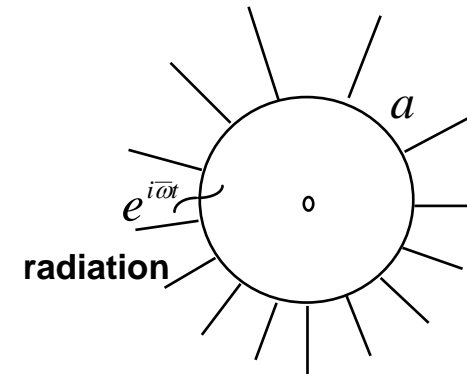
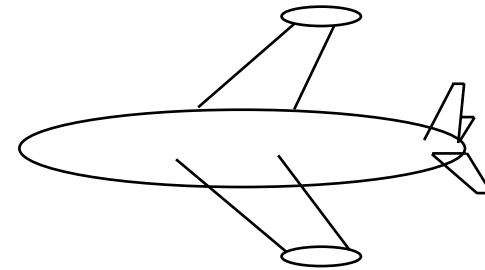
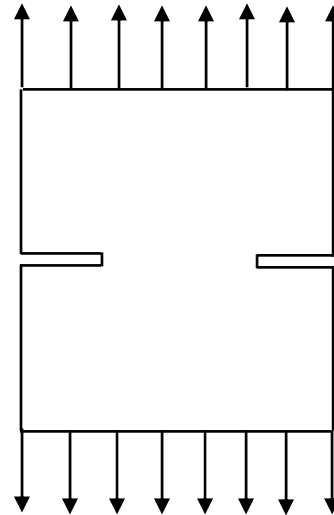
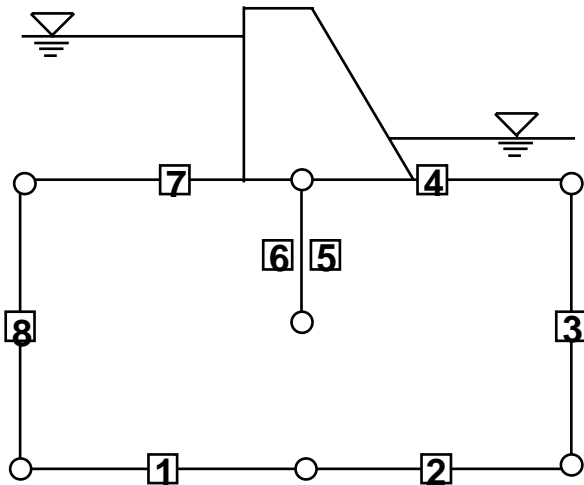


# On the Dual Representation Model and Its Applications



J.T. Chen

Department of Civil Engineerin, National Taiwan University  
Presentation for Institute of Applied Mechanics, May 13, 1994



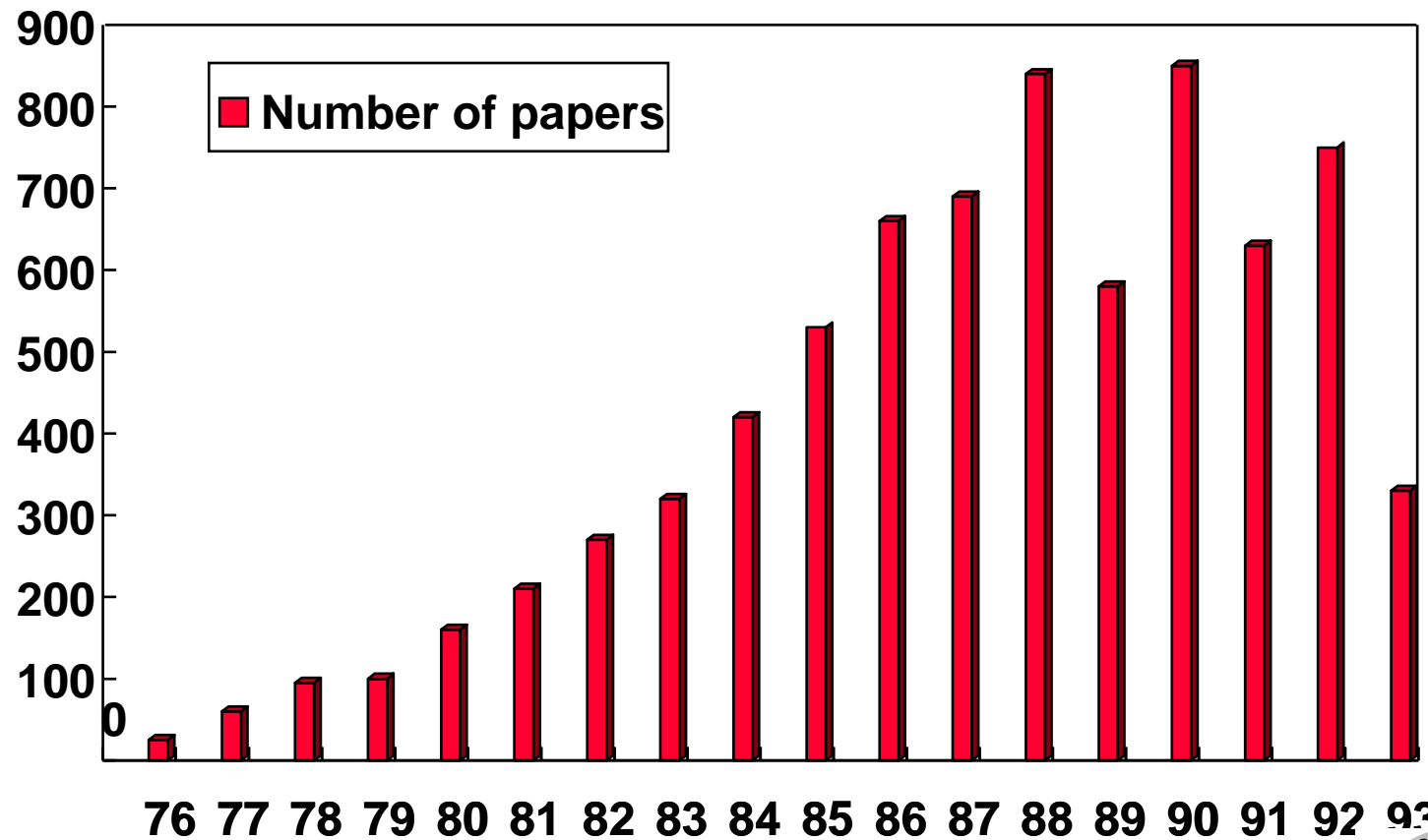
## *Outlines*

- **Introduction to BEM**
- **Introduction to dual BEM**
- **Theory of dual integral equations**
- **Theory of dual series representations**
- **The roles of dual integral equations**
- **Regularization methods for hypersingularity**
- **Regularization methods for divergent series**
- **Applications of dual integral equations**
- **Applications of dual series representations**
- **Conclusions**



