

# 第廿六屆力學會議學生論文競賽

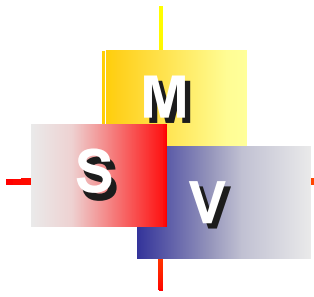
## A new meshless method for free vibration analysis of plates using radial basis function

報 告 人：李應德 先生

指 導 教 授：陳正宗 教授

時 間：2002年12月20日

地 點：國立虎尾技術學院

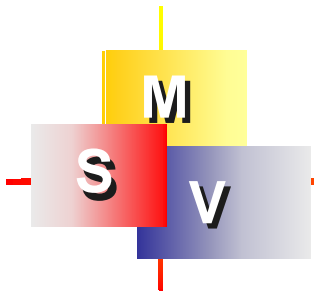


# Outlines

---

1. Introduction
2. Methods of solution
3. Illustrated examples
4. Discussion
5. Conclusions



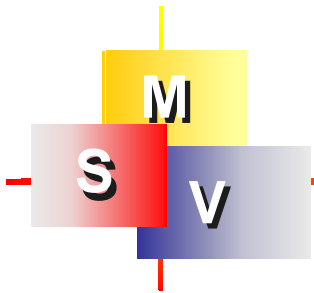


# Outlines

---

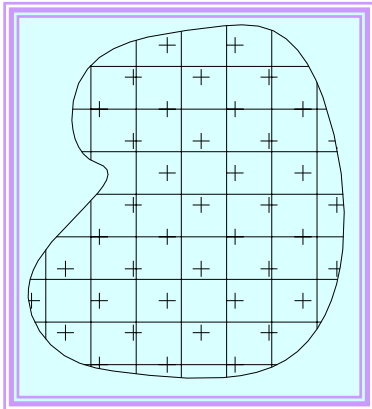
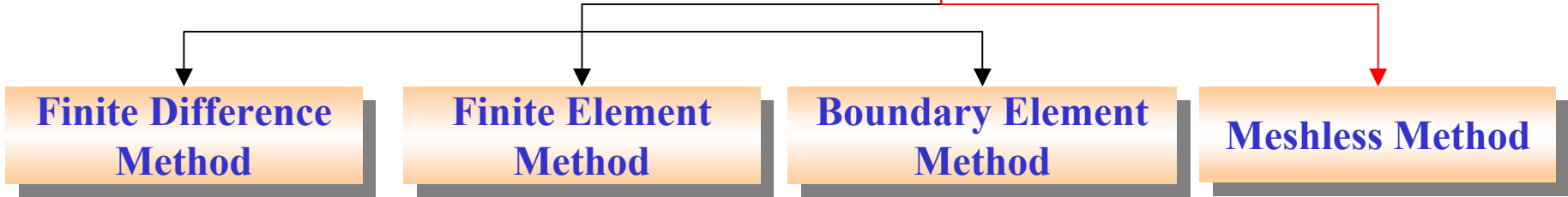
- 1. Introduction**
- 2. Methods of solution**
- 3. Illustrated examples**
- 4. Discussion**
- 5. Conclusions**



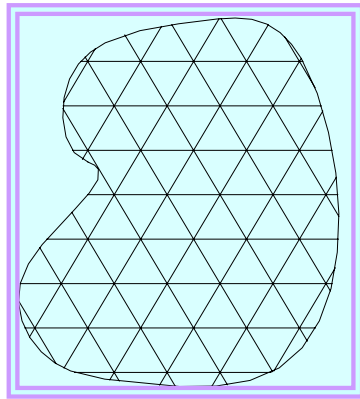


# Methods of solution

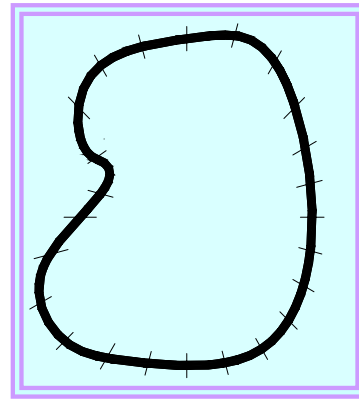
Methods of solution



~~Mesh~~

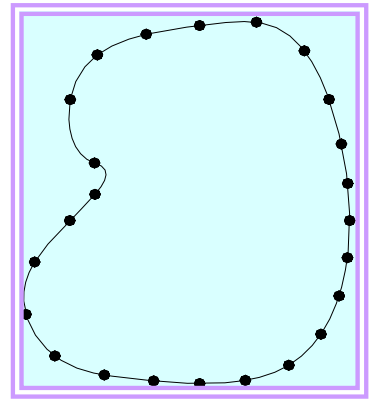


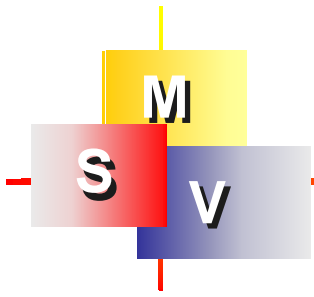
~~Mesh~~



~~Mesh~~

Singular ~~integral~~





# Outlines

---

**1. Introduction**

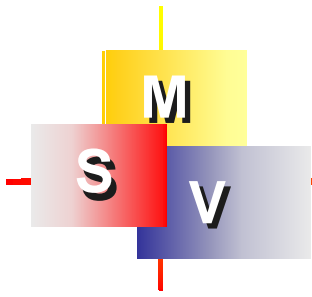
**2. Methods of solution**

**3. Illustrated examples**

**4. Discussion**

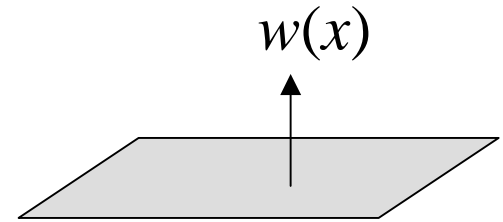
**5. Conclusions**





# Vibration of plates

## Governing Equation:



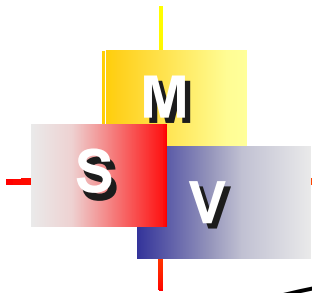
$$\nabla^4 w(x) = \lambda^4 w(x), \quad x \in \Omega$$

