# An Introduction to the Boundary Element Method (BEM) and Its Applications in Modeling Composite Materials 

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## Outline

- An introduction to the Boundary Element Method (BEM)
- Applications of the BEM in solving engineering problems
- BEM in large-scale modeling of fiber-reinforced composites
- Discussions
- References
- Acknowledgements
- Further Information


## An Introduction to the BEM

## - Two Different Approaches in Computational Mechanics



## A Brief History of the BEM

Jaswon and Symm (1963)

- 2D Potential Problems

F. J. Rizzo (1964, paper 1967)
- 2D Elasticity Problems


## Advantages of the BEM and the Mysteries

## Advantages:

- Accuracy - due to the semi-analytical nature and use of integrals
- More efficient in modeling stage due to the reduction of dimensions
- Good for stress concentration and infinite domain problems
- Good for modeling thin shell-like structures/materials
- Neat ...


## Mysteries:

- BIEs are singular which are difficult to deal with (wrong!)
- BEM is slow and thus inefficient (not necessarily!)
- FEM can solve everything. Who needs BEM? (not exactly true!)


## Formulation: The Potential Problem

- Governing Equation

$$
\nabla^{2} u(P)=0, \quad \forall P \in V
$$

- For 3D problems, the Green's function is

$$
G\left(P, P_{o}\right)=\frac{1}{4 \pi r}, \quad r=\left|P_{o} P\right|
$$

- BIE formulation


$$
C\left(P_{o}\right) u\left(P_{o}\right)=\int_{S}\left[G \frac{\partial u}{\partial n}-u \frac{\partial G}{\partial n}\right] d S, \quad \forall P_{o} \in S
$$

- Discretization of the BIE using the boundary elements

$$
[H]\{u\}=[G]\left\{\frac{\partial u}{\partial n}\right\}, \quad \text { or } \quad[A]\{x\}=\{b\} .
$$



## Singular or Non-Singular?

- Re-examine the BIE

$$
C\left(P_{o}\right) u\left(P_{o}\right)=\int_{S}\left[G \frac{\partial u}{\partial n}-u \frac{\partial G}{\partial n}\right] d S, \quad \forall P_{o} \in S .
$$

The second integral in the BIE is singular and is considered as a CPV integral

- However, the constant in the free term is also a CPV integral

$$
C\left(P_{o}\right)=-\int_{S} \frac{\partial G\left(P, P_{o}\right)}{\partial n} d S(P) .
$$

- Re-write the BIE to obtain the weakly-singular form of the BIE

$$
\int_{O\left(1 / r^{2}\right) \quad O(r)}^{\frac{\partial G}{\partial n}} \underbrace{u u(P)}_{O(P)-u\left(P_{o}\right)} d S=\int_{S} G \frac{\partial u}{\partial n} d S, \quad \forall P_{o} \in S .
$$

- Non-singular form also exists (Liu \& Rudolphi, EABE, 1991 and CM, 1999)


## Example: Results for Heat Transfer in a Fuel Cell

Predicted Temperature Distributions Using the BEM and FEM

(a) The fuel cell model
(b) BEM (max. temp. $=378.40 \mathrm{~K}$ )
(c) FEM (max. temp. $=378.31 \mathrm{~K})$

## Example: Coupled Structural Acoustics Analysis

- Applications
$>$ Acoustic radiation/scattering from elastic structures submerged in fluids
$>$ Prediction of noises of an elastic structure in vibration
$>$ Dynamics of fluid-filled elastic piping system
> Acoustic cavity analysis



## The BIE Formulation for Structural Acoustics

- Governing Equations
> In elastic domain:

$$
\begin{aligned}
& \left(c_{1}^{2}-c_{2}^{2}\right) u_{k, k i}(P)+c_{2}^{2} u_{i, k k}(P)+\omega^{2} u_{i}(P)=0, \quad \forall P \in V \\
& \nabla^{2} \phi(P)+k^{2} \phi(P)=0, \quad \forall P \in E
\end{aligned}
$$

$>$ In acoustic domain:

- BIE Formulations
$>$ In elastic domain: $\quad C_{i j}\left(P_{o}\right) \mathbf{u}_{j}\left(P_{o}\right)=\int_{S} \mathbf{U}_{i j}\left(P, P_{o}\right) \mathbf{t}_{j}(P) d S(P)-\int_{S} \mathbf{T}_{i j}\left(P, P_{o}\right) \mathbf{u}_{j}(P) d S(P)$
$>$ In acoustic domain: $\quad C\left(P_{o}\right) \phi\left(P_{o}\right)=\int_{S_{s}}\left[\frac{\partial G\left(P, P_{o}\right)}{\partial n} \phi(P)-G\left(P, P_{o}\right) \frac{\partial \phi(P)}{\partial n}\right] d S(P)+\phi^{\prime}\left(P_{o}\right)$
- Interface Conditions
$>$ Velocity continuity condition across the interface: $\frac{\partial \phi}{\partial n}=\rho_{f} \omega^{2} u_{n}$
$>$ Stress equilibrium condition: $t_{i}=-\phi n_{i}$
- Discretization of the BIE using boundary elements