## Growth Rate of BEM Papers

← Cauchy singularity → | hypersingularity | divergent series |



## *Dual Integral Equations by Hong and Chen(1984-1986)*

Singular integral equation



Hypersingular integral equation

Cauchy principal value



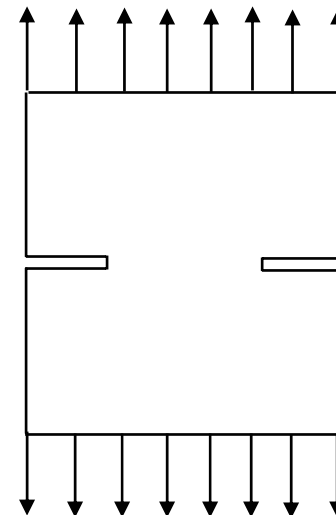
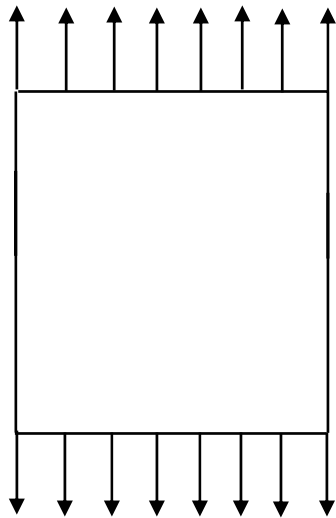
Hadamard principal value

Boundary element method



Dual boundary element method

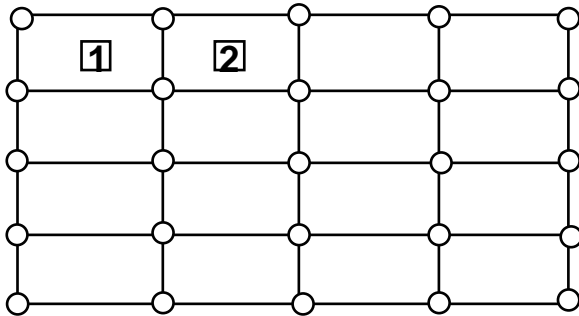
normal  
boundary



degenerate  
boundary

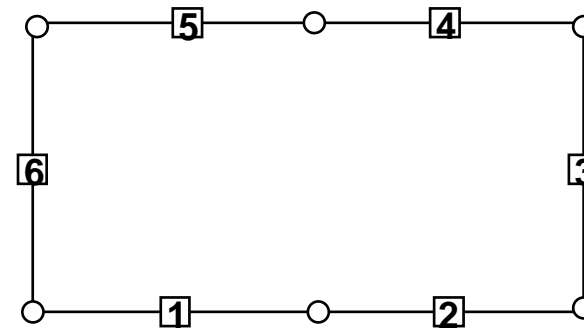
# What Is Boundary Element Method ?

- **Finite element method**



○ **geometry node**

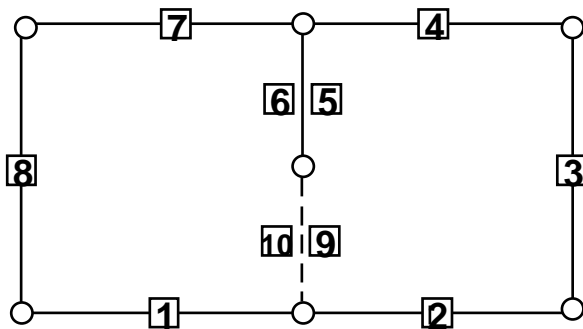
## Boundary element method



▣ **the Nth constant or linear element**

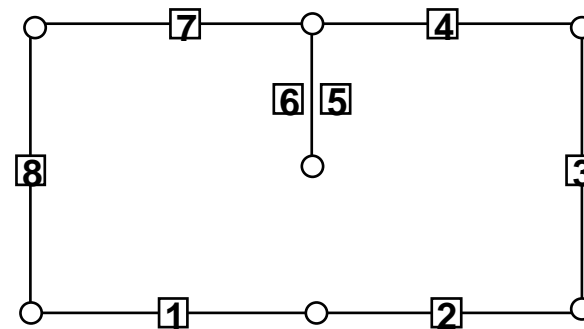
## *What Is Dual Boundary Element Method ?*

- **Boundary element method**



**Artificial boundary introduced !**

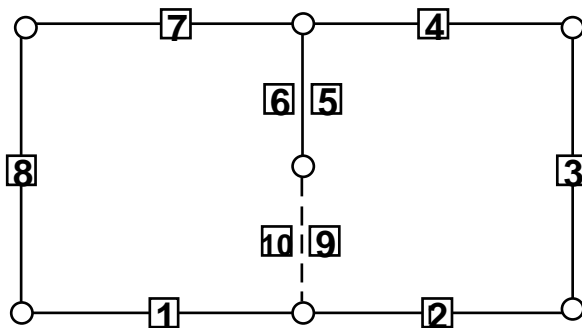
### **Dual boundary element method**



**Dual integral equations needed !**

# Theory of Dual Integral Equations Dual Boundary Element Method

## • Boundary element method

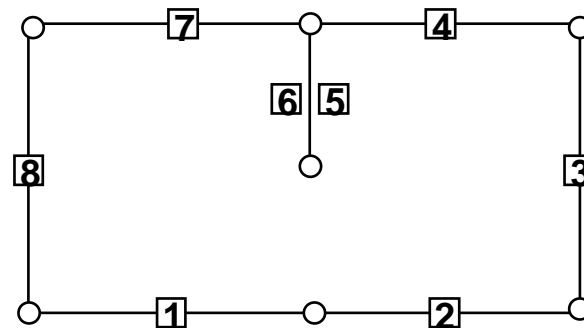


Only U, T equation is used

$$2\pi u(x) = \int_B T(s, x) u(s) dB(s) - \int_B U(s, x) t(s) dB(s), \quad x \in D$$

$$2\pi t(x) = \int_B M(s, x) u(s) dB(s) - \int_B L(s, x) t(s) dB(s), \quad x \in D$$

