

Engineering Mathematics(III)

J. T. Chen

Department of Harbor and River Engineering, National Taiwan Ocean University

due 24/10 morning, Fall 1994 (m3hw1.te)

HW No.1

Solve the particular solution (steady state solution) of the SDOF vibration system $\ddot{x} + 2\xi\omega\dot{x} + \omega^2x = \cos(\bar{\omega}t)$ by

- (1). conventional method.
- (2). method of complex variables.
- (3). Discuss the change of amplitude and phase between input and output.
- (4). Repeat (1), (2) and (3) steps if $\bar{\omega} = \omega$ and $\xi = 0$?
- (5). Repeat (1), (2) and (3) steps if $\bar{\omega} = \omega$ and $\xi \neq 0$?
- (6). Can the solution be derived by limiting process

$\bar{\omega} \rightarrow \omega$, if $\xi \neq 0$

$\bar{\omega} \rightarrow \omega$, if $\xi = 0$?

(Hint: by superimposing the complementary solution before taking limit)

HW No.2

Solve $z^4 = 1$ and plot in the complex plane.

HW No.3

The first root of Hw No.2 is defined $W = e^{-2\pi i/4}$. In discrete Fourier transform, we have

$$X(n) = \sum_{k=0}^{N-1} x_0(k) e^{-i2\pi nk/N}, \quad n = 0, 1, \dots, N-1$$

For $N = 4$, prove that

$$\begin{bmatrix} X(0) \\ X(2) \\ X(1) \\ X(3) \end{bmatrix} = \begin{bmatrix} 1 & W^0 & 0 & 0 \\ 1 & W^2 & 0 & 0 \\ 0 & 0 & 1 & W^1 \\ 0 & 0 & 1 & W^3 \end{bmatrix} \begin{bmatrix} 1 & 0 & W^0 & 0 \\ 0 & 1 & 0 & W^0 \\ 1 & 0 & W^2 & 0 \\ 0 & 1 & 0 & W^2 \end{bmatrix} \begin{bmatrix} x_0(0) \\ x_0(1) \\ x_0(2) \\ x_0(3) \end{bmatrix}$$

Note: This step is the factorization in FFT(Fast Fourier Transform).

【存檔：E:/ctex/course/math3/94hw1.te】 【建檔:Nov./3/'94】