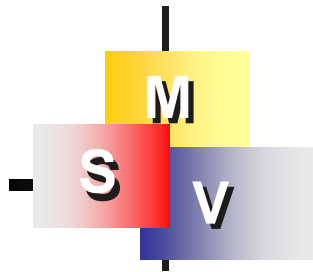


# Part III

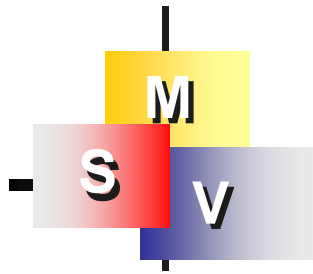
## Plate vibration



# Outlines

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1. Introduction
2. Plate vibration
3. Derivation by Circulants
4. SVD updating terms
5. Conclusions



# Outlines

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- 1. Introduction**
- 2. Plate vibration**
- 3. Derivation by Circulants**
- 4. SVD updating terms**
- 5. Conclusions**

M

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V

# Vibration of plates

## Governing Equation:

$$\nabla^4 u(x) = \lambda^4 u(x), \quad x \in \Omega$$

$$\lambda^4 = \frac{\omega^2 \rho h}{D}$$

$$D = \frac{E h^3}{12 (1 - \nu^2)}$$

$\omega$  is the angle frequency

$\nabla^4$  is the harmonic operator

$\rho$  is the surface density

$D$  is the flexural rigidity

$h$  is the plates thickness

$E$  is the Young's modulus of the thin plates

$\nu$  is the Poisson ration

M

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# Field representation using RBF

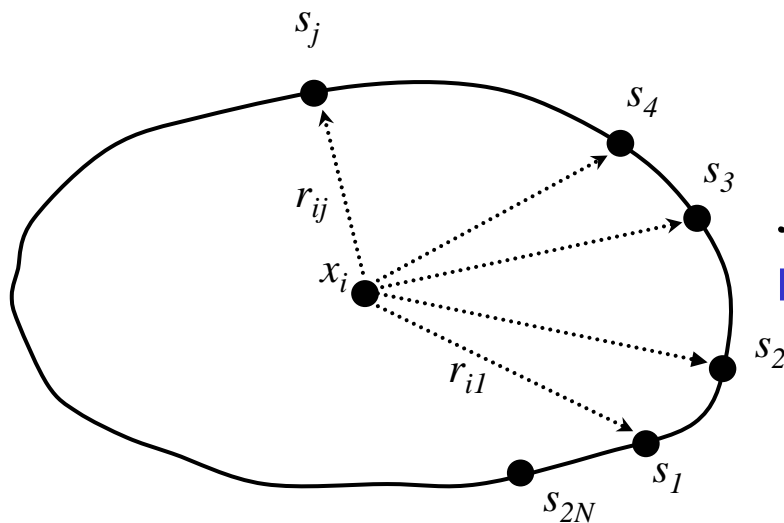
$$u(x) = \sum c_j \psi(x_i, s_j)$$

$$\psi(x, s) = \psi(r)$$

$$\{u\} = \begin{bmatrix} \cdot & * & * & * & * \\ * & \cdot & * & * & * \\ * & * & \cdot & * & * \\ * & * & * & \cdot & * \\ * & * & * & * & \cdot \end{bmatrix} \{c\}$$

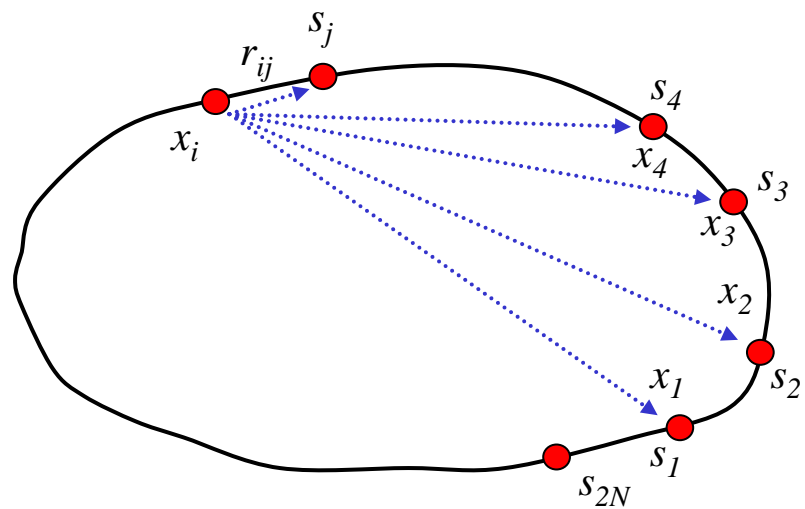
$r \neq 0$

$r = 0$



Field representation

$x \rightarrow B$



To match B.C.

M

S

V

# Data bank of RBF

Radial basis function (RBFs)

Mesh method

Meshless method

Globally-supported RBFs

Compactly-supported RBFs  
C.S. Chen

Globally-supported RBFs

DRBEM

Nardini  
Brebbia  
1982

Method of particular integral

Ahmad & Banerjee  
1986

$$\psi(r) = (1-r)_+^4 (4r+1)$$

Volume potential

The present method

Imaginary-part fundamental solution

$$\psi(r) = 1 + r$$

$$\psi(r) = C - r$$

Method of fundamental solution

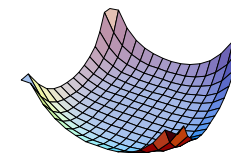
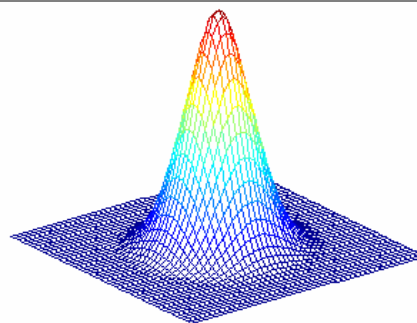
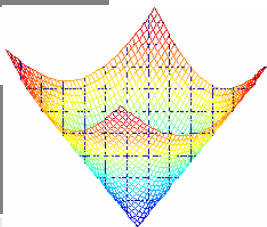
$$\psi(r) = J_0(\lambda r) + I_0(\lambda r)$$

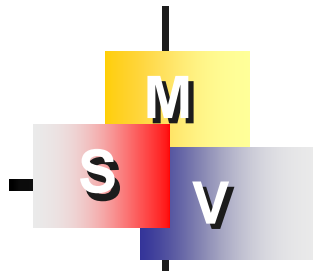
Equivalence

Polyzos & Beskos  
1994

$$\begin{aligned} \psi(r) &= U_c(s, x) \\ &= U_c(|x-s|) \\ &= U_c(r) \end{aligned}$$

(Potential theory)

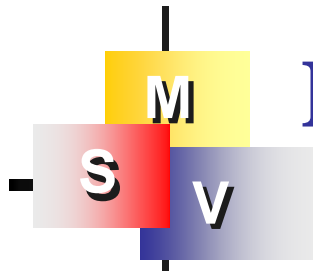




# Outlines

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1. Introduction
2. Plate vibration
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# Displacement field of plate vibration

$$u(s, x) = \sum_{j=1}^{2N} P(s_j, x)\phi_j + \sum_{j=1}^{2N} Q(s_j, x)\psi_j$$

$2N$  is the number of boundary nodes

$s$  is the source point

$x$  is the collocation point

$\nearrow_j$  and  $\triangleleft_j$  are the unknown densities

$P$  and  $Q$  can be obtained from either two combinations of  $U$ ,  $\nearrow$ ,  $M$  and  $V$



M

S

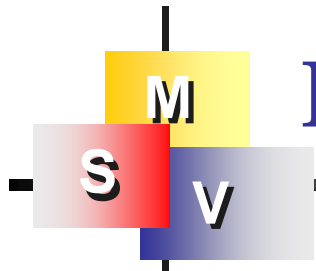
V

## Four kernels

### Imaginary-part fundamental solution

$$U(s, x) = \text{Im} \left\{ \frac{i}{8\lambda^2} (H_0^{(2)}(\lambda r) + H_0^{(1)}(i\lambda r)) \right\}$$

$$U(s, x) = \frac{1}{8\lambda^2} (J_0(\lambda r) + I_0(\lambda r))$$



## Four kernels

---

$$\Theta(s, x) = K_{\theta}(U(s, x))$$

$$M(s, x) = K_m(U(s, x))$$

$$V(s, x) = K_v(U(s, x))$$

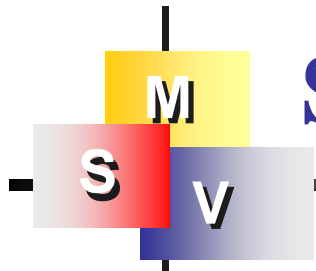


# Operators

$$K_{\theta}(\cdot) = \frac{\partial(\cdot)}{\partial n}$$

$$K_m(\cdot) = \nu \nabla^2(\cdot) + (1 - \nu) \frac{\partial^2(\cdot)}{\partial n^2}$$

$$K_{\nu}(\cdot) = \frac{\partial \nabla^2(\cdot)}{\partial n} + (1 - \nu) \frac{\partial}{\partial t} \left( \frac{\partial^2(\cdot)}{\partial n \partial t} \right)$$