$$\lambda^4 = \frac{\omega^2 \rho h}{D}$$

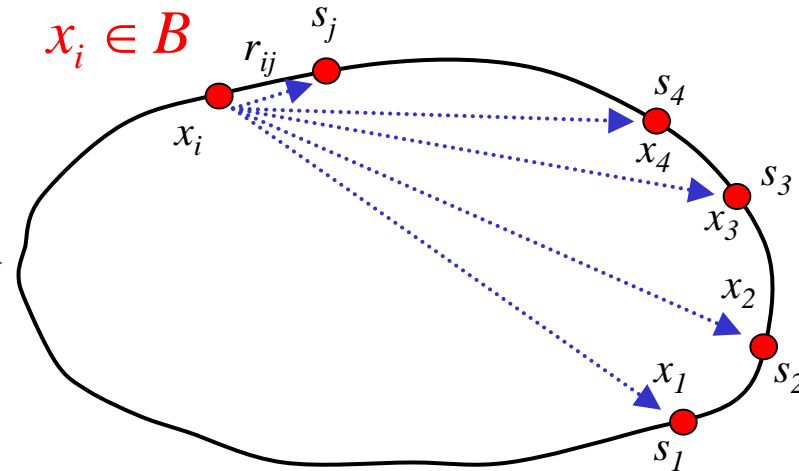
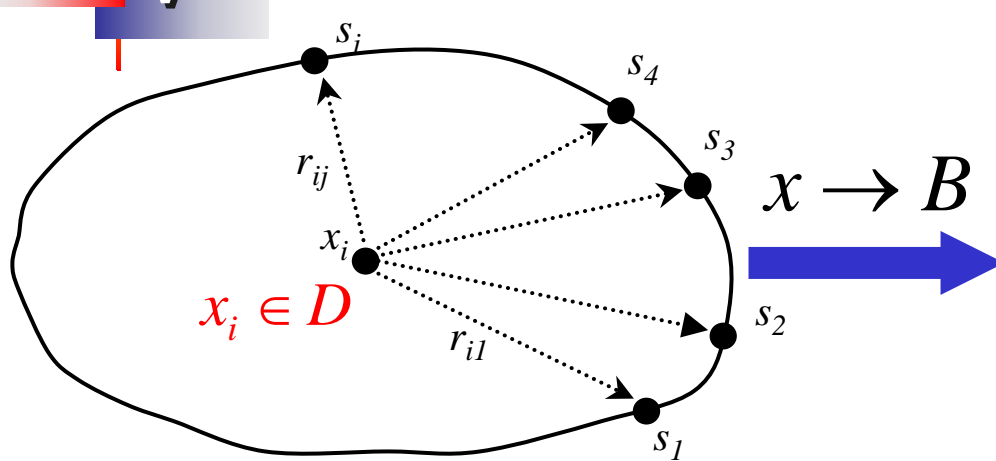
$$D = \frac{E h^3}{12 (1 - \nu)}$$

$\omega$  is the angular frequency  
 $\nabla^4$  is the biharmonic operator  
 $\rho$  is the surface density  
 $h$  is the plate thickness  
 $D$  is the flexural rigidity  
 $E$  is the Young's modulus  
 $\nu$  is the Poisson ratio





# Field representation using RBF



Field representation

To match B.C.