## Results for A Structural Acoustics Analysis

Radiated Sound Pressure from Steel Spherical Shells with Different Thickness and Under an Internal Harmonic Pressure Load ( $r=5 a, M=112$ )



## Analysis of the Acoustic Fields of a Submarine



A simplified submarine model with BEM (Surface elements only)


Sound pressure in the exterior domain

## BEM for Modeling Thin Layered Materials

## Advantages:

- BEM is good for modeling thin shell-like materials/structures
- Much fewer elements are needed using the BEM than the FEM in the modeling (no element connectivity and aspect-ratio restrictions).
- Accuracy.


Difficulties: Treatment of the nearly singular integrals in the BIEs.
-3D elasticity case (Liu, IJNME, 1998)

- 2D elasticity case (Luo, Liu and Berger, CM, 1998)
- 2D piezoelectricity case (Liu and Fan, CMAME, 2002)


## Analysis of Fiber-Reinforced Composites with the Presence of the Interphases

## A Unit Cell Model of Fiber-Reinforced Composites



Interphases in fiber-reinforced composites are modeled using the BEM and FEM to investigate their effects on the mechanical properties and interface failures of the material.

## Analysis of Fiber-Reinforced Composites with the Presence of the Interphases (Cont.)



BEM (384 quadratic line elements)


FEM (10,188 quadratic area elements)

## Analysis of Fiber-Reinforced Composites with the Presence of the Interphases (Cont.)



Stress distribution


Effective Young's modulus

## Analysis of Fiber-Reinforced Composites with the Presence of the Interphases (Cont.)

## A Circular-Arc Crack Between the Interphase and the Matrix




Effects of the interphase materials on the stress intensity factor ( $K_{1} / \sigma_{\text {ave }} \sqrt{\pi R \alpha}$ ) for the circular-arc interface crack

## BEM for Thin Piezoelectric Solids

Applications of Piezoelectric Materials

- Thin piezo films and coatings as sensors/actuators in smart materials
- Micro-electro-mechanical systems (MEMS)
- ...


Electrical Current Of
Electrical Current On
The mechanical and electrical coupling effect in piezoelectric materials

## BEM for Thin Piezoelectric Solids (Cont.)

BIE for piezoelectricity (weakly-singular form):

$$
\begin{aligned}
& \int_{S} \mathbf{T}\left(P, P_{0}\right)\left[\mathbf{u}(P)-\mathbf{u}\left(P_{0}\right)\right] d S(P)=\int_{S} \mathbf{U}\left(P, P_{0}\right) \mathbf{t}(P) d S(P) \\
&+\int_{V} \mathbf{U}\left(P, P_{0}\right) \mathbf{b}(P) d V(P), \forall P_{0} \in S
\end{aligned}
$$

for a finite piezoelectric solid, in which (for 2D case):

$$
\begin{aligned}
& \mathbf{u}=\left\{\begin{array}{l}
u_{1} \\
u_{2} \\
-\phi
\end{array}\right\}, \\
& \mathbf{t}=\left\{\begin{array}{c}
t_{1} \\
t_{2} \\
-\omega
\end{array}\right\}, \quad \mathbf{b}=\left\{\begin{array}{c}
f_{1} \\
f_{2} \\
-q
\end{array}\right\}, \\
& \mathbf{U}=\left[\begin{array}{lll}
U_{11} & U_{12} & \Phi_{1} \\
U_{21} & U_{22} & \Phi_{2} \\
U_{31} & U_{32} & \Phi_{3}
\end{array}\right], \quad \mathbf{T}=\left[\begin{array}{lll}
T_{11} & T_{12} & \Omega_{1} \\
T_{21} & T_{22} & \Omega_{2} \\
T_{31} & T_{32} & \Omega_{3}
\end{array}\right] .
\end{aligned}
$$

## BEM for Thin Piezoelectric Solids (Cont.)

A PZT-5 Strip Subjected to Pressure Load $P$ and Voltage $V_{0}$



Displacement component $w$ along the bottom edge of the strip ( $M=24$ ) for different thicknesses

## BEM for Thin Piezoelectric Solids (Cont.)

## Analysis of Piezoelectric Parallel Bimorph

(Bending deformation with applied voltage)