# Slope, Moment and Shear

**Slope**  $\theta(x) = K_{\theta}(u(x))$

**Moment**  $m(x) = K_m(u(x))$

**Shear**  $v(x) = K_v(u(x))$

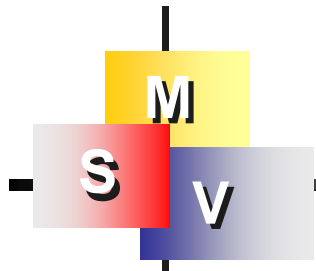
M

S

V

# True eigenequation of three cases

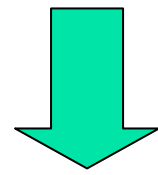
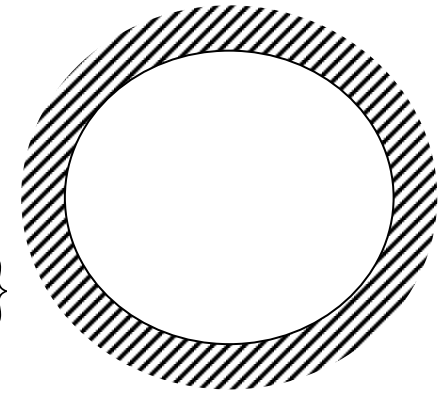
	B.C.	True eigenequation
Clamped plate	$u(x)=0$ $\square(x)=0$	$J'_\ell(\lambda\rho)I_\ell(\lambda\rho) - I'_\ell(\lambda\rho)J_\ell(\lambda\rho) = 0$
Simply-supported plate	$u(x)=0$ $m(x)=0$	$\frac{I_{\ell+1}(\lambda\rho)}{I_\ell(\lambda\rho)} + \frac{J_{\ell+1}(\lambda\rho)}{J_\ell(\lambda\rho)} = \frac{2\lambda\rho}{(1-\nu)}$
Free plate	$m(x)=0$ $v(x)=0$	$(\ell^2(\ell^2-1)(-1+\nu)^2 + \lambda^4 a^4)(J_{\ell+1}(\lambda a)I_\ell(\lambda a) + J_\ell(\lambda a)I_{\ell+1}(\lambda a))$ $+ 2\ell\lambda^2 a^2(1-\ell)(-1+\nu)(J_{\ell+1}(\lambda a)I_\ell(\lambda a) - J_\ell(\lambda a)I_{\ell+1}(\lambda a))$ $+ \lambda a(-1+\nu)(2\lambda^2 a^2 J_{\ell+1}(\lambda a)I_{\ell+1}(\lambda a) + 4\ell^2(-1+\ell)J_\ell(\lambda a)I_\ell(\lambda a)) = 0$



# Clamped plate

$$u(x) = 0 \implies [U]\{\phi\} + [\Theta]\{\psi\} = \{0\}$$

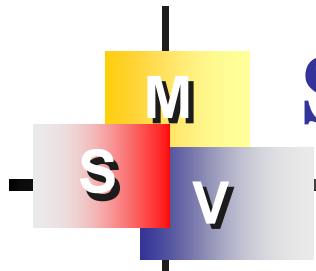
$$\theta(x) = 0 \implies [U_\theta]\{\phi\} + [\Theta_\theta]\{\psi\} = \{0\}$$



Nontrivial

$$0 = \det[SM^c]$$

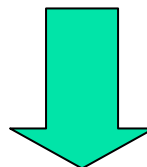
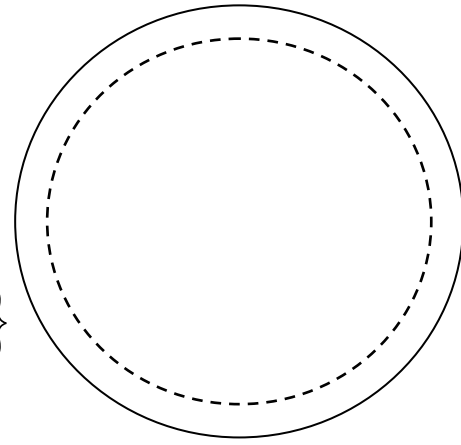
$$\begin{bmatrix} U & \Theta \\ U_\theta & \Theta_\theta \end{bmatrix} \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$



# Simply-supported plate

$$u(x) = 0 \implies [U]\{\phi\} + [\Theta]\{\psi\} = \{0\}$$

$$m(x) = 0 \implies [U_m]\{\phi\} + [\Theta_m]\{\psi\} = \{0\}$$



**Nontrivial**

$$0 = [SM^s]$$

$$\begin{bmatrix} U & \Theta \\ U_m & \Theta_m \end{bmatrix} \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

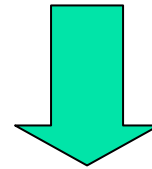
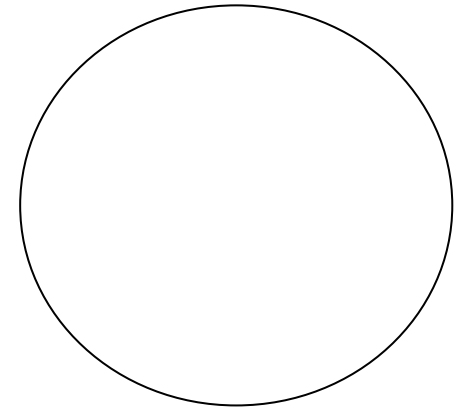




# Free plate

$$m(x) = 0 \implies [U_m]\{\phi\} + [\Theta_m]\{\psi\} = \{0\}$$

$$v(x) = 0 \implies [U_v]\{\phi\} + [\Theta_v]\{\psi\} = \{0\}$$



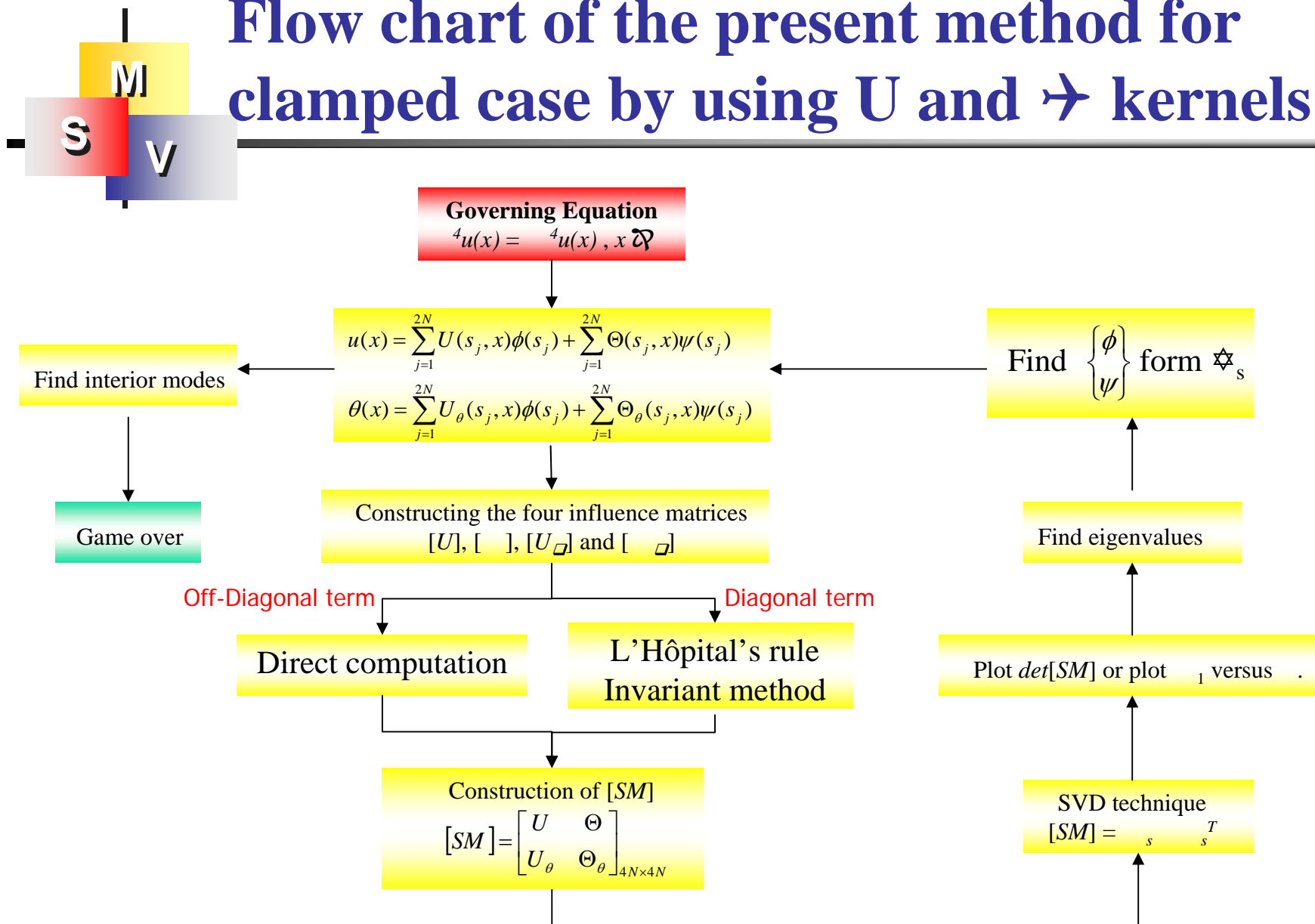
**Nontrivial**

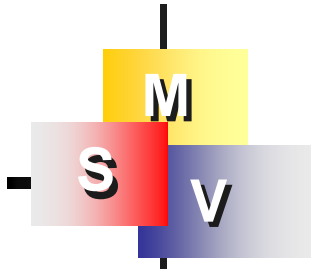
$$0 = [SM^F]$$

$$\begin{bmatrix} U_m & \Theta_m \\ U_v & \Theta_v \end{bmatrix} \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