$$u(x_i) = \sum c_j \psi(x_i, s_j)$$

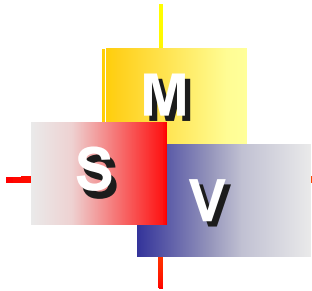
$$\psi(x, s) = \psi(r)$$

$$r \equiv |s - x|$$

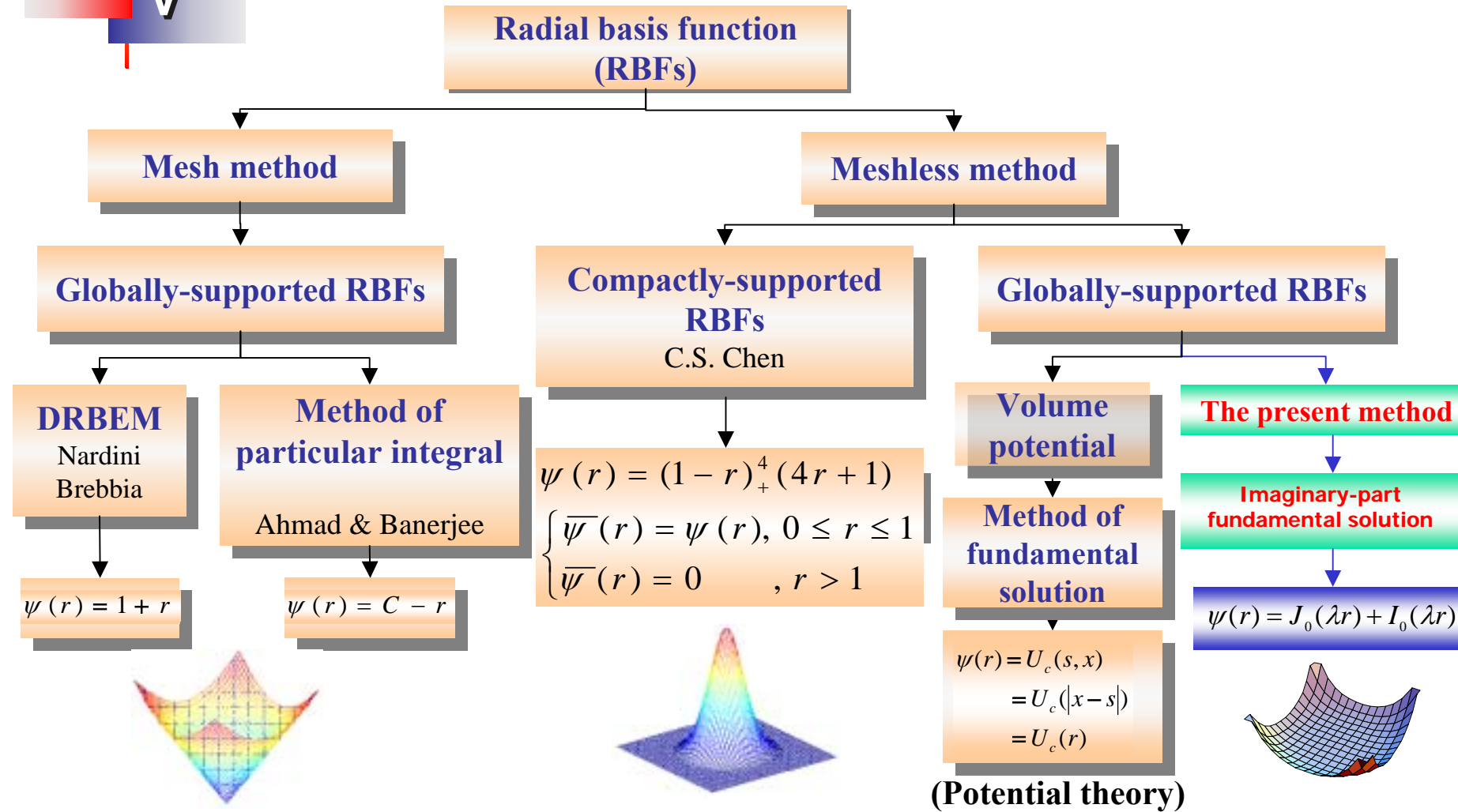
$$\{u\} = \begin{bmatrix} \cdot & * & * & * & * \\ * & \cdot & * & * & * \\ * & * & \cdot & * & * \\ * & * & * & \cdot & * \\ * & * & * & * & \cdot \end{bmatrix} \{c\}$$

$r \neq 0$   
 $r = 0$

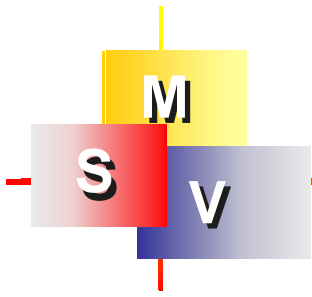




# Data bank of RBF







# Displacement, Slope and Moment

**Displacement**

$$w(x) = \sum_{j=1}^{2N} W(s_j, x) p(s_j) + \sum_{j=1}^{2N} \Theta(s_j, x) q(s_j)$$

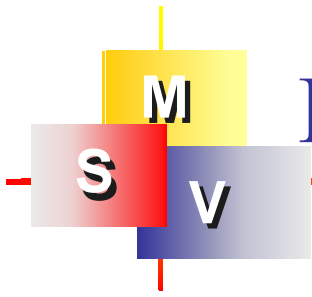
**Slope**

$$\theta(x) = \sum_{j=1}^{2N} W_n(s_j, x) p(s_j) + \sum_{j=1}^{2N} \Theta_n(s_j, x) q(s_j)$$

**Moment**

$$m(x) = \sum_{j=1}^{2N} W_m(s_j, x) p(s_j) + \sum_{j=1}^{2N} \Theta_m(s_j, x) q(s_j)$$



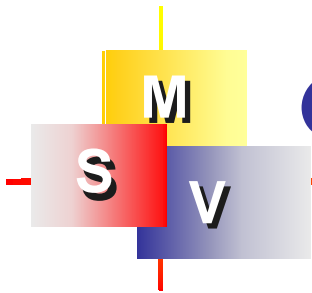


# Imaginary-part fundamental solution

$$W(s, x) = \text{Im} \left\{ \frac{i}{8\lambda^2} (H_0^{(2)}(\lambda r) + H_0^{(1)}(i\lambda r)) \right\}$$

$$W(s, x) = \frac{1}{8\lambda^2} (J_0(\lambda r) + I_0(\lambda r))$$



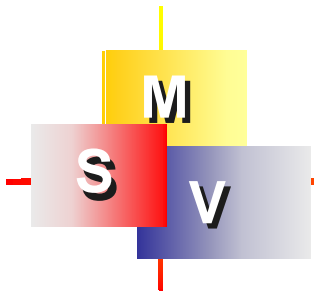


# Constructing the six kernel functions

$$\begin{array}{ccc}
 W(s, x) & \xrightarrow{\quad} & \Theta(s, x) = \frac{\partial W(s, x)}{\partial n_s} \\
 \frac{\partial}{\partial n_x} \downarrow & & \frac{\partial}{\partial n_s} \downarrow \\
 W_n(s, x) = \frac{\partial W(s, x)}{\partial n_x} & \xrightarrow{\quad} & \Theta_n(s, x) = \frac{\partial^2 W(s, x)}{\partial n_s \partial n_x} \\
 \frac{\partial}{\partial n_x} \downarrow & & \frac{\partial}{\partial n_s} \downarrow \\
 W_{nn}(s, x) = \frac{\partial^2 W(s, x)}{\partial n_x \partial n_x} & \xrightarrow{\quad} & \Theta_{nn}(s, x) = \frac{\partial^3 W(s, x)}{\partial n_s (\partial n_x)^2}
 \end{array}$$