## Dual boundary element method



Both equations are used

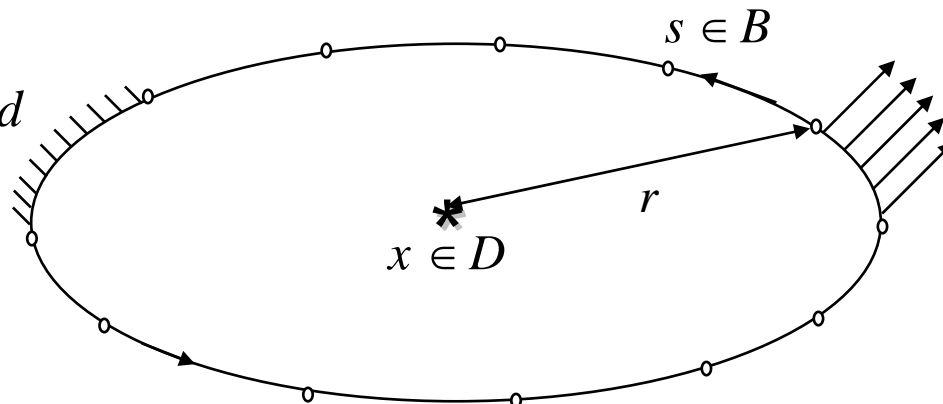
## Theory of Dual Integral Equations

- Dual integral equations for domain point

$$2\pi u(x) = \int_B T(s, x)u(s)dB(s) - \int_B U(s, x)t(s)dB(s), \quad x \in D$$

$$2\pi t(x) = \int_B M(s, x)u(s)dB(s) - \int_B L(s, x)t(s)dB(s), \quad x \in D$$

$u(s) = \text{specified}$   
 $t(s) = ?$



$t(s) = \text{specified}$   
 $u(s) = ?$

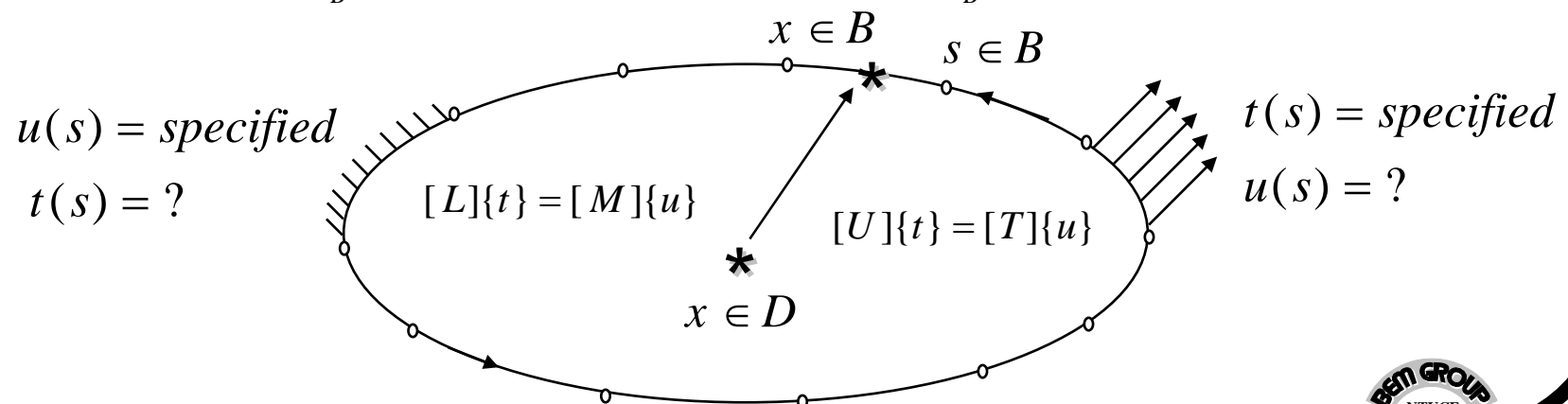


## Theory of Dual Integral Equations

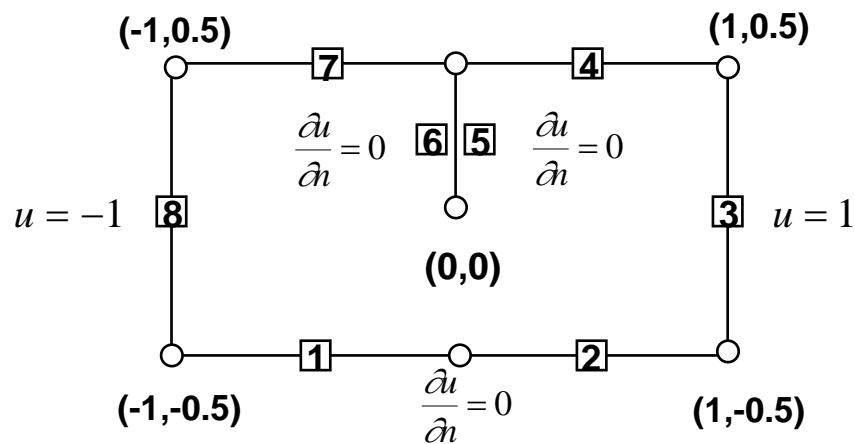
- Dual integral equations for boundary point

$$\pi u(x) = C.P.V. \int_B T(s, x) u(s) dB(s) - R.P.V. \int_B U(s, x) t(s) dB(s), \quad x \in B$$

$$\pi t(x) = H.P.V. \int_B M(s, x) u(s) dB(s) - C.P.V. \int_B L(s, x) t(s) dB(s), \quad x \in B$$



# Degeneracy of the Degenerate Boundary



- geometry node
- the Nth constant or linear element

$$[U]\{t\} = [T]\{u\}$$

$$[L]\{t\} = [M]\{u\}$$

	5(+)		6(+)					
$[U]$	1.693	-0.045	0.471	0.347	-0.054	-0.054	0.039	-0.335
	1.045	-1.693	-0.335	0.039	-0.054	-0.054	0.347	0.471
	0.445	-0.335	-1.693	-0.335	0.019	0.019	0.445	0.703
	0.347	0.039	-0.335	-1.693	-0.281	-0.281	-0.045	0.471
	0.081	-0.081	0.063	-0.638	-1.193	-1.193	-0.638	0.063
	0.081	-0.081	0.063	-0.638	-1.193	-1.193	-0.638	0.063
	0.039	0.347	0.471	-0.045	-0.281	-0.281	-1.693	-0.334
	0.335	0.445	0.703	0.445	0.019	0.019	-0.335	-1.693

	5(+)		6(-)					
$[T]$	$\pi$	0.000	0.588	0.519	-0.321	0.321	0.927	1.107
	0.000	$-\pi$	1.107	0.927	0.321	-0.321	0.519	0.588
	0.219	1.107	$-\pi$	1.107	0.464	-0.464	0.219	0.490
	0.19	0.927	1.107	$-\pi$	0.785	-0.785	0.000	0.588
	0.27	0.927	0.888	1.326	$-\pi$	$-\pi$	1.326	0.888
	0.27	0.927	0.888	1.326	$-\pi$	$-\pi$	1.326	0.888
	0.27	0.519	0.588	0.000	-0.7854	0.785	$-\pi$	1.107
	0.07	0.219	0.490	0.219	-0.464	0.464	1.107	$-\pi$

	5(+)		6(+)					
$[L]$	$\pi$	0.000	0.184	0.519	0.458	0.458	0.927	0.805
	0.000	$\pi$	0.805	0.927	0.458	0.458	0.519	0.184
	0.612	0.805	$\pi$	0.805	0.464	0.464	0.612	0.490
	0.519	0.927	0.805	$\pi$	0.347	0.347	0.000	0.184
	0.511	0.511	0.888	1.417	$\pi$	$-\pi$	-1.417	-0.888
	0.511	-0.511	-0.888	-1.417	$-\pi$	$\pi$	1.417	0.888
	0.927	0.519	0.184	0.000	0.347	0.347	$\pi$	0.805
	0.805	0.612	0.490	0.612	0.464	0.464	0.805	$\pi$

	5(+)		6(-)					
$[M]$	4.000	-1.333	-0.205	-0.061	0.600	-0.600	-0.800	-1.600
	1.333	4.000	-1.600	-0.800	-0.600	0.600	-0.061	-0.205
	0.282	-1.600	4.000	-1.600	-0.400	0.400	-0.282	-0.236
	0.061	-0.800	-1.600	4.000	-1.000	1.000	-1.333	-0.205
	0.853	-0.853	-0.715	-3.765	8.000	-8.000	3.765	0.715
	0.853	0.853	0.715	3.765	-8.000	8.000	-3.765	-0.715
	0.800	-0.062	-0.205	-1.333	1.000	-1.000	4.000	-1.600
	1.600	-0.282	-0.235	-0.282	0.400	-0.400	-1.600	4.000