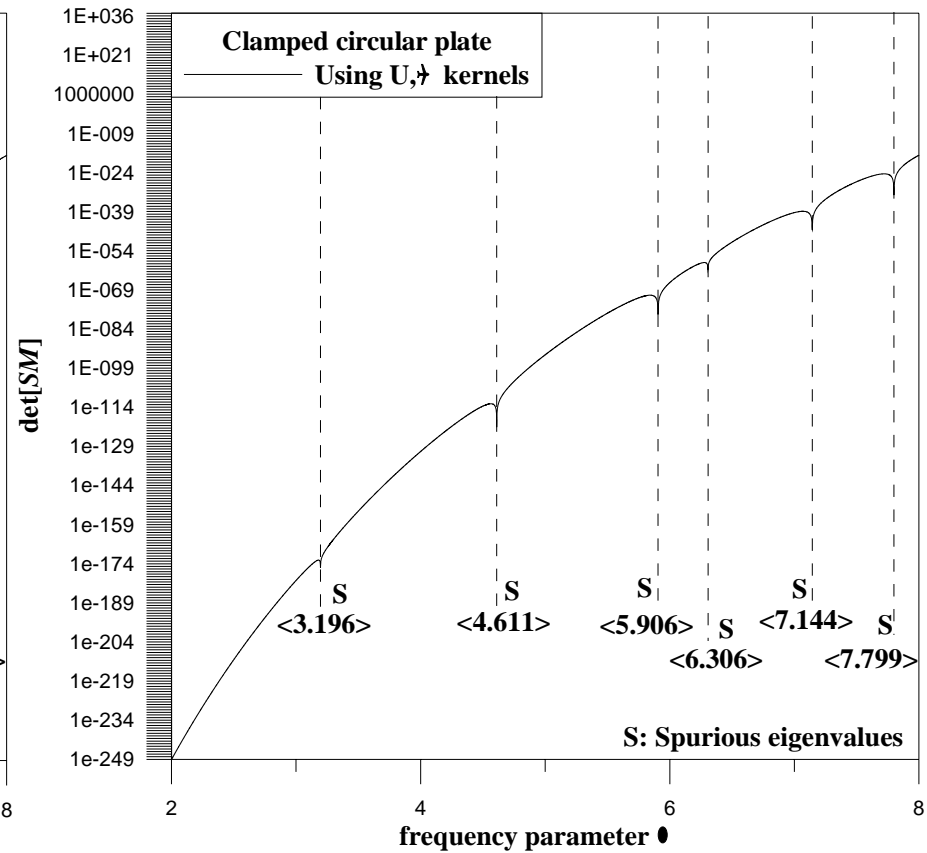
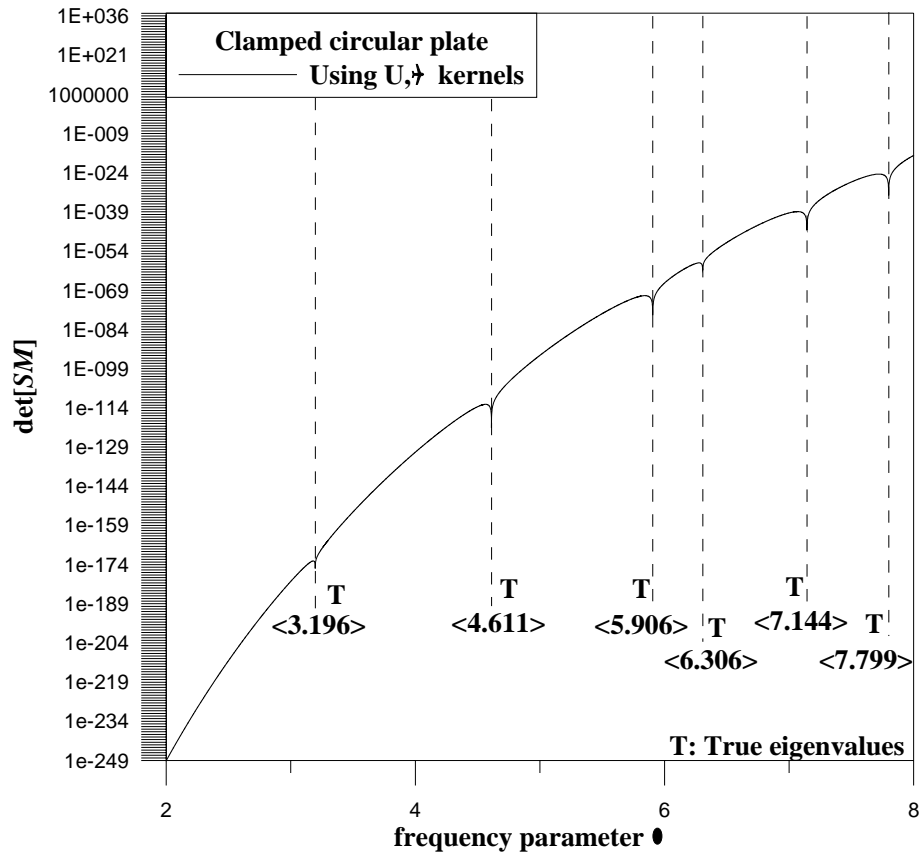


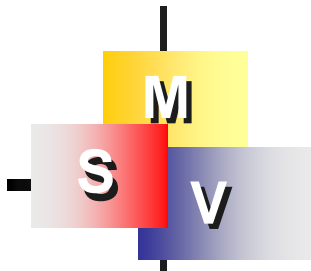
# Flow chart of the present method for clamped case by using U and $\Theta$ kernels



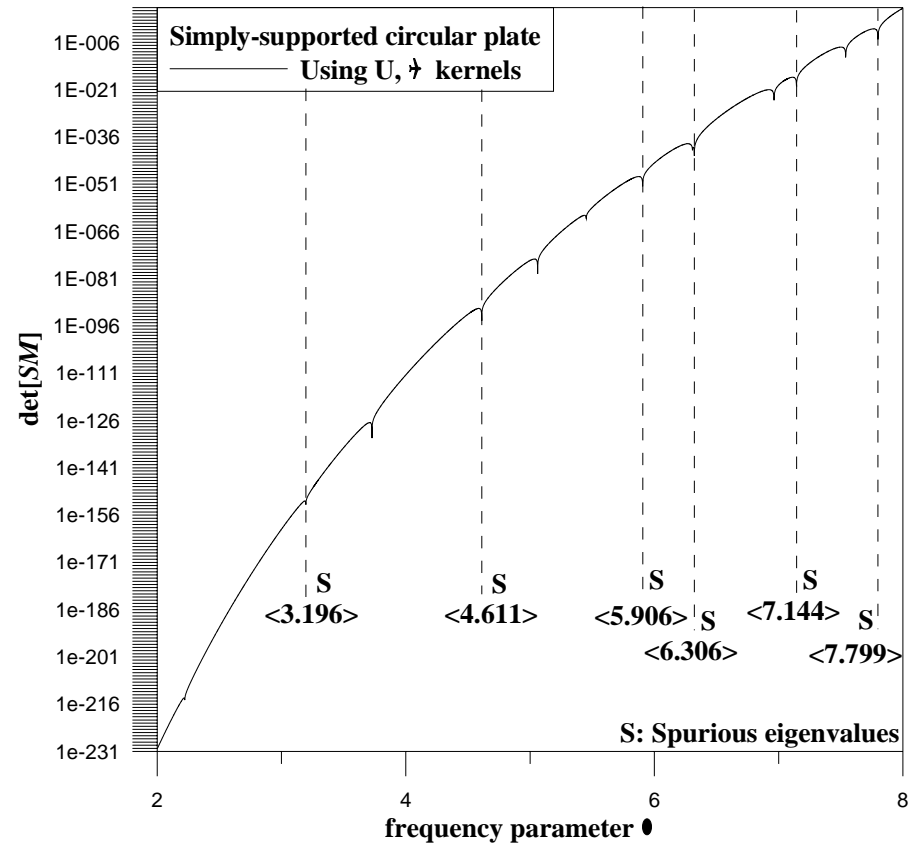
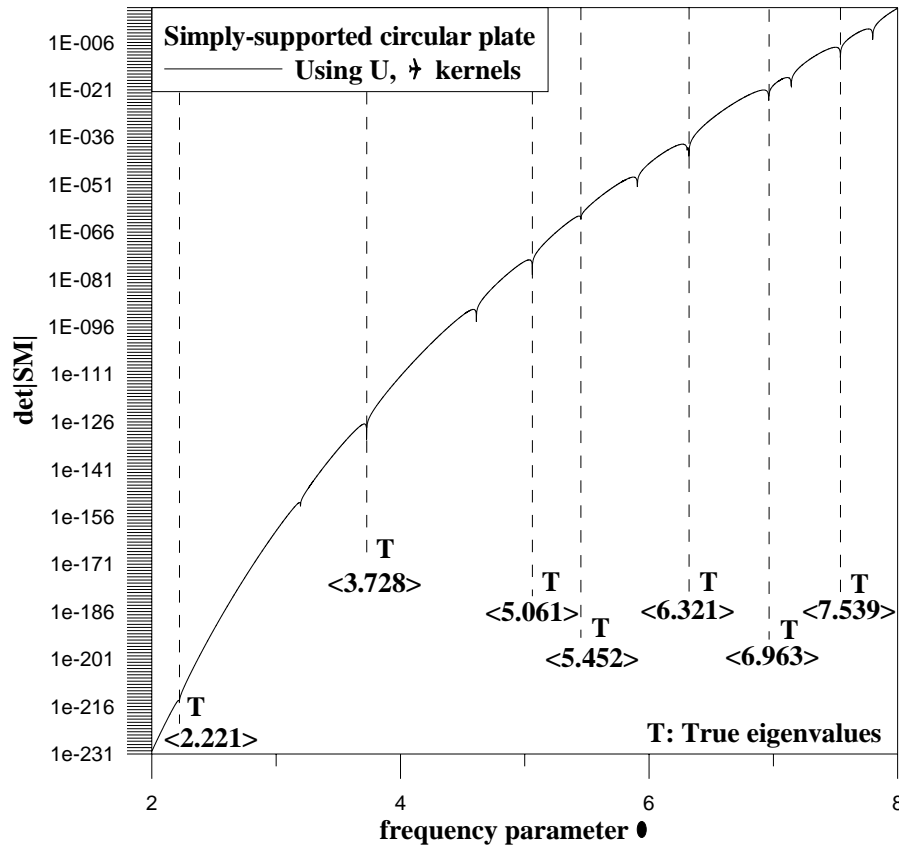