$$V \Theta_m(s_j, x) = \Theta_{nn}(s_j, x) + \frac{v}{\rho} \Theta_n(s_j, x)$$



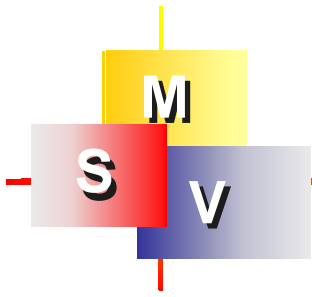


# Outlines

---

1. Introduction
2. Methods of solution
3. Illustrated examples
4. Discussion
5. Conclusions

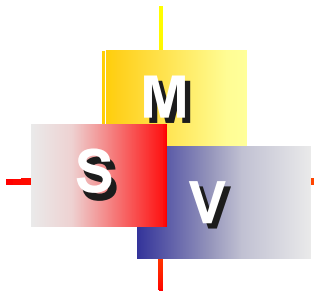




# Two cases

	Clamped plate	Simply-supported plate
Boundary condition	$w(x)=0$ $q(x)=0$	$w(x)=0$ $m(x)=0$
Field representation	$w(x)=[W]\{p\}+[Q]\{q\}$ $q(x)=[W_n]\{p\}+[Q_n]\{q\}$	$w(x)=[W]\{p\}+[Q]\{q\}$ $m(x)=[W_m]\{p\}+[Q_m]\{q\}$
Eigenequation	$J_\ell(\lambda\rho)I_{\ell+1}(\lambda\rho)+I_\ell(\lambda\rho)J_{\ell+1}(\lambda\rho)=0$	$\frac{I_{\ell+1}(\lambda\rho)}{I_\ell(\lambda\rho)} + \frac{J_{\ell+1}(\lambda\rho)}{J_\ell(\lambda\rho)} = \frac{2\lambda\rho}{(1-\nu)}$



