y} + x - 2, q = \dots$

$u = -e^{-2y} + (2e^{-y} + x - 1)e^{-y}$

x, y, u, p, q, s

↓

2 indep. var.