A parallel bimorph


The deformed shape
(Note that the thickness of the layers can be made arbitrarily small without the need to use smaller and smaller elements in the BEM)

## Current Status of the BEM Research

- Fast solvers that can solve problems beyond the reach of other methods
- Large-scale analyses with DOFs above 20M
- Multi-physics and multi-scales


MEMS


VFY218 at $2 \mathrm{GHz}, \mathrm{V}$-pol


Electromagnetic wave scatterings from targets
(Chew, et al., 2004)

# Large-Scale Modeling of Fiber-Reinforced Composites with a <br> Fast Multipole Boundary Element Method 

In collaboration with:<br>Professor Naoshi Nishimura at Kyoto University

## The Approach

- A model with elastic matrix and rigid inclusions for fiber-reinforced composites is adopted (the rigid-inclusion model)
- This model is likely to be valid for short fibers or long fibers with much higher stiffness than that of matrix
- This approach is the first step towards more general elastic matrix/elastic fiber models
- The fast-multipole method is used to solve the large-scale BEM equations for this problem



## Boundary Integral Equation Formulation

Representation integral:

$$
\begin{equation*}
\mathbf{u}(\mathbf{x})=\int_{S}[\mathbf{U}(\mathbf{x}, \mathbf{y}) \mathbf{t}(\mathbf{y})-\mathbf{T}(\mathbf{x}, \mathbf{y}) \mathbf{u}(\mathbf{y})] d S(\mathbf{y})+\mathbf{u}^{\infty}(\mathbf{x}), \quad \forall \mathbf{x} \in V \tag{1}
\end{equation*}
$$

with $S=\bigcup_{\alpha} S_{\alpha}$
For each rigid inclusion $S_{\alpha}$ :

$$
\begin{equation*}
\mathbf{u}(\mathbf{y})=\mathbf{d}+\boldsymbol{\omega} \times \mathbf{p}(\mathbf{y}) \tag{2}
\end{equation*}
$$

with $\mathbf{d}$ and $\omega$ being the rigid-body translation and rotation, respectively

It can be shown that:

$$
\begin{equation*}
\int_{S_{\alpha}} \mathbf{T}(\mathbf{x}, \mathbf{y}) \mathbf{u}(\mathbf{y}) d S(\mathbf{y})=\mathbf{0} \tag{3}
\end{equation*}
$$

for each rigid inclusion $S_{\alpha}$


## Boundary Integral Equation Formulation (Cont.)

"Simplified" BIE formulation for rigid-inclusion problems:

$$
\begin{equation*}
\mathbf{u}(\mathbf{x})=\int_{S} \mathbf{U}(\mathbf{x}, \mathbf{y}) \mathbf{t}(\mathbf{y}) d S(\mathbf{y})+\mathbf{u}^{\infty}(\mathbf{x}), \quad \forall \mathbf{x} \in S \tag{4}
\end{equation*}
$$

Both $\mathbf{u}$ and $\mathbf{t}$ are unknown. Need six more equations for each inclusion

Consider the equilibrium of each inclusion (6 equations):

$$
\begin{gather*}
\int_{S_{\alpha}} \mathbf{t}(\mathbf{y}) d S(\mathbf{y})=\mathbf{0}  \tag{5}\\
\int_{S_{\alpha}} \mathbf{p}(\mathbf{y}) \times \mathbf{t}(\mathbf{y}) d S(\mathbf{y})=\mathbf{0} \tag{6}
\end{gather*}
$$

for $\alpha=1,2, \ldots, n$
Eqs. (4-6) provide enough equations for solving the rigid-inclusion problem

## Fast Multipole Method (FMM)

- Ranked among the top ten algorithms of the 20th century (with FFT, QR, ...)
- Developed by Rokhlin and

Greengard (mid of 1980's)

- For 3-D elasticity: Peirce and Napier (1995); Rodin, et al. (1997); Popov and Power (2001), and many others
- More research (more large-scale applications)
- Education or re-education
- A review: Nishimura, Applied

Mechanics Review, July 2002


Conventional evaluation of contribution from distant particles: $O\left(N^{2}\right)$ algorithm


## Fast Multipole Algorithm



- The entire boundary is divided into multi-level cells
- Each boundary element is placed in a cell, which contains a specified number of elements
- A tree structure of the boundary elements is obtained
- Interactions (integrations) of element-to-element is replaced by those of cell-to-cell
- Expansions are employed to accelerate the evaluations of these interactions
(Nishimura, 2002)