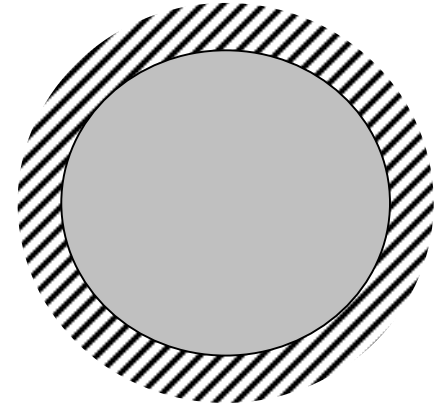


# Clamped plate

$$w(x) = 0 \implies [W]\{p\} + [\Theta]\{q\} = \{0\}$$

$$\theta(x) = 0 \implies [W_n]\{p\} + [\Theta_n]\{q\} = \{0\}$$

$$x \in B$$



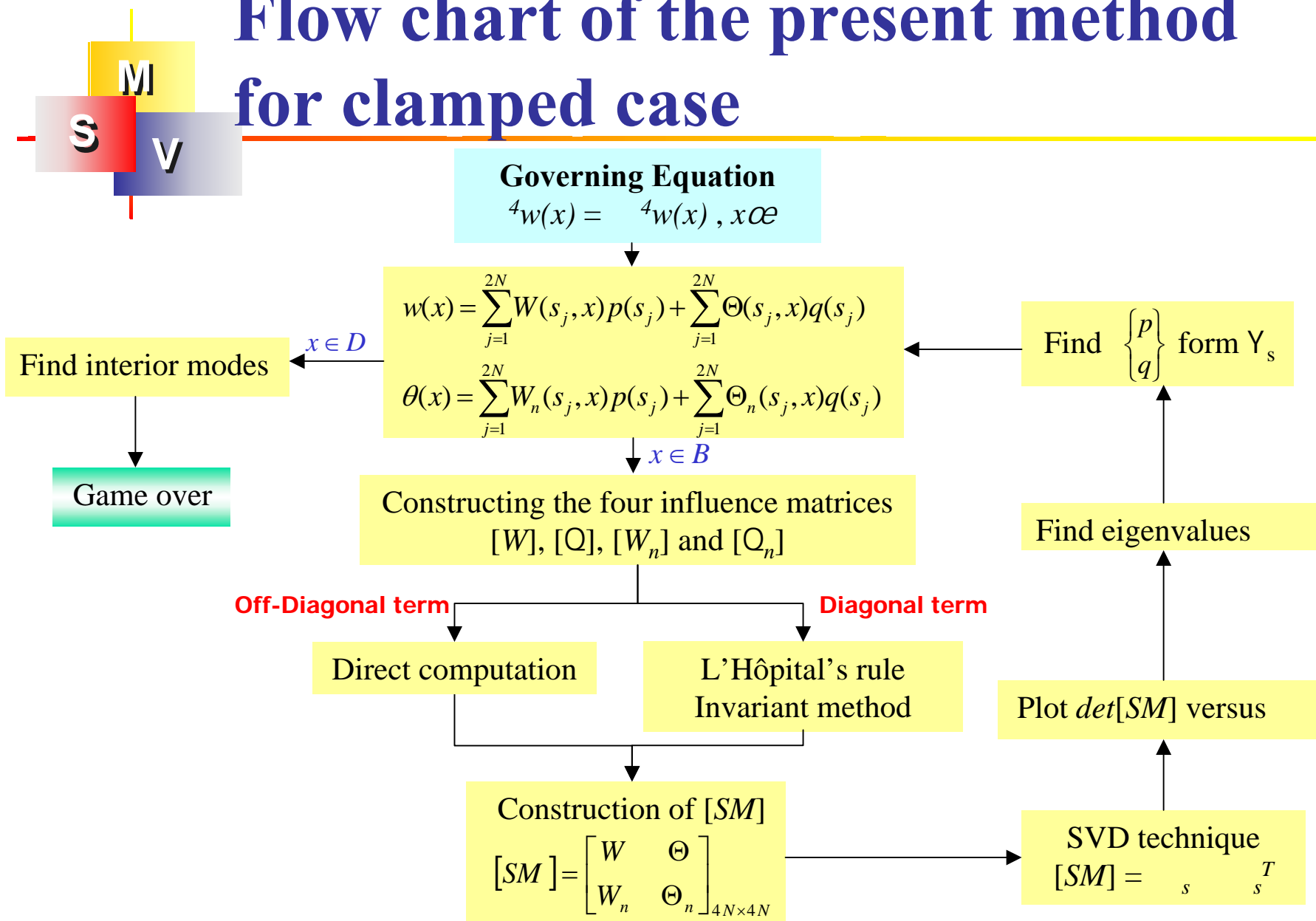
**Nontrivial**

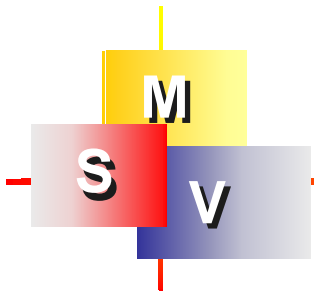
$$\det[SM] = 0$$

$$\begin{bmatrix} W & \Theta \\ W_n & \Theta_n \end{bmatrix} \begin{Bmatrix} p \\ q \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$



# Flow chart of the present method for clamped case





# Simply-supported plate

$$w(x) = 0 \implies [W]\{p\} + [\Theta]\{q\} = \{0\}$$

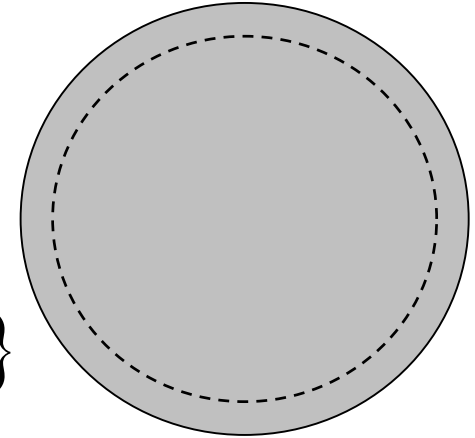
$$m(x) = 0 \implies [W_m]\{p\} + [\Theta_m]\{q\} = \{0\}$$

$$x \in B$$

$$\det[SM] = 0$$

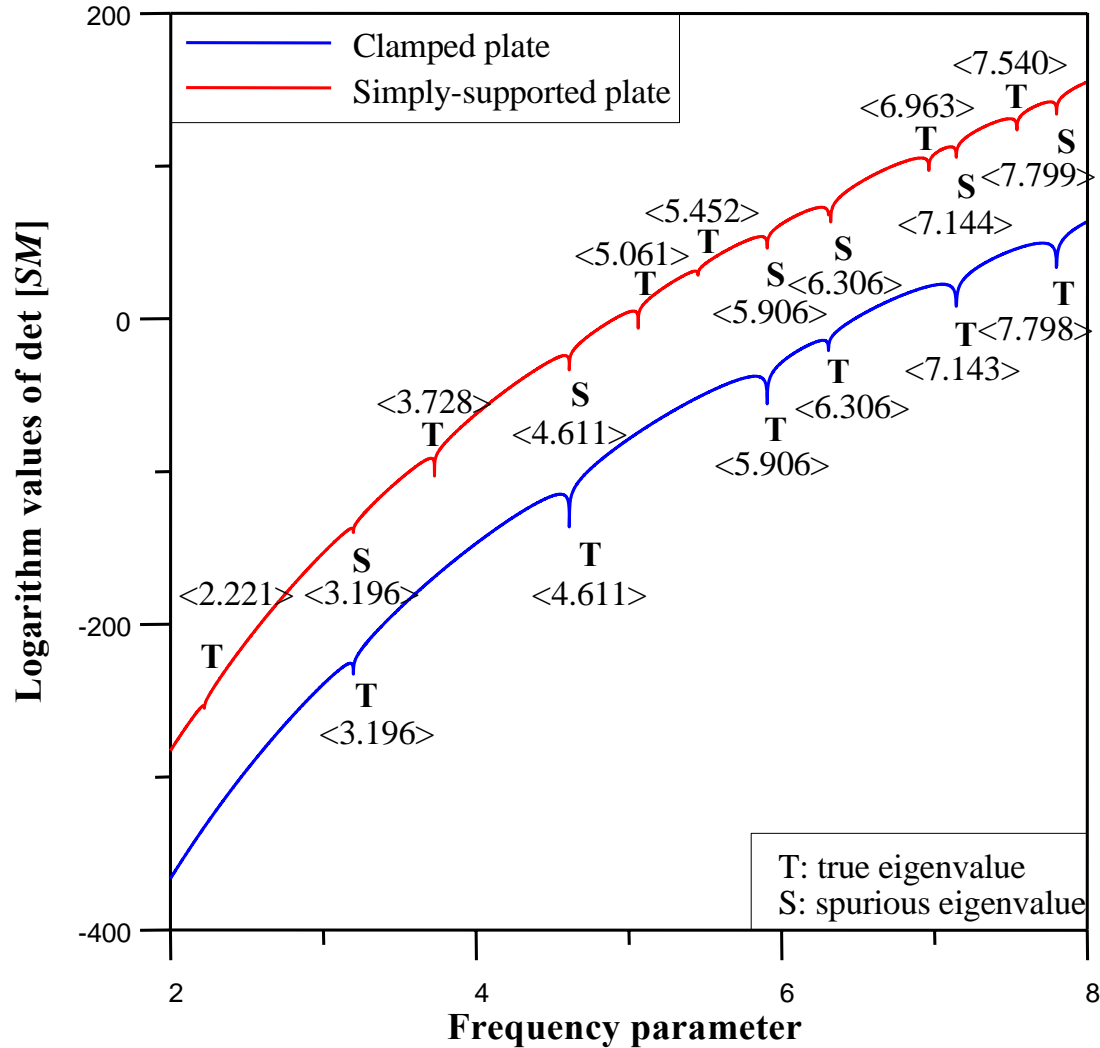
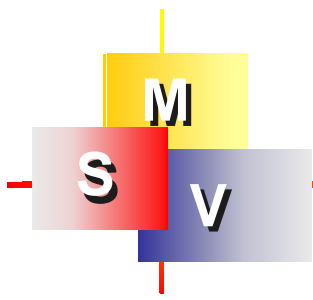
$$\begin{bmatrix} W & \Theta \\ W_m & \Theta_m \end{bmatrix} \begin{Bmatrix} p \\ q \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