## Definitions of R.P.V., C.P.V. and H.P.V.

• **R.P.V.**

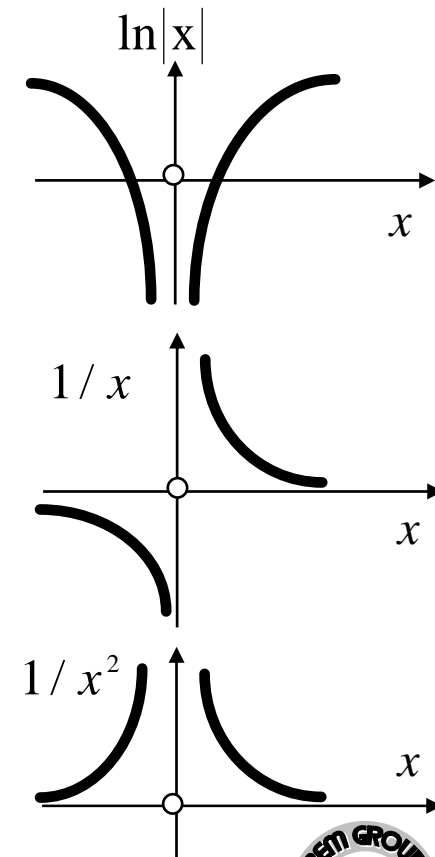
$$R.P.V. \int_{-1}^1 \ln|x| dx = (x \ln|x| - x) \Big|_{x=-1}^{x=1} = -2$$

• **C.P.V.**

$$C.P.V. \int_{-1}^1 \frac{1}{x} dx = \lim_{\varepsilon \rightarrow 0} \int_{-1}^{-\varepsilon} \frac{1}{x} dx + \int_{\varepsilon}^1 \frac{1}{x} dx = 0$$

• **H.P.V.**

$$H.P.V. \int_{-1}^1 \frac{1}{x^2} dx = \lim_{\varepsilon \rightarrow 0} \int_{-1}^{-\varepsilon} \frac{1}{x^2} dx + \int_{\varepsilon}^1 \frac{1}{x^2} dx - \frac{2}{\varepsilon} = -2$$



# Regularization methods for hypersingularity

## use of simple solutions

1. constant potential
2. rigid body motion
3. complementary solution
  - (a). nondegenerate boundary
  - (b). degenerate boundary: enclosing technique

## kernel function

1. static kernel subtraction
2. quasi-static part decomposition
3. integration by parts reduction one order singularity for kernel

## density function

1. regularized  $u$   
 $u(s) \rightarrow u(s) - u(x)$
2. regularized  $u, t$   
 $u(s) \rightarrow u(s) - u(x) - u'(x)r_i\bar{s}_i - t(x)r_i\bar{n}_i$   
 $t(s) \rightarrow t(s) - t(x)$
3. integration by parts  
 $u(s) \rightarrow u'(s)$

## trace to boundary

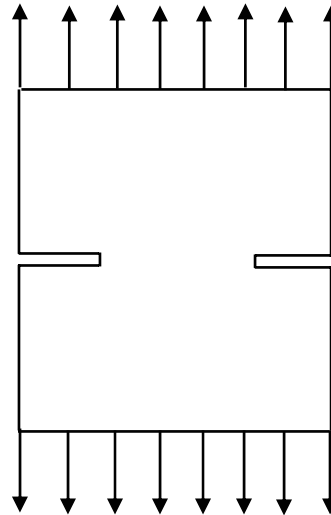
1. limiting process
2. jump function
3. L'Hospital rule
4. Cesaro sum

## surrounding integral

1. CPV concept
2. HPV concept
3. free term
4. Introducing boundary terms
  - (a). Stokes' theorem
  - (b). integration by parts
  - (c). Stokes' transformation
  - (d). summation by parts
  - (e). Leibnitz rule
5. quadrature rule

## *Applications of Dual Integral Equations*

**Crack problem**



*Work in CSIST (1986-1990)*

**Analysis, Design and Experiment for Solid Rocket Motor**



## Research in CSIST (1986-1990)

**Solid mechanics**



**Aerodynamics**

**Hadamard principal value**



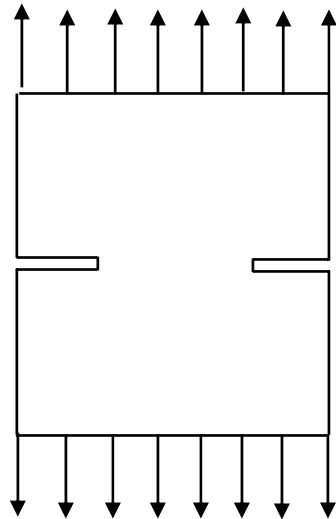
**Mangler principal value**

**Boundary element method**

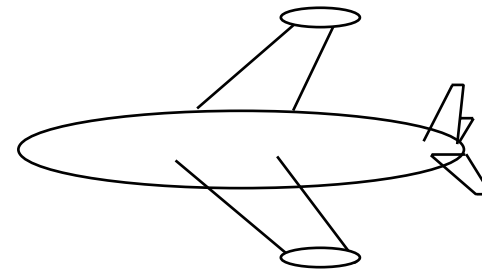


**Panel method**

**Crack problem**



**Thin-airfoil Aerodynamics**



*Two Books in CSIST (1986-1990)*

**Book for academic research**

**BEM**

**Book for industry applications**

**FEM**

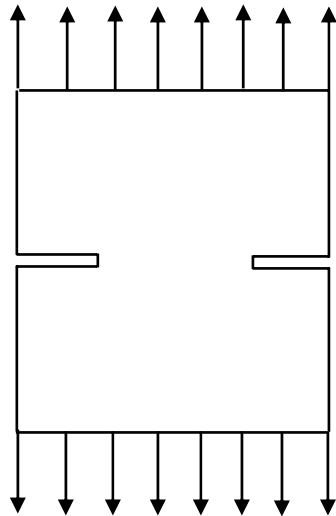
with MSC/NASTRAN



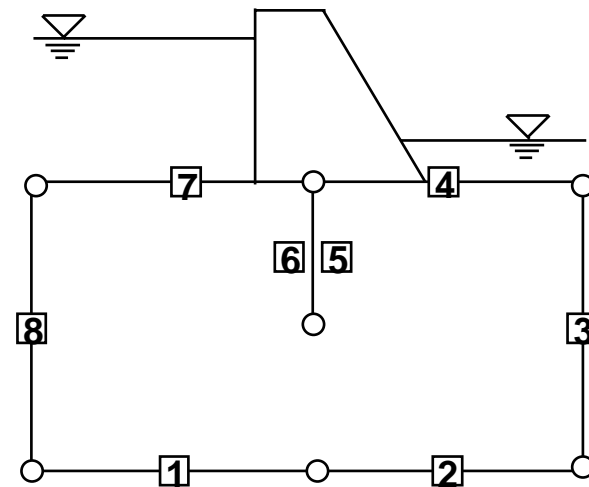


## *Research in NTUCE (1990-present)*

**Crack problem**



**Seepage with sheetpiles**



# Roles of hypersingularity in boundary element method

## complementary constraints

higher order element

degenerate boundary

corner problem

fictitious eigenvalue

adaptive BEM

secondary field calculation

condition number

symmetry formulation

image system

1. Hermite element

1. cutoff wall
2. sheet pile
3. crack
4. baffle
5. thin airfoil
6. antenna

(o)  $\begin{cases} U \\ L \end{cases} \{t\} = \begin{bmatrix} T \\ M^+ \end{bmatrix} \{u\}$