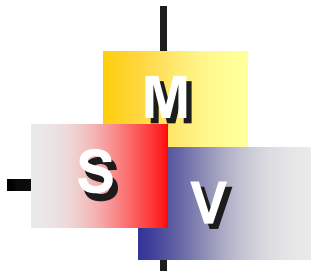
# Case 1: Circular clamped plate using the present method



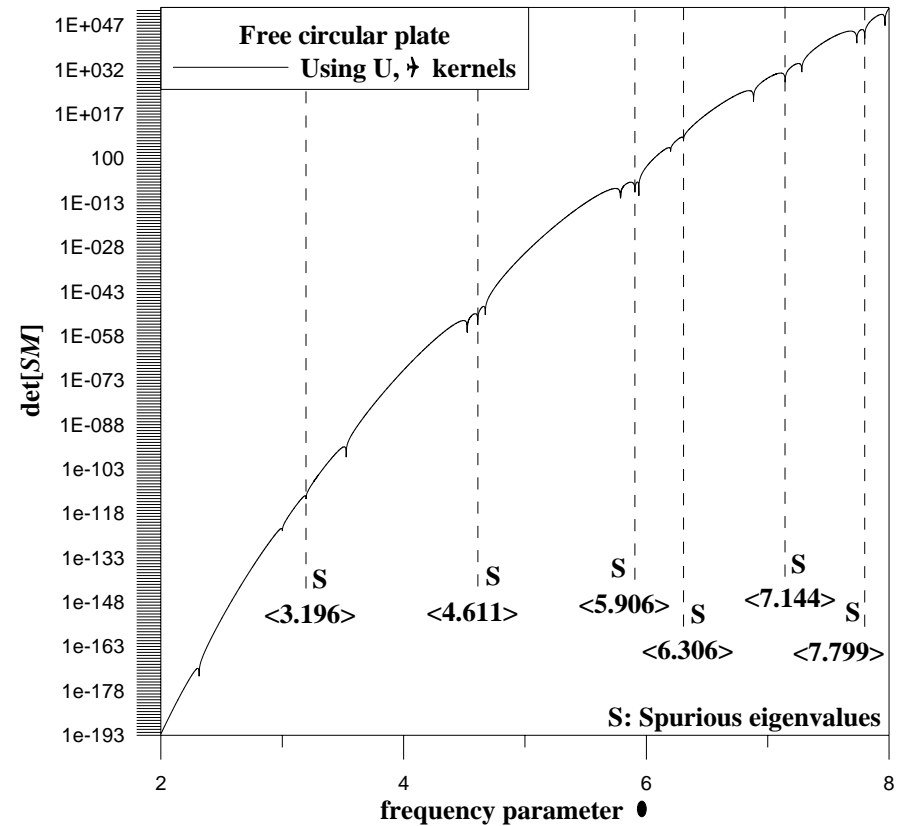
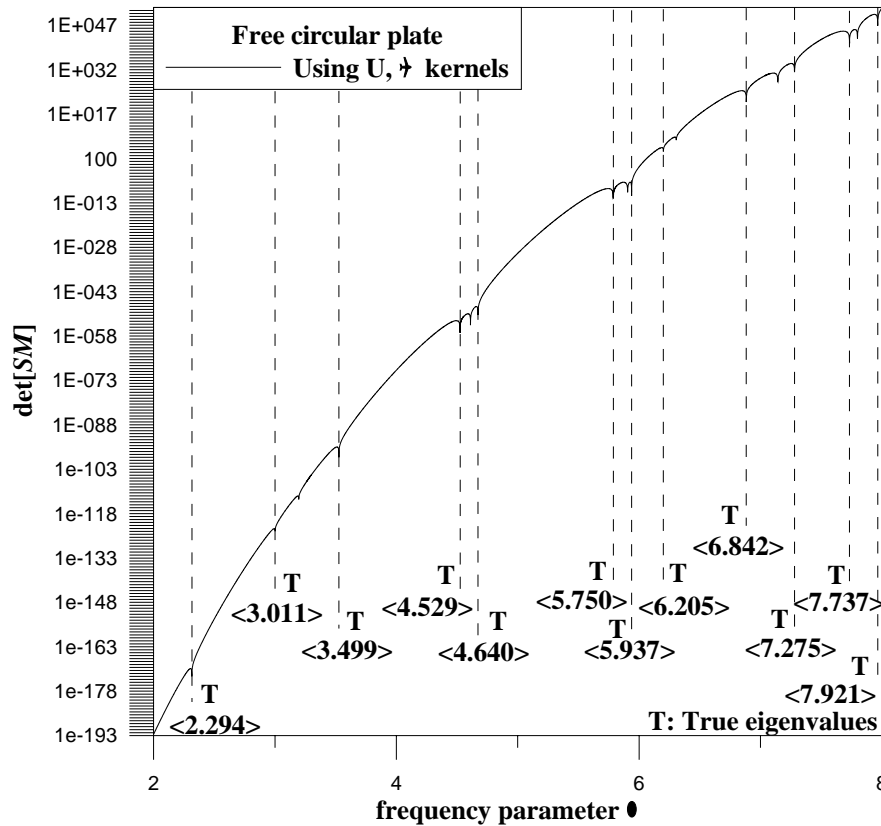


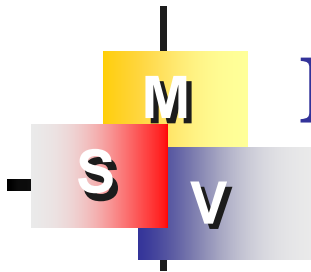
# Case 2: Circular simply-supported plate using the present method