Nontrivial

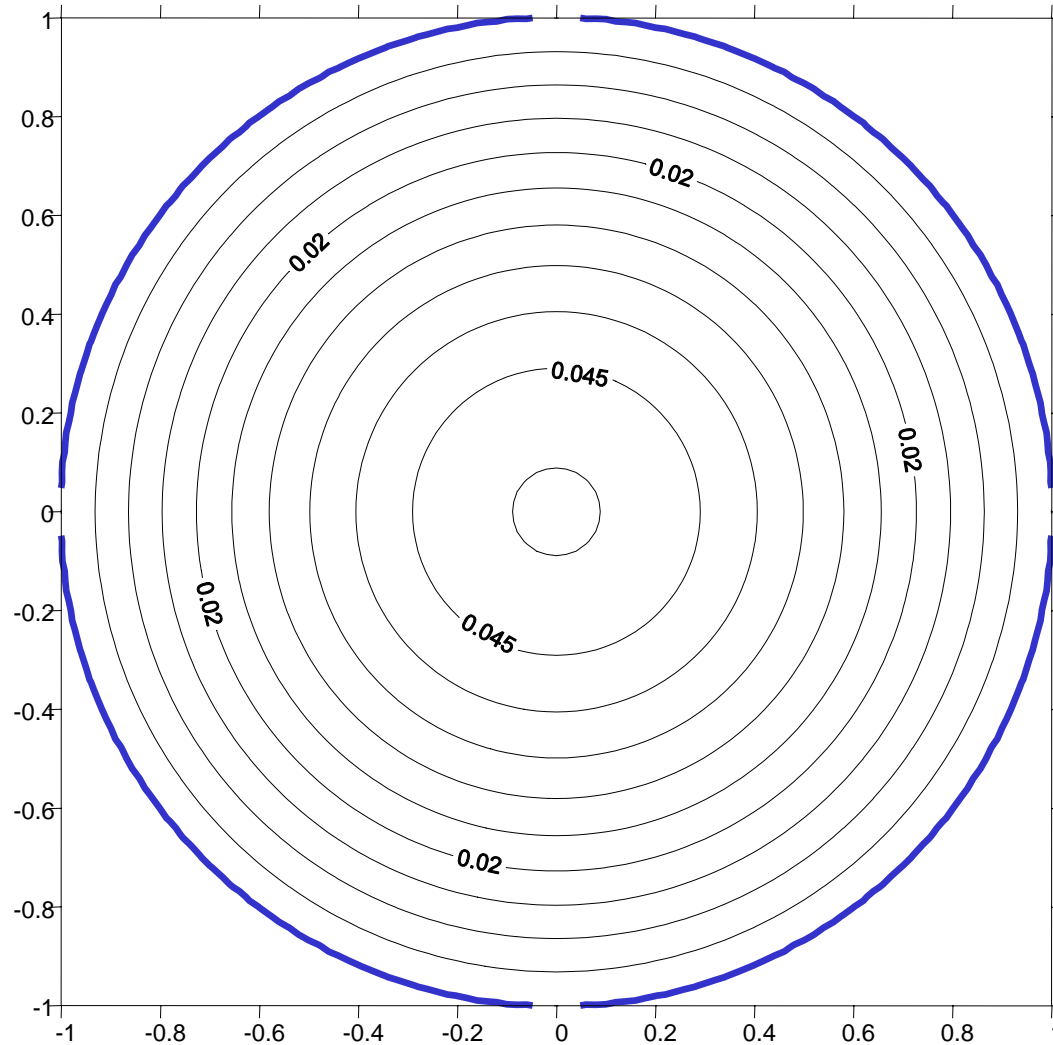
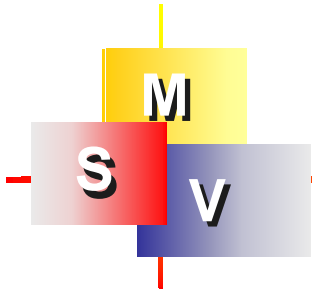