(o)  $\begin{cases} U \\ L \end{cases} \{t\} = \begin{bmatrix} T \\ M^- \end{bmatrix} \{u\}$

(x)  $\begin{cases} U \\ L \end{cases} \{t\} = \begin{bmatrix} M^- \\ M^+ \end{bmatrix} \{u\}$

1.  $\begin{cases} U \\ L \end{cases} \{t\} = \begin{bmatrix} T \\ M^+ \end{bmatrix} \{u\}$
2.  $\begin{cases} U \\ L \end{cases} \{t\} = \begin{bmatrix} T \\ M^- \end{bmatrix} \{u\}$
3.  $\begin{cases} U \\ L \end{cases} \{t\} = \begin{bmatrix} M^- \\ M^+ \end{bmatrix} \{u\}$

1. kernel function
2. region of singularity
3. boundary condition

1. error estimator

1. hoop stress on boundary
2. tangent flux along boundary
3. regularized version for stress near boundary

1. pseudo-differential operator

$U(-1)$	$T(0)$
$L(0)$	$M(1)$

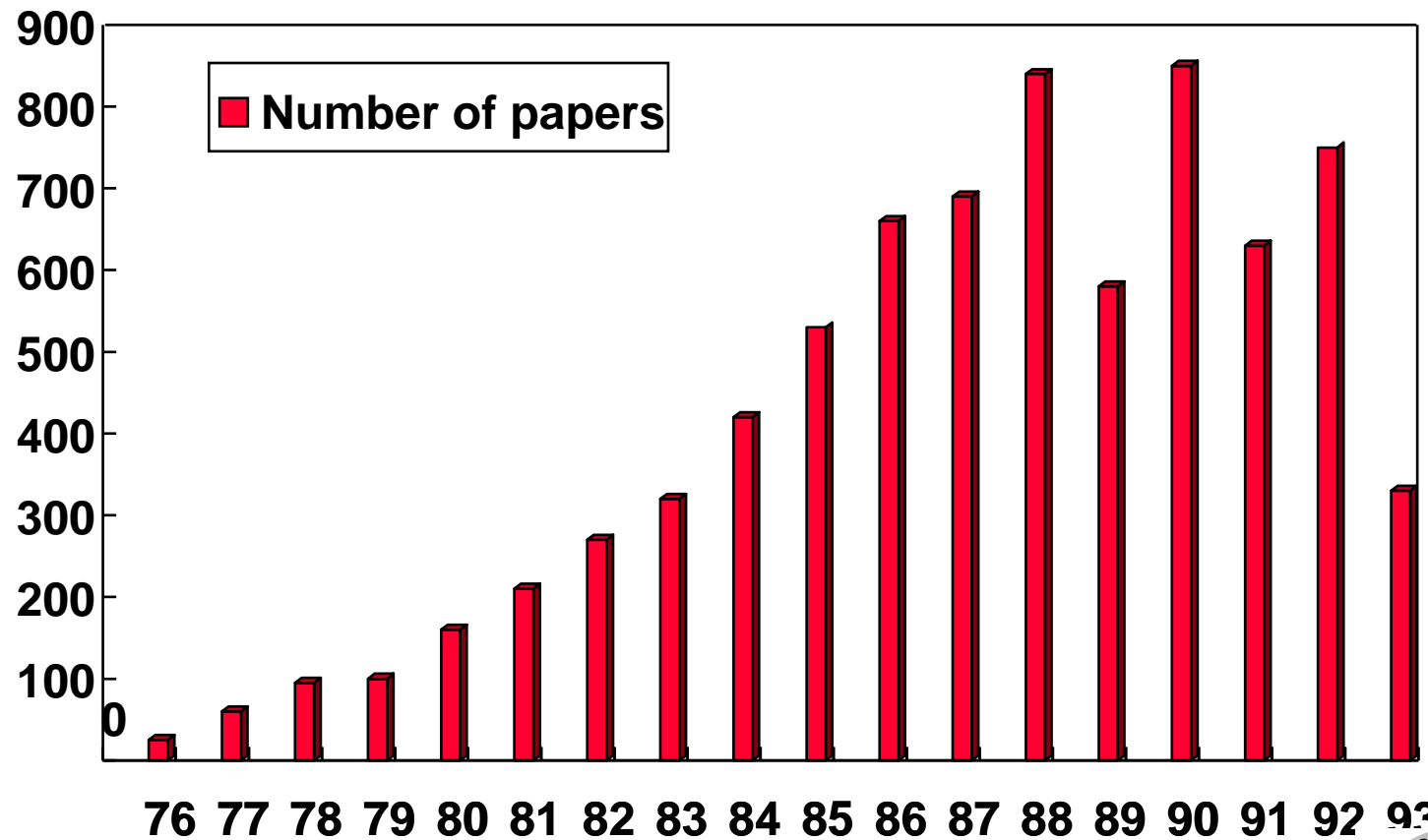
2.  $T, L$  is more stable than  $U, M$

1. double boundary integration

1. normal vector of dipole or dislocation

## Growth Rate of BEM Papers

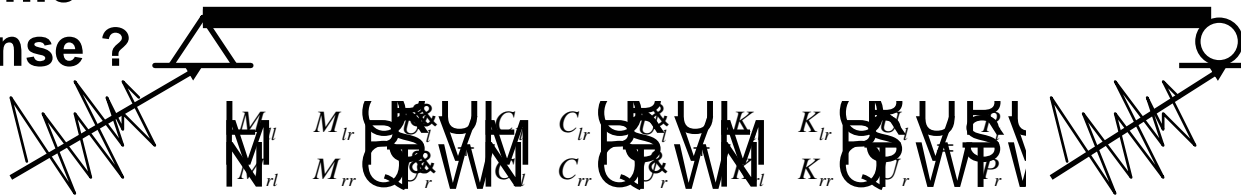
← Cauchy singularity → | hypersingularity | divergent series |