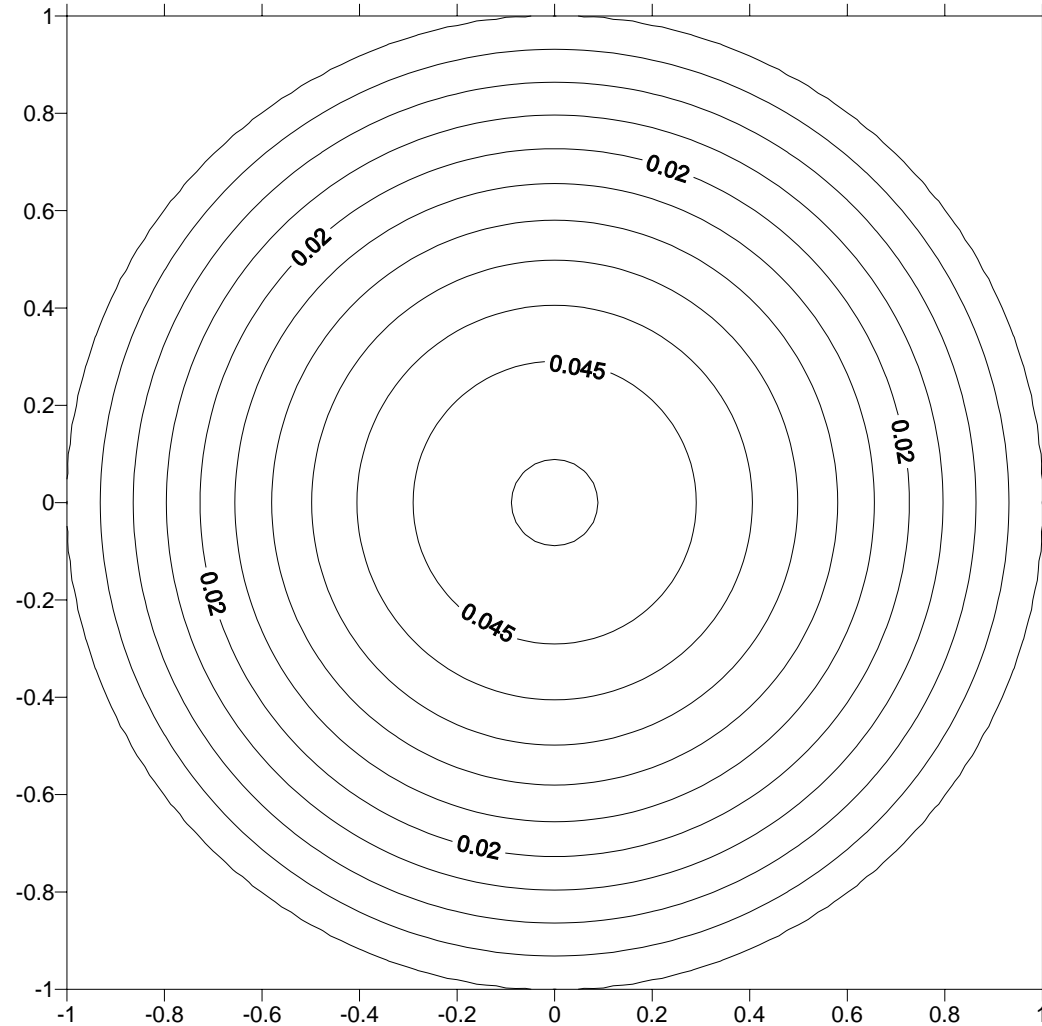


# Case 3: Circular free plate using the present method





# Mode 1 ( $\omega = 2.221$ )

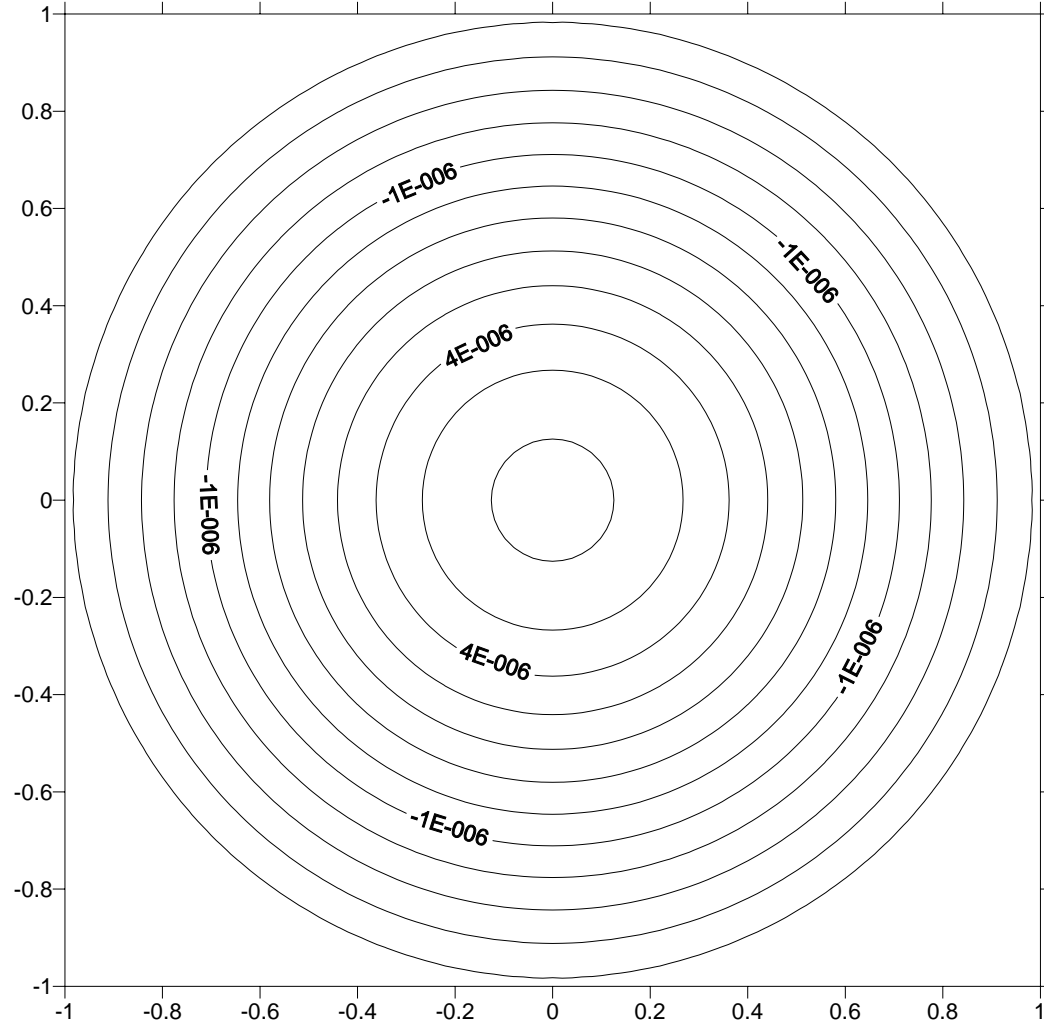


M

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V

# Mode 2 ( $\omega = 3.196$ )

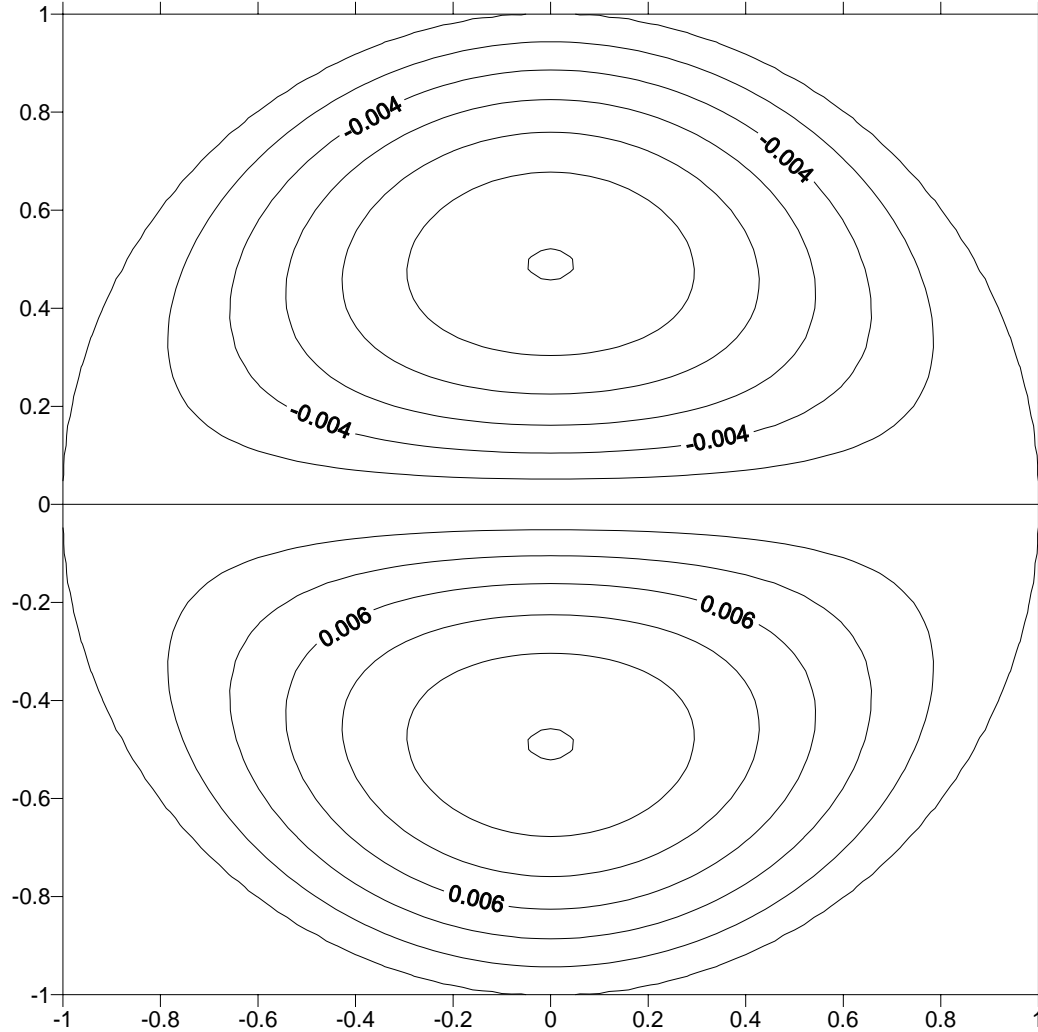


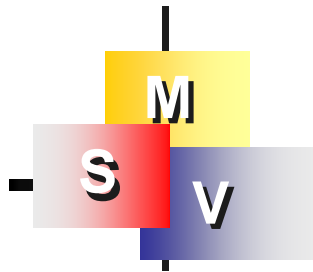
M

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V

# Mode 3 ( $\omega = 3.728$ )





# Outlines

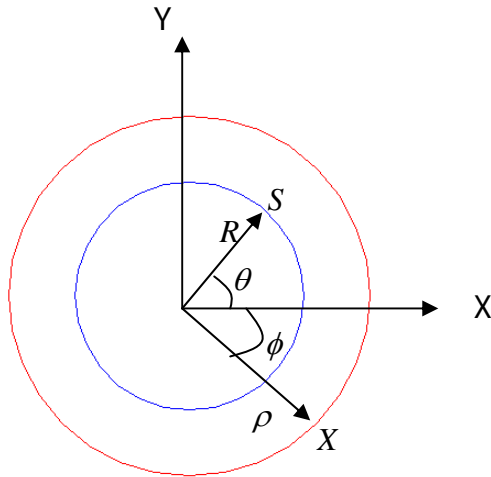
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1. Introduction
2. Plate vibration
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4. SVD updating terms
5. Conclusions

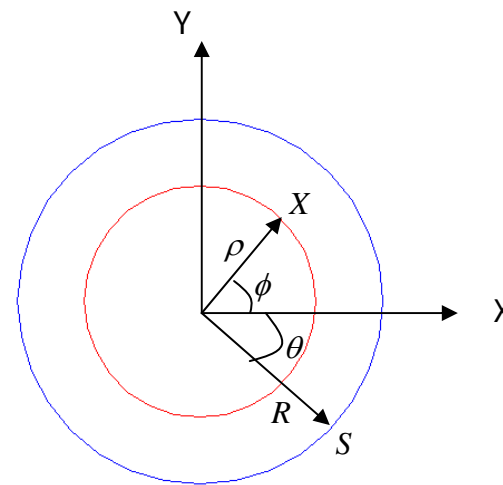


# Degenerate kernels for circular case

The degenerate kernels for interior and exterior problems:



