

# 程式 45 Stiffness and flexibility

1. For a rod, we have stiffness and flexibility matrices,

$$[K] = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}, [F] = \frac{1}{4} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix},$$

For a beam, we have stiffness and flexibility matrices,

$$[K] = \begin{bmatrix} 12 & 6 & -12 & 6 \\ 6 & 4 & -6 & 2 \\ -12 & -6 & 12 & -6 \\ 6 & 2 & -6 & 4 \end{bmatrix}, [F] = \frac{1}{150} \begin{bmatrix} 2 & 1 & -2 & 1 \\ 1 & 38 & -1 & -37 \\ -2 & -1 & 2 & -1 \\ 1 & -37 & -1 & 38 \end{bmatrix},$$

We have employed pseudo-inverse or truncated SVD technique to determine the inverse of a singular matrix. Now we will propose another method.

$$U\tilde{t} = T\tilde{u},$$

$T^{-1}$  does not exist.

$$T = C + \Phi_r \Psi_r^T = \begin{bmatrix} \Phi_\ell & \Phi_r \end{bmatrix} \begin{bmatrix} \Sigma_\ell & 0 \\ 0 & \Sigma_r \end{bmatrix} \begin{bmatrix} \Psi_\ell^T \\ \Psi_r^T \end{bmatrix},$$

$$T\Psi_r = 0,$$

$$\tilde{u} = \tilde{u}_c + \tilde{u}_p = \Psi_r \tilde{y} + \tilde{u}_p,$$

$$\tilde{u}_p \cdot \tilde{\psi} = 0 \Rightarrow \Phi_r^T \tilde{u}_p = 0,$$

$$\Rightarrow U\tilde{t} = T\tilde{u} = T(\Psi_r \tilde{y} + \tilde{u}_p) = (C + \Phi_r \Psi_r^T) \tilde{u}_p = C\tilde{u}_p, u_p = C^{-1}U\tilde{t}.$$

2. Solve the Laplace problem with the following boundary conditions.

(a)  $u(0) = 100, t(0) = 0,$

(b)  $u(0) = 100, t(1) = 0,$

(c)  $u(0) = 100, t(1) = 100.$