## Why Dual Series Representations ? Support Motion Problems

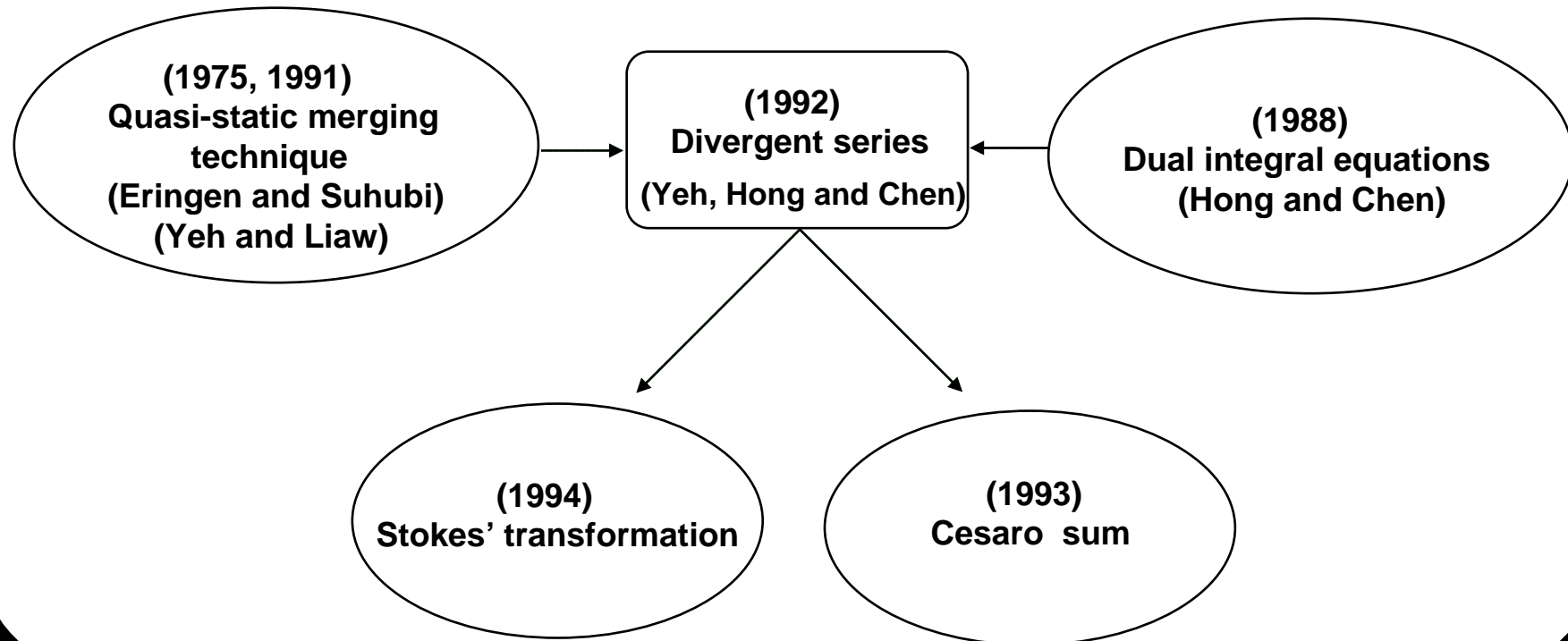
$$\rho \frac{\partial^2 u(x,t)}{\partial t^2} + (2\alpha\rho - \beta G) \frac{\partial u(x,t)}{\partial x} - G \frac{\partial^2 u(x,t)}{\partial x^2} = 0$$

dynamic  
response ?



random  
response ?

## *History of The Research on Divergent Series*



## *Methods of Solution*

- **Quasi-static decomposition method (Mindlin and Goodman, 1950)**  
**Accelerate the convergence rate**
- **Series representation (Eringen and Suhubi, 1975, Yeh and Liaw, 1991)**  
**Quasi-static solution is not necessary to be determined**
- **Low convergence and divergence will occur using series representation proposed by Pilkey**
  
- **Two goals**  
**Omit the calculation of quasi-static solution**  
**Accelerate the convergence rate**

## Dual Integral Equations and Dual Series Representation

- Dual Integral Equations:**

$$\begin{aligned}
 u(x,t) &= \int_0^t \int_B U(s,x;\tau,t) \mathfrak{F}(s,\tau) dB(s) d\tau - \int_0^t \int_B T(s,x;\tau,t) \mathfrak{G}(s,\tau) dB(s) d\tau \\
 &\quad + \int_0^t \int_V U(s,x;\tau,t) f(s,\tau) dV(s) d\tau \\
 t(x,t) &= \int_0^t \int_B L(s,x;\tau,t) \mathfrak{F}(s,\tau) dB(s) d\tau - \int_0^t \int_B M(s,x;\tau,t) \mathfrak{G}(s,\tau) dB(s) d\tau \\
 &\quad + \int_0^t \int_V L(s,x;\tau,t) f(s,\tau) dV(s) d\tau
 \end{aligned}$$

- Series :**

$$\begin{aligned}
 U(s,x;\tau,t) &= \lim_{N \rightarrow \infty} C(N,1) \left\{ \sum_{m=1}^N e^{-k\omega_m(t-\tau)} u_m(x) u_m(s) / N_m \right\} \\
 T(s,x;\tau,t) &= \lim_{N \rightarrow \infty} C(N,1) \left\{ \sum_{m=1}^N e^{-k\omega_m(t-\tau)} u_m(x) t_m(s) / N_m \right\} \\
 L(s,x;\tau,t) &= \lim_{N \rightarrow \infty} C(N,2) \left\{ \sum_{m=1}^N e^{-k\omega_m(t-\tau)} t_m(x) u_m(s) / N_m \right\} \\
 M(s,x;\tau,t) &= \lim_{N \rightarrow \infty} C(N,2) \left\{ \sum_{m=1}^N e^{-k\omega_m(t-\tau)} t_m(x) t_m(s) / N_m \right\}
 \end{aligned}$$

$C(N,r)$  : Cesaro operator with order  $r$



## Cesaro Regularization Technique

- Series Solution(Partial Sum)**

$$s_0 = a_0$$

$$s_1 = a_0 + a_1$$

$$s_2 = a_0 + a_1 + a_2$$

~~MM~~

$$s_{N-1} = a_0 + a_1 + a_2 + \dots + a_{N-1}$$

(partial sum)  $s_N = a_0 + a_1 + a_2 + \dots + a_{N-1} + a_N$  (divergent,  $N \rightarrow \infty$ )

$$\frac{s_0 + s_1 + \dots + s_{N-1} + s_N}{N+1} = a_0 + \frac{N}{N+1}a_1 + \frac{N-1}{N+1}a_2 + \dots + \frac{2}{N+1}a_{N-1} + \frac{1}{N+1}a_N \quad (\text{convergent, } N \rightarrow \infty)$$

(Cesaro sum)  $S_N = \frac{1}{N+1} \sum_{k=0}^N (N-k+1) a_k$  (moving average)





## Stokes' Transformation --- Summation by Parts

- **Term by Term Differentiation Is Not Always Legal**
- **Boundary Term Is Present for Some Cases**

$$f'(x) = \frac{d}{dx} \left[ \sum_{k=0}^N c_k u_k(x) \right] = \sum_{k=0}^N c_k u_k'(x) + \underbrace{\sum_{k=0}^N b_k u_k'(x)}_{\text{Boundary term}}$$

if  $\sum_{k=0}^N b_k u_k'(x) \neq 0$

- **Term by Term Differentiation Is Legal**

if  $\sum_{k=0}^N b_k u_k'(x) = 0$



## Regularization Techniques for Derivative of Double Layer Potential Different Points of View

- **Divergent Integral (Hypersingular kernel) :**

$$H. P. V. \int_B M(s, x) u(s) dB(s)$$

- **Divergent Series (Dual series representation) :**

$$C(N, 2) \left\{ \sum_{m=0}^N \int_B t_m(s) u(s, t) dB(s) t_m(x) \right\}$$

- **Cesaro Sum (Arithmetic mean) :**

$$S_N(x, t) = C(N, 1) \left\{ \sum_{m=0}^N a_m(x, t) \right\} = \frac{s_0(x, t) + s_1(x, t) + \dots + s_{N-1}(x, t) + s_N(x, t)}{N + 1}$$