Exterior problem



Interior problem

Blue: field points  
Red: source points

$$U(s, x) = \begin{cases} U^I(R, \theta; \rho, \phi) = \frac{1}{8\lambda^2} \sum_{m=-\infty}^{\infty} [J_m(\lambda R)J_m(\lambda \rho) + (-1)^m I_m(\lambda R)I_m(\lambda \rho)](\cos(m(\theta - \phi))), & R > \rho \\ U^E(R, \theta; \rho, \phi) = \frac{1}{8\lambda^2} \sum_{m=-\infty}^{\infty} [J_m(\lambda \rho)J_m(\lambda R) + (-1)^m I_m(\lambda \rho)I_m(\lambda R)](\cos(m(\theta - \phi))), & R < \rho \end{cases}$$

M

S

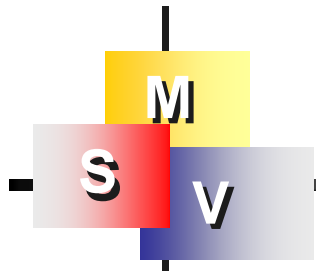
V

# Circulants

$$[K] = \begin{bmatrix} a_0 & a_1 & a_2 & \cdots & a_{2N-2} & a_{2N-1} \\ a_{2N-1} & a_0 & a_1 & \cdots & a_{2N-3} & a_{2N-2} \\ a_{2N-2} & a_{2N-1} & a_0 & \cdots & a_{2N-4} & a_{2N-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ a_2 & a_3 & a_4 & \cdots & a_0 & a_1 \\ a_1 & a_2 & a_3 & \cdots & a_{2N-1} & a_0 \end{bmatrix}$$

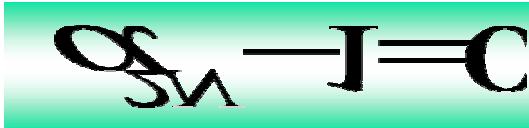
$$a_{j-i} = K(s_j, x_i)$$

$$[K] = a_0 I + a_1 (C_{2N})^1 + a_2 (C_{2N})^2 + \cdots + a_{2N-1} (C_{2N})^{2N-1}$$



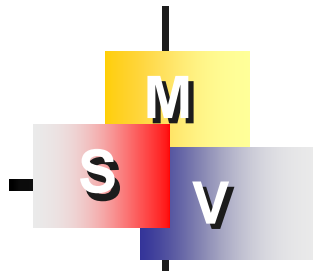
# Circulants

$$C_{2N} = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 0 & 1 \\ 1 & 0 & 0 & \dots & 0 & 0 \end{bmatrix}_{2N \times 2N}$$



$$\alpha_\ell = e^{i\frac{2\pi\ell}{2N}} = \cos\left(\frac{2\pi\ell}{2N}\right) + i \sin\left(\frac{2\pi\ell}{2N}\right)$$





# Circulants

$$\lambda_\ell^{[U]} = a_0 + a_1 \alpha_\ell + a_2 \alpha_\ell^2 + \cdots + a_{2N-1} \alpha_\ell^{2N-1}$$

$$\ell = 0, \pm 1, \pm 2, \cdots, \pm (N-1), N$$

$$\lambda_\ell^{[U]} = \frac{N}{4\lambda^2} [J_\ell(\lambda\rho)J_\ell(\lambda\rho) + (-1)^\ell I_\ell(\lambda\rho)I_\ell(\lambda\rho)]$$

M

S

V

# The eigenvalues of matrices

$$[U] = \Phi \Sigma_U \Phi^T$$

$$= \Phi \begin{bmatrix} \lambda_0^{[U]} & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & \lambda_1^{[U]} & 0 & \cdots & 0 & 0 & 0 \\ 0 & 0 & \lambda_{-1}^{[U]} & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda_{(N-1)}^{[U]} & 0 & 0 \\ 0 & 0 & 0 & \cdots & 0 & \lambda_{-(N-1)}^{[U]} & 0 \\ 0 & 0 & 0 & \cdots & 0 & 0 & \lambda_N^{[U]} \end{bmatrix} \Phi^T$$

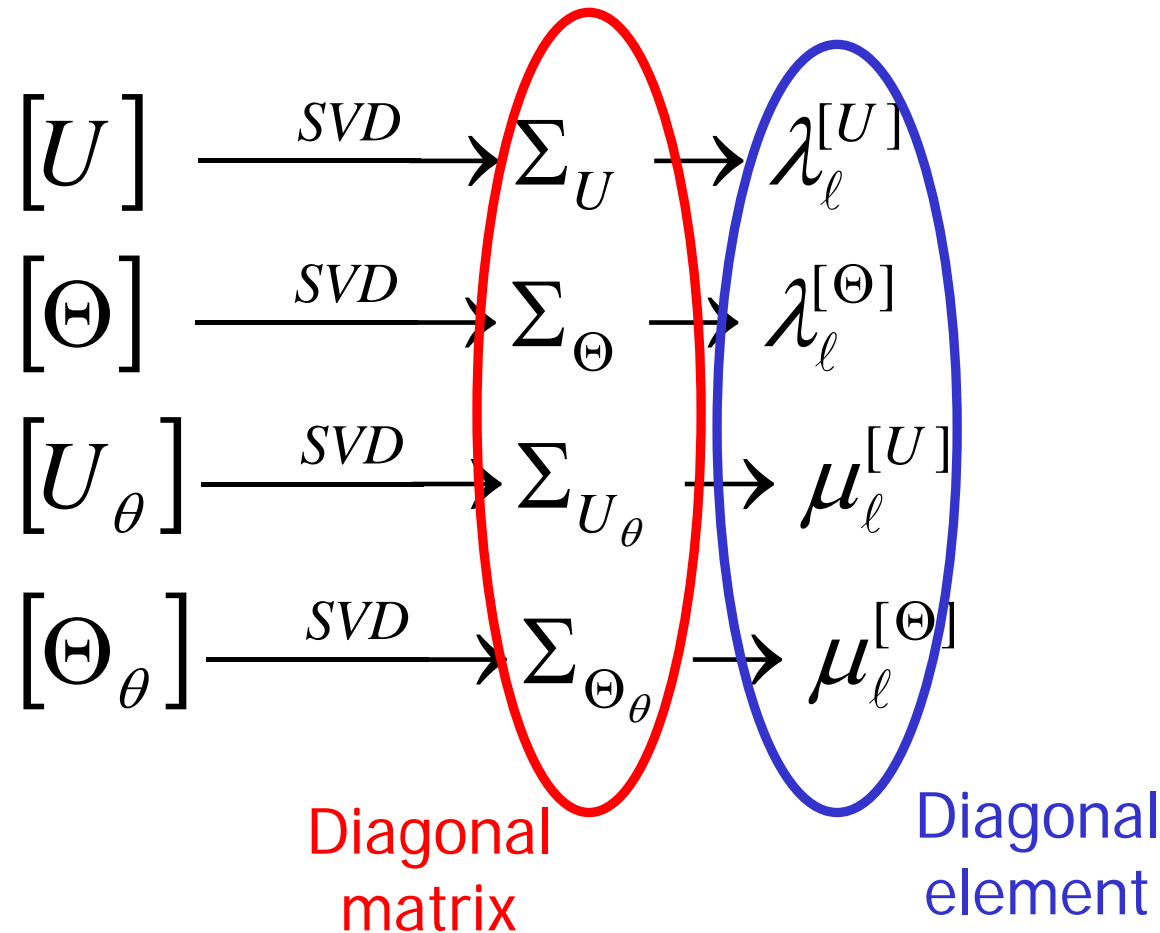
$2N \times 2N$

M

S

V

# Relationships



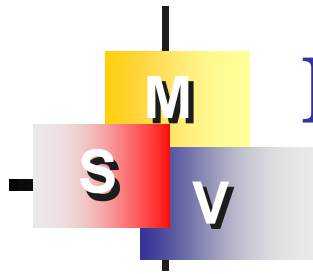
M

S

V

## Determinant (for clamped)

$$\begin{aligned}
 [SM^c] &= \begin{bmatrix} \Phi \Sigma_U \Phi^T & \Phi \Sigma_{\Theta} \Phi^T \\ \Phi \Sigma_{U_\theta} \Phi^T & \Phi \Sigma_{\Theta_\theta} \Phi^T \end{bmatrix}_{2N \times 2N} \\
 &= \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_U & \Sigma_{\Theta} \\ \Sigma_{U_\theta} & \Sigma_{\Theta_\theta} \end{bmatrix} \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix}^T
 \end{aligned}$$