## Fast Multipole Expansions

Apply the following expansion:

$$
\begin{equation*}
\frac{1}{r(\mathbf{x}, \mathbf{y})}=\sum_{n=0}^{\infty} \sum_{m=-n}^{n} S_{n, m}(\overrightarrow{\mathbf{O x}}) \overline{R_{n, m}}(\overrightarrow{\mathbf{O y}}) \tag{7}
\end{equation*}
$$

where $\mathbf{O}$ represents a third point, $R_{n, m}$ and $S_{n, m}$ are solid harmonic functions
Displacement kernel is written as:

$$
\begin{equation*}
U_{i j}(\mathbf{x}, \mathbf{y})=\frac{1}{8 \pi \mu} \sum_{n=0}^{\infty} \sum_{m=-n}^{n}\left[F_{i j, n, m}(\overrightarrow{\mathbf{O x}}) \overline{R_{n, m}}(\overrightarrow{\mathbf{O y}})+G_{i, n, m}(\overrightarrow{\mathbf{O x}})(\overrightarrow{\mathbf{O y}})_{j} \overline{R_{n, m}}(\overrightarrow{\mathbf{O y}})\right] \tag{8}
\end{equation*}
$$

which is in the form: $\quad U \sim k_{n}^{(1)}(\mathbf{O x}) k_{n}^{(2)}(\mathbf{O y})$
The FMM expansion:

$$
\begin{equation*}
\int_{S_{o}} U_{i j}(\mathbf{x}, \mathbf{y}) t_{j}(\mathbf{y}) d S(\mathbf{y})=\frac{1}{8 \pi \mu} \sum_{n=0}^{\infty} \sum_{m=-n}^{n}\left[F_{i j, n, m}(\overrightarrow{\mathbf{O x}}) \overline{M_{j, n, m}}(\mathbf{O})+G_{i, n, m}(\overrightarrow{\mathbf{O x}}) \overline{M_{n, m}}(\mathbf{O})\right] \tag{9}
\end{equation*}
$$

where the four multipole moments are given by:

$$
\begin{equation*}
M_{j, n, m}(\mathbf{O})=\int_{S_{o}} R_{n, m}(\overrightarrow{\mathbf{O y}}) t_{j}(\mathbf{y}) d S(\mathbf{y}) ; \quad M_{n, m}(\mathbf{O})=\int_{S_{o}}(\overrightarrow{\mathbf{O y}})_{j} R_{n, m}(\overrightarrow{\mathbf{O y}}) t_{j}(\mathbf{y}) d S(\mathbf{y}) \tag{10}
\end{equation*}
$$

## Fast Multipole Algorithm (Cont.)

## upward and downward passes


(Nishimura, 2004)

## A Rigid Sphere in Elastic Medium



## A Rigid Sphere in Elastic Medium (Cont.)



Radial and tangential stresses obtained by a BEM model with 120 elements

## A Rigid Sphere in Elastic Medium (Cont.)



Contour plot for stress on the surface of the sphere

## Study of Fiber-Reinforced Composites: The Representative Volume Element (RVE)



## A BEM Mesh



A BEM mesh used for the short fiber inclusion (with 456 constant elements)

## Load Transfer Studies



A model with 216 "randomly" distributed and oriented short fibers

## Efficiency of the Fast Multipole BEM



CPU time used for solving the BEM models for the short-fiber cases

## Modeling of CNT-Based Composites (Cont.)



A small RVE containing 2,000 CNT fibers with the total DOF $=3,612,000$ (CNT length $=50 \mathrm{~nm}$, volume fraction $=10.48 \%$ ). A larger model with 16,000 CNT fibers and 28.9 M DOFs was solved successfully on a FUJITSU HPC2500 supercomputer (at the Kyoto University) within 34 hours.

## Modeling of CNT-Based Composites (Cont.)



Computed effective moduli of CNT/polymer composites using three RVEs and compared with NASA's multi-scale results

## Discussions

- BEM is a very efficient numerical tool for many problems in engineering
- Computational mechanics can play a significant role in the development of composite materials
- Multi-scale, multiphysics and large-scale approaches are urgently needed for the development of new materials
- There are plenty of opportunities for the computational mechanics (FEM/BEM/BNM/Meshfree methods) in material modeling, bio-engineering and many other fields


## A Bigger Picture of Computational Solid Mechanics

FEM: Large-scale structural, nonlinear, and transient problems


Meshfree: Large deformation, fracture and moving boundary problems

"If the only tool you have is a hammer, then every problem you can solve looks like a nail!"


## Future of Computational Mechanics

## Large scale, multiscale, instant and visual!



An Example:

Virtual Reality (VR) with large scale MD simulations of a fractured ceramic nanocomposite (Spheres with different colors represent atoms of different materials in the nanocomposite)
(A. Nakano, et al., 2001)

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