- **Reproducing Kernel (Fejer kernel) :**

$$F_{N+1}(x) = \frac{1}{2\pi(N+1)} \frac{\sin^2((N+1)x/2)}{\sin^2(x/2)}$$

- **Moving Average (MA model) :**

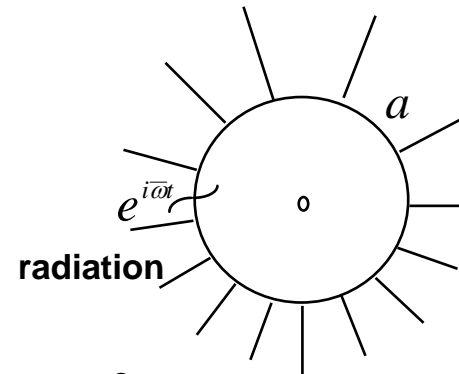
$$S_N(x, t) = \frac{1}{N+1} \sum_{m=0}^N (N-m+1) a_m(x, t)$$

- **Stokes' Transformation (Summation by parts) :**

$$f'(x) = \frac{d}{dx} \left[ \sum_{k=0}^N c_k u_k(x) \right] = \sum_{k=0}^N c_k u_k'(x) + \sum_{k=0}^N b_k u_k'(x)$$

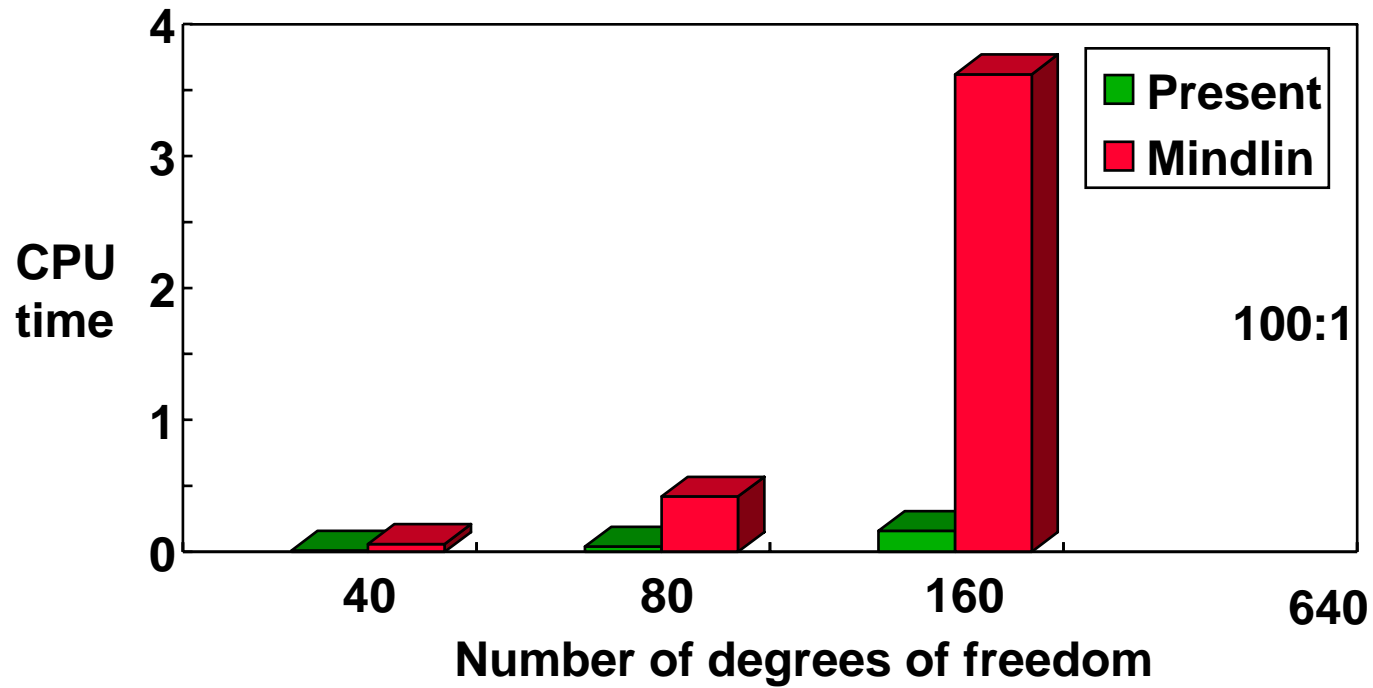


## Applications of Dual Series Representations



$$u = \lim_{\bar{\omega} \rightarrow \omega} \frac{0}{0} \rightarrow \text{finite, if } \bar{\omega} \rightarrow \omega$$

## Comparisons of CPU Time



## Reproducing Techniques for Solutions

**Solution**  $u(x,t)$  ?

**Modal dynamics**

$$u(x,t) = \sum_{k=0}^{k=n} \bar{q}_k(t) u_k(x)$$

?

**Fourier integral**

$$u(x,t) = \int_{-\infty}^{\infty} U(x,\omega) e^{-i\omega t} d\omega$$

**Reproducing**

$$u(x,t) = C(N,r) \sum_{k=0}^{k=N} \bar{q}_k(t) u_k(x)$$

$$u(x,t) = \int_{-\pi}^{\pi} K_N^r(x-s) u(s,t) ds$$

$$K_N^1(x-s) = \frac{1}{(N+1)} \frac{\sin^2((N+1)(x-s)/2)}{\sin^2((x-s)/2)}$$

$$u(x,t) = \int_{-\infty}^{\infty} U(x,\omega) W(\omega) e^{-i\omega t} d\omega$$