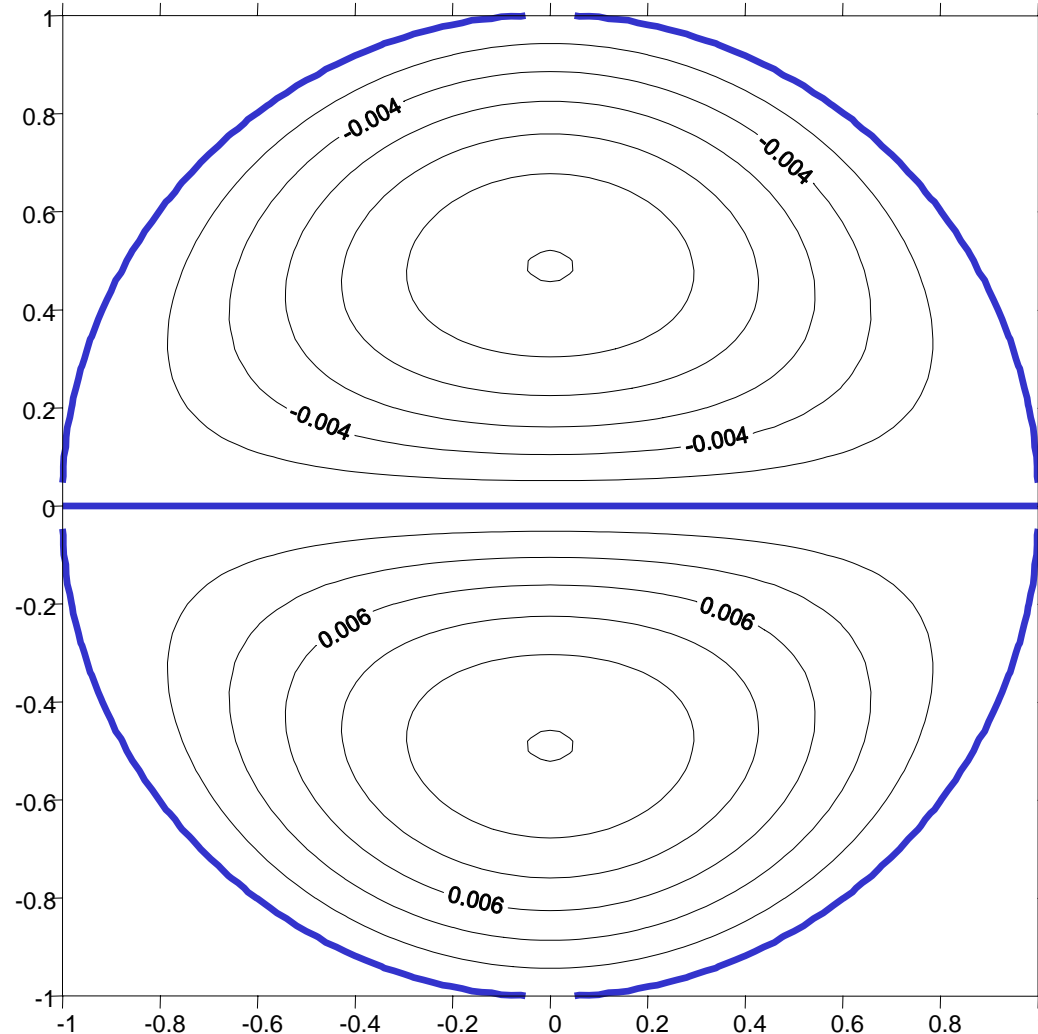
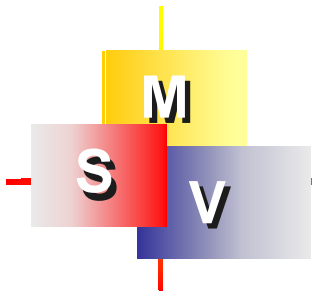
# Circular clamped and simply-supported plate using the present methods



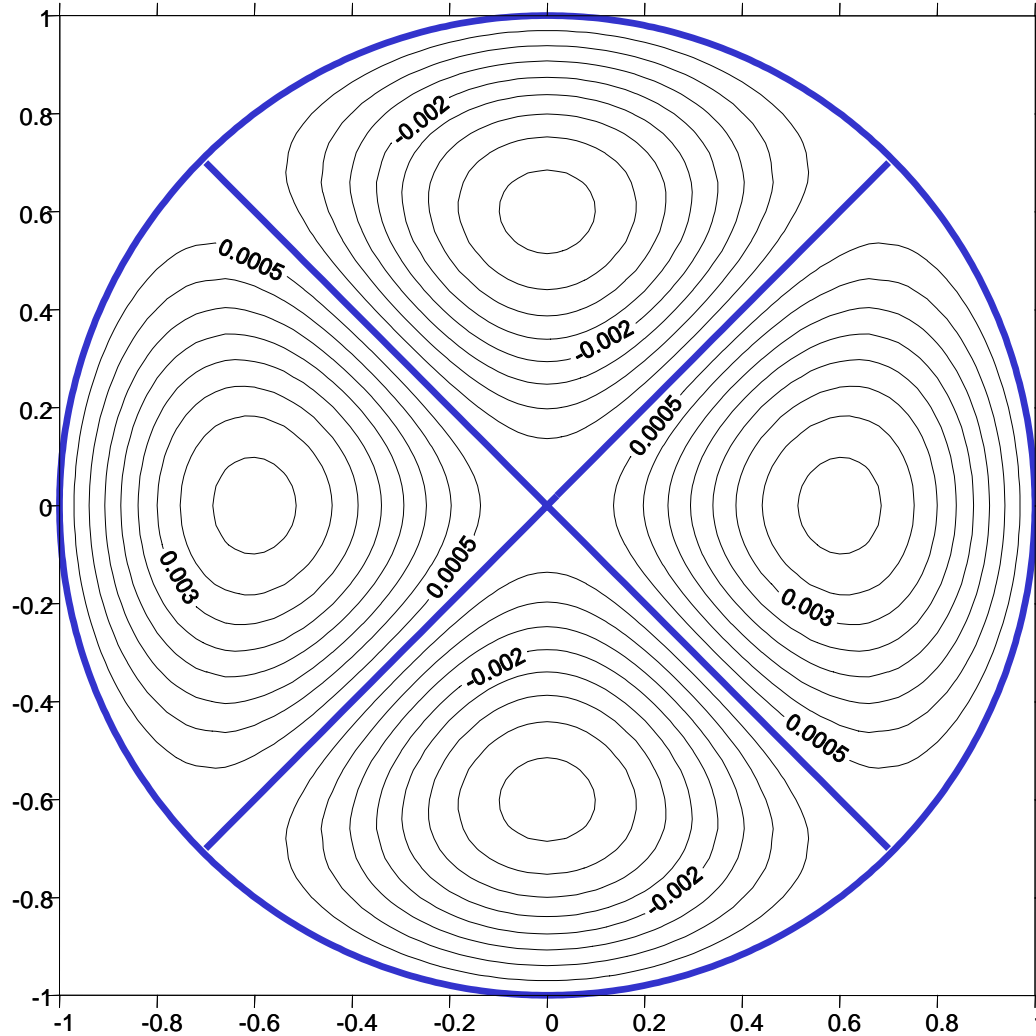
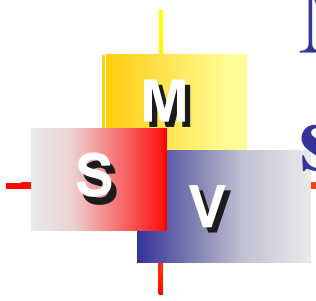
# Mode 1 ( $\lambda = 2.221$ ) for simply-supported plate