# Eigenequation for clamped boundary

$$\det[ SM^C ]$$

$$= \prod_{\ell=-(N+1)}^N (\lambda_{\ell}^{[U]} \mu_{\ell}^{[\Theta]} - \lambda_{\ell}^{[\Theta]} \mu_{\ell}^{[U]})$$

$$= \prod_{\ell=-(N+1)}^N \frac{(-1)^{\ell} N^2}{16 \lambda^2} [J_{\ell+1}(\lambda \rho) I_{\ell}(\lambda \rho) + I_{\ell+1}(\lambda \rho) J_{\ell}(\lambda \rho)]$$

$$\{ J_{\ell+1}(\lambda \rho) I_{\ell}(\lambda \rho) + I_{\ell+1}(\lambda \rho) J_{\ell}(\lambda \rho) \} = 0,$$

$$\ell = 0, \pm 1, \pm 2, \dots, \pm (N-1), N$$



M

S

V

# Determinant (for simply-supported)

$$\begin{aligned}
 [SM^S] &= \begin{bmatrix} \Phi \Sigma_U \Phi^T & \Phi \Sigma_{\Theta} \Phi^T \\ \Phi \Sigma_{U_m} \Phi^T & \Phi \Sigma_{\Theta_m} \Phi^T \end{bmatrix} \\
 &= \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_U & \Sigma_{\Theta} \\ \Sigma_{U_m} & \Sigma_{\Theta_m} \end{bmatrix} \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix}^T
 \end{aligned}$$

M

S

V

# Relationships

$$[U] \xrightarrow{SVD} \Sigma_U \rightarrow \lambda_l^{[U]}$$

$$[\Theta] \xrightarrow{SVD} \Sigma_{\Theta} \rightarrow \lambda_l^{[\Theta]}$$

$$[U_m] \xrightarrow{SVD} \Sigma_{U_m} \rightarrow v_l^{[U]}$$

$$[\Theta_m] \xrightarrow{SVD} \Sigma_{\Theta_m} \rightarrow v_l^{[\Theta]}$$

M

S

V

## Eigenequation for simply-supported boundary

$$\det[SM^S]$$

$$= \prod_{\ell=-(N+1)}^N (\lambda_\ell^{[U]} v_\ell^{[\Theta]} - \lambda_\ell^{[\Theta]} v_\ell^{[U]})$$

$$= \prod_{\ell=-(N+1)}^N \frac{(-1)^\ell N^2}{16\lambda^2 \rho} [J_\ell(\lambda\rho) I_{\ell+1}(\lambda\rho) + I_\ell(\lambda\rho) J_{\ell+1}(\lambda\rho)]$$

$$\{(-1+\nu)(J_{\ell+1}(\lambda\rho) I_\ell(\lambda\rho) + J_\ell(\lambda\rho) I_{\ell+1}(\lambda\rho)) + 2\lambda\rho J_\ell(\lambda\rho) I_\ell(\lambda\rho)\} = 0$$

$$\ell = 0, \pm 1, \pm 2, \dots, \pm(N-1), N$$

M

S

V

# Determinant (for simply-supported)

$$\begin{aligned}
 [SM^F] &= \begin{bmatrix} \Phi \Sigma_{U_m} \Phi^T & \Phi \Sigma_{\Theta_m} \Phi^T \\ \Phi \Sigma_{U_v} \Phi^T & \Phi \Sigma_{\Theta_v} \Phi^T \end{bmatrix} \\
 &= \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_{U_m} & \Sigma_{U_m} \\ \Sigma_{U_v} & \Sigma_{\Theta_v} \end{bmatrix} \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix}^T
 \end{aligned}$$

M

S

V

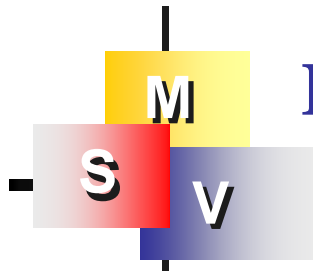
# Relationships

$$[U_m] \xrightarrow{SVD} \Sigma_{U_m} \rightarrow v_l^{[U]}$$

$$[\Theta_m] \xrightarrow{SVD} \Sigma_{\Theta_m} \rightarrow v_l^{[\Theta]}$$

$$[U_v] \xrightarrow{SVD} \Sigma_{U_v} \rightarrow \delta_l^{[U]}$$

$$[\Theta_v] \xrightarrow{SVD} \Sigma_{\Theta_v} \rightarrow \delta_l^{[\Theta]}$$



## Eigenequation for free boundary

$$\det[SM^F]$$

$$= \prod_{\ell=-(N+1)}^N (v_\ell^{[U]} \delta_\ell^{[\Theta]} - v_\ell^{[\Theta]} \delta_\ell^{[U]})$$

$$= \prod_{\ell=-(N+1)}^N \frac{(-1)^\ell N^2}{16\lambda^2 \rho^4} [J_{\ell+1}(\lambda\rho)I_\ell(\lambda\rho) + J_\ell(\lambda\rho)I_{\ell+1}(\lambda\rho)]$$

$$\begin{aligned} & \{\ell^2(\ell^2 - 1)(-1 + \nu)^2 + \lambda^4 \rho^4\} (J_{\ell+1}(\lambda\rho)I_\ell(\lambda\rho) + J_\ell(\lambda\rho)I_{\ell+1}(\lambda\rho)) \\ & + 2\ell\lambda^2 \rho^2 (1 - \ell)(-1 + \nu) (J_{\ell+1}(\lambda\rho)I_\ell(\lambda\rho) - J_\ell(\lambda\rho)I_{\ell+1}(\lambda\rho)) \\ & + \lambda\rho(-1 + \nu) (2\lambda^2 \rho^2 J_{\ell+1}(\lambda\rho)I_{\ell+1}(\lambda\rho) + 4\ell^2(-1 + \ell)J_\ell(\lambda\rho)I_\ell(\lambda\rho)) = 0, \\ & \ell = 0, \pm 1, \pm 2, \dots, \pm(N-1), N \end{aligned}$$

# Comparisons of the NDIF and present method

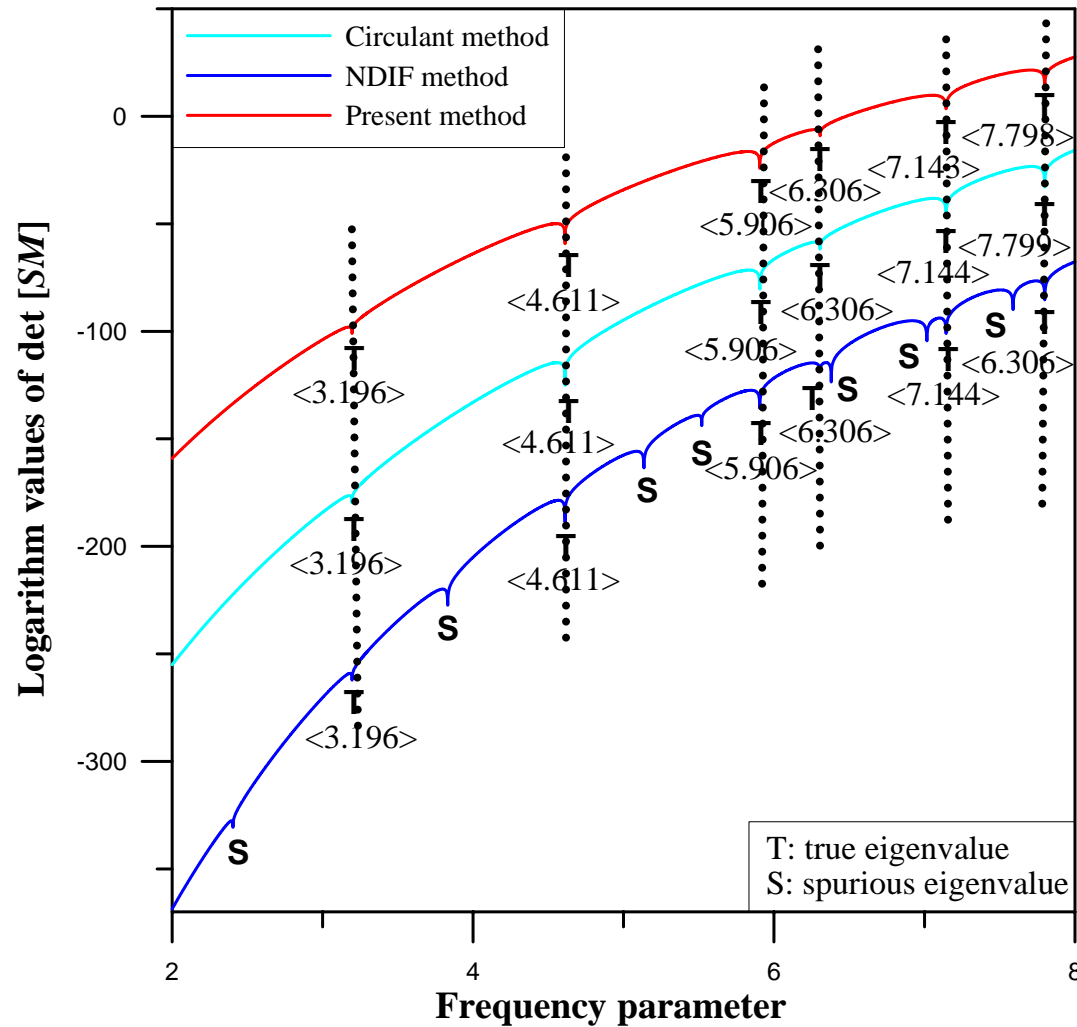
	<b>Kang</b>	<b>Present method</b>
<b>Base</b>	$U(s, x) = J_0(\lambda r)$ $\Theta(s, x) = I_0(\lambda r)$	$U(s, x) = \frac{1}{8\lambda^2} (J_0(\lambda r) + I_0(\lambda r))$ $\Theta(s, x) = \frac{\partial U(s, x)}{\partial n_s}$
<b>Clamped plate</b>	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
	$J_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
<b>Simply-supported plate</b>	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$
	$J_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
<b>Treatment</b>	<b>Net approach</b>	<b>Dual formulation with SVD updating</b>