$$u(x,t) = \sum_{k=-N}^{k=N} U(x,\omega_k) w_k^r e^{-i\omega_k t} \Delta\omega$$

$$w_n^r = \frac{\Gamma(N+1) \Gamma(N+r-n+1)}{\Gamma(N-n) \Gamma(N+r+1)}$$

## *Conclusions*

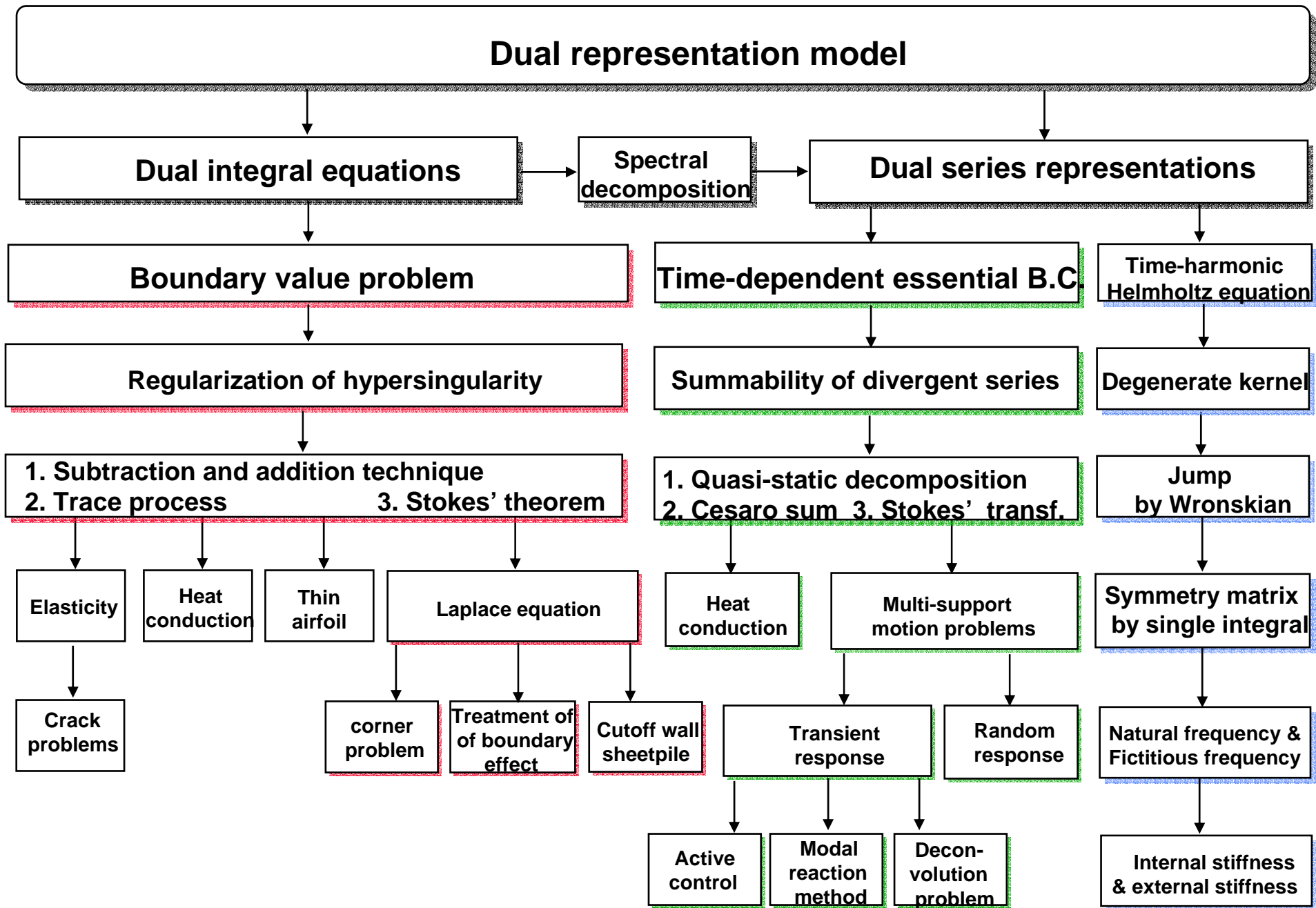
- The theory of dual integral equation has been reviewed
- The role of hypersingularity is examined
- The dual series representations are introduced
- The applications to seepage flow with sheet piles, crack problem and thin airfoil aerodynamics have been demonstrated.
- The applications of dual series representations to multi-support motions is demonstrated.

Hypersingularity

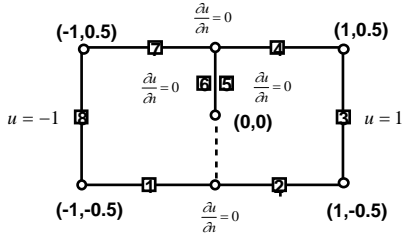
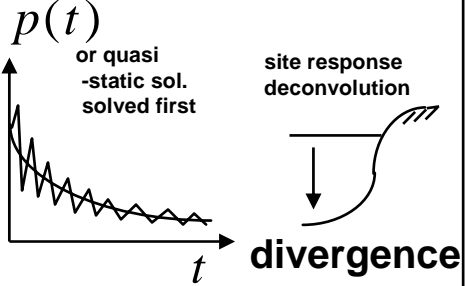
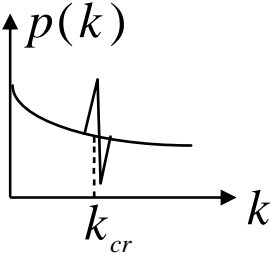


Divergent series



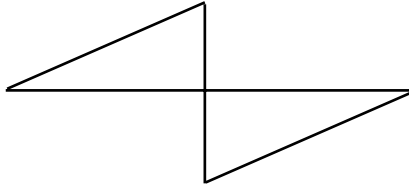


## Why Dual Representation Model ?

	Boundary value problem	Initial-boundary value problem	Time harmonic problem
Physical problem	Flow with corners or sheetpiles	Multi-support motions	exterior radiation
Mathematical tools	H.P.V. hypersingularity	Cesaro sum Stokes' transformation	Wronskian Hilbert transform determinant
Numerical problem			
Numerical improvement	avoid artificial boundary and. boundary effect	avoid quasi-static solution and accelerate convergence	Avoid fictitious eigenvalue

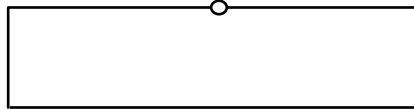


# How to Simulate the Discontinuity ?



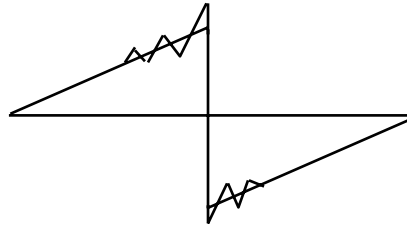
**CPV + jump term**

$$\pm \frac{1}{2}u(x) + CPV \int_{\mathbb{R}} f(s,x)u(s)dB(s)$$



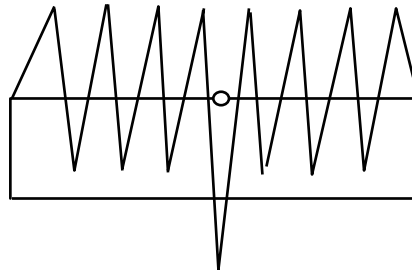
**HPV**

$$HPV \int_{\mathbb{R}} M(s,x)u(s)dB(s)$$



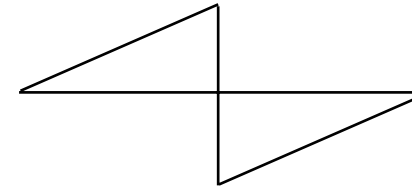
**Gibbs phenomenon**

$$\sum c_i u_i(x)$$



**divergent series**

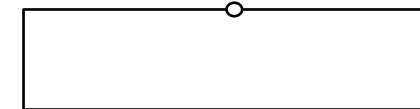
$$\sum c_i t_i(x)$$



**degenerate series**

$$T^i(s,x) = \sum_{m=-\infty}^{m=\infty} \frac{i}{c_m} \{ \nabla_s C_m(ks) \cdot n(s) \} R_m(kx)$$

$$T^e(s,x) = \sum_{m=-\infty}^{m=\infty} \frac{i}{c_m} C_m(kx) \{ \nabla_s R_m(ks) \cdot n(s) \}$$



**degenerate series**

$$M^i(s,x) = \sum_{m=-\infty}^{m=\infty} \frac{i}{c_m} \{ \nabla_x C_m(ks) \cdot n(s) \} \{ \nabla_s R_m(kx) \cdot n(x) \}$$

$$M^e(s,x) = \sum_{m=-\infty}^{m=\infty} \frac{i}{c_m} \{ \nabla_x C_m(kx) \cdot n(x) \} \{ \nabla_s R_m(ks) \cdot n(s) \}$$