M

S

V

# Circular clamped plate using different methods





M

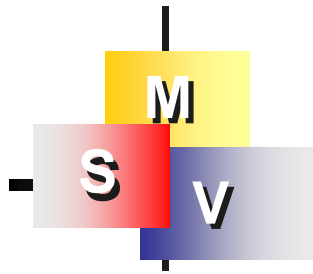
S

V

## Comparisons of Leissa and present method

	Leissa (Kitahara)	Present method
Clamped plate	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
Simply-supported plate	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$
Free plate	$\frac{\lambda^2 J_\ell(\lambda \rho) + (1-\nu)[\lambda J'_\ell(\lambda \rho) - \ell^2 J_\ell(\lambda \rho)]}{\lambda^2 I_\ell(\lambda \rho) - (1-\nu)[\lambda I'_\ell(\lambda \rho) - \ell^2 I_\ell(\lambda \rho)]}$ $= \frac{\lambda^3 I'_\ell(\lambda \rho) + (1-\nu)\ell^2[\lambda J'_\ell(\lambda \rho) - J_\ell(\lambda \rho)]}{\lambda^3 I'_\ell(\lambda \rho) - (1-\nu)\ell^2[\lambda I'_\ell(\lambda \rho) - I_\ell(\lambda \rho)]}$	$\{\ell^2(\ell^2 - 1)(-1 + \nu)^2 + \lambda^4 \rho^4\}(J_{\ell+1}(\lambda \rho)I_\ell(\lambda \rho)$ $+ J_\ell(\lambda \rho)I_{\ell+1}(\lambda \rho)) + 2\ell\lambda^2 \rho^2(1 - \ell)(-1 + \nu)$ $(J_{\ell+1}(\lambda \rho)I_\ell(\lambda \rho) - J_\ell(\lambda \rho)I_{\ell+1}(\lambda \rho)) + \lambda \rho(-1 + \nu)$ $(2\lambda^2 \rho^2 J_{\ell+1}(\lambda \rho)I_{\ell+1}(\lambda \rho) + 4\ell^2(-1 + \ell)J_\ell(\lambda \rho)I_\ell(\lambda \rho))$ $= 0$

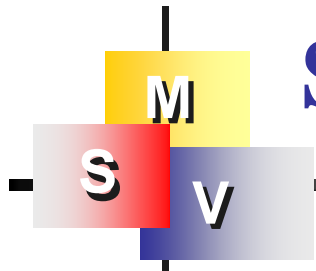
J



# Outlines

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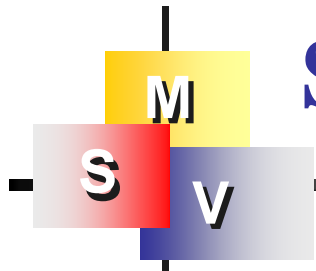
1. Introduction
2. Plate vibration
3. Derivation by Circulants
4. **SVD updating terms**
5. Conclusions



# SVD updating terms (clamped case)

$$[SM^c] \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{bmatrix} U & \Theta \\ U_\theta & \Theta_\theta \end{bmatrix} \begin{Bmatrix} \phi \\ \psi \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

$$[SM_1^c] \begin{Bmatrix} \phi' \\ \psi' \end{Bmatrix} = \begin{bmatrix} M & V \\ M_\theta & V_\theta \end{bmatrix} \begin{Bmatrix} \phi' \\ \psi' \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$



# SVD updating terms (clamped case)

$$[C] = \begin{bmatrix} (SM^C)^T \\ (SM_1^C)^T \end{bmatrix}$$

$$= \begin{bmatrix} \Phi & 0 & 0 & 0 \\ 0 & \Phi & 0 & 0 \\ 0 & 0 & \Phi & 0 \\ 0 & 0 & 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_U & \Sigma_{U_\theta} \\ \Sigma_\Theta & \Sigma_{\Theta_\theta} \\ \Sigma_M & \Sigma_{M_\theta} \\ \Sigma_V & \Sigma_{V_\theta} \end{bmatrix}_{8N \times 4N} \begin{bmatrix} \Phi^{-1} & 0 \\ 0 & \Phi^{-1} \end{bmatrix}$$

M

S

V

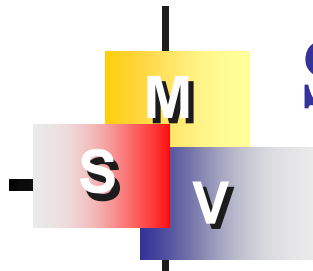
# SVD updating terms (clamped case)

Based on the least squares

$$[C]^T [C] = \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} [D]_{4N \times 4N} \begin{bmatrix} \Phi^{-1} & 0 \\ 0 & \Phi^{-1} \end{bmatrix}$$

$$\det[[C]^T [C]] = \det [D]$$

$$= \prod_{\ell=-(N-1)}^N [(\lambda_{\ell}^{[U]} \mu_{\ell}^{[\Theta]} - \mu_{\ell}^{[U]} \lambda_{\ell}^{[\Theta]})^2 + (\lambda_{\ell}^{[U]} \mu_{\ell}^{[M]} - \mu_{\ell}^{[U]} \lambda_{\ell}^{[M]})^2 \\ + (\lambda_{\ell}^{[U]} \mu_{\ell}^{[V]} - \mu_{\ell}^{[U]} \lambda_{\ell}^{[V]})^2 + (\lambda_{\ell}^{[\Theta]} \mu_{\ell}^{[M]} - \mu_{\ell}^{[\Theta]} \lambda_{\ell}^{[M]})^2 \\ + (\lambda_{\ell}^{[\Theta]} \mu_{\ell}^{[V]} - \mu_{\ell}^{[\Theta]} \lambda_{\ell}^{[V]})^2 + (\lambda_{\ell}^{[M]} \mu_{\ell}^{[V]} - \mu_{\ell}^{[M]} \lambda_{\ell}^{[V]})^2]$$



## SVD updating terms (clamped case)

The only possibility for zero determinant of  $[D]$  

$$(\lambda_l^{[U]} \mu_l^{[\Theta]} - \mu_l^{[U]} \lambda_l^{[\Theta]}) = 0, \quad (\lambda_l^{[U]} \mu_l^{[M]} - \mu_l^{[U]} \lambda_l^{[M]}) = 0,$$

$$(\lambda_l^{[U]} \mu_l^{[V]} - \mu_l^{[U]} \lambda_l^{[V]}) = 0, \quad (\lambda_l^{[\Theta]} \mu_l^{[M]} - \mu_l^{[\Theta]} \lambda_l^{[M]}) = 0,$$

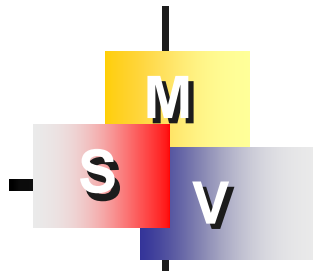
$$(\lambda_l^{[\Theta]} \mu_l^{[V]} - \mu_l^{[\Theta]} \lambda_l^{[V]}) = 0, \quad (\lambda_l^{[M]} \mu_l^{[V]} - \mu_l^{[M]} \lambda_l^{[V]}) = 0.$$

at the same time for the same  $l$ .

The common term is

$$J_l(\lambda r) I_{l+1}(\lambda r) + J_{l+1}(\lambda r) I_l(\lambda r) = 0$$

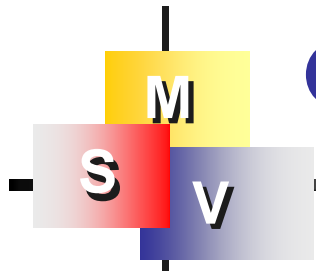
**True eigenequation**



# Outlines

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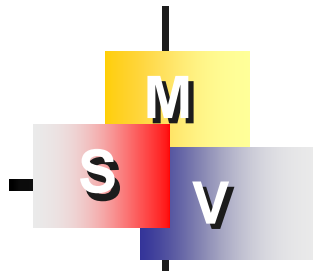
1. Introduction
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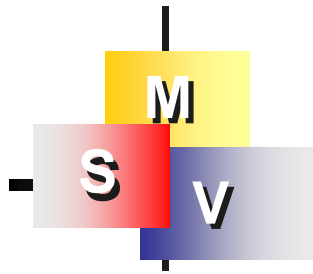
# Conclusions

1. Since any two combinations of the four types of potentials, **six options**( $C_2^4$ ) were considered.
2. **Spurious eigenequation** only depends on the adopted **kernel function**, while the **true eigenequation** is relevant to the specified **boundary condition**.
3. True eigenequation can be extract out by using **SVD updating term**.





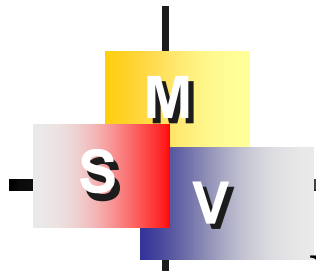
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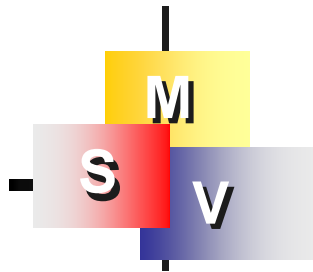
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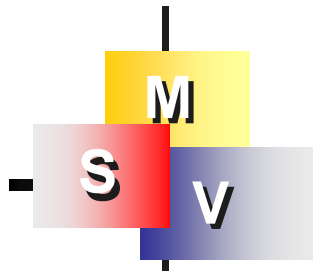
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