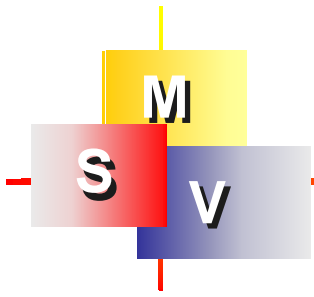


# Mode 2 ( $\lambda = 3.728$ ) for simply-supported plate



# Mode 2 ( $\lambda = 5.061$ ) for simply-supported plate





# Outlines

---

1. Introduction
2. Methods of solution
3. Illustrated examples
4. Discussion
5. Conclusions



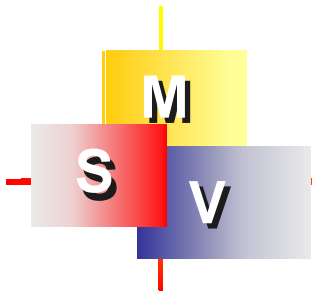
# Circulants

Discretization into  $2N$  nodes on the circular boundary

$$[W] = \begin{bmatrix} a_0 & a_1 & a_2 & \cdots & a_{2N-2} & a_{2N-1} \\ a_{2N-1} & a_0 & a_1 & \cdots & a_{2N-3} & a_{2N-2} \\ a_{2N-2} & a_{2N-1} & a_0 & \cdots & a_{2N-4} & a_{2N-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ a_2 & a_3 & a_4 & \cdots & a_0 & a_1 \\ a_1 & a_2 & a_3 & \cdots & a_{2N-1} & a_0 \end{bmatrix}$$

$$\lambda_\ell = a_0 + a_1 \alpha_\ell + a_2 \alpha_\ell^2 + \cdots + a_{2N-1} \alpha_\ell^{2N-1}$$

$$\ell = 0, \pm 1, \pm 2, \cdots, \pm (N-1), N \quad : \text{eigenvalue of } [W]$$

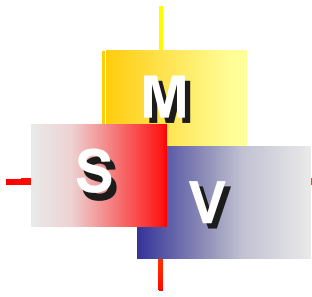


# Circulants

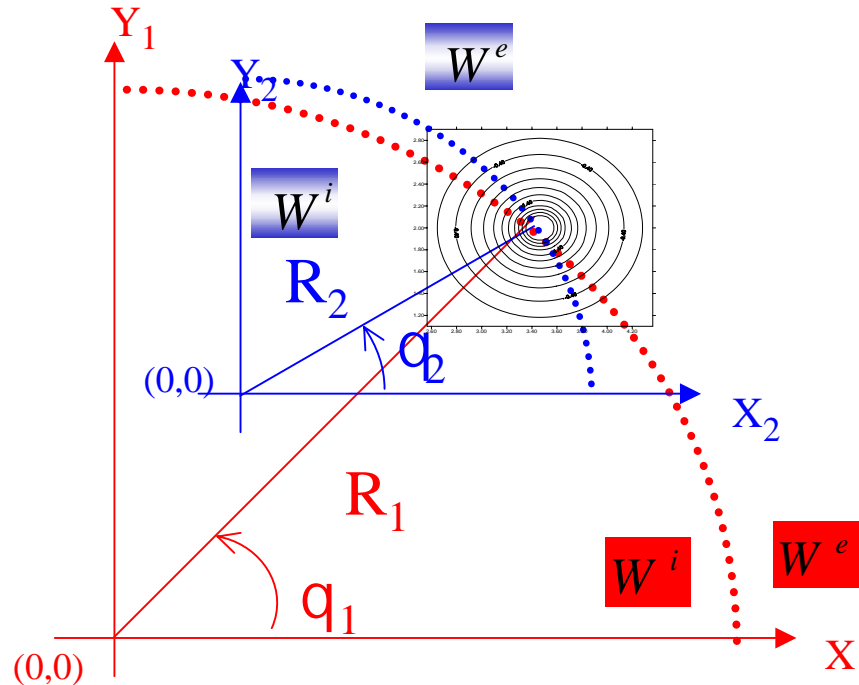
$$C_{2N} = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & 1 \\ 1 & 0 & 0 & \cdots & 0 & 0 \end{bmatrix}_{2N \times 2N}$$

$$\alpha_\ell = e^{i\frac{2\pi\ell}{2N}} = \cos\left(\frac{2\pi\ell}{2N}\right) + i \sin\left(\frac{2\pi\ell}{2N}\right) : \text{eigenvalue of } C_{2N}$$





# Degenerate kernels for circular case



$$W(s, x) = \begin{cases} W^I(R, \theta; \rho, \phi) = \frac{1}{8\lambda^2} \sum_{m=-\infty}^{\infty} [J_m(\lambda R)J_m(\lambda \rho) + (-1)^m I_m(\lambda R)I_m(\lambda \rho)](\cos(m(\theta - \phi))), & R > \rho \\ W^E(R, \theta; \rho, \phi) = \frac{1}{8\lambda^2} \sum_{m=-\infty}^{\infty} [J_m(\lambda \rho)J_m(\lambda R) + (-1)^m I_m(\lambda \rho)I_m(\lambda R)](\cos(m(\theta - \phi))), & R < \rho \end{cases}$$





M

S

V

# Eigenvalues of influence matrices

$$\lambda_\ell = \frac{N}{4\lambda^2} [J_\ell(\lambda\rho)J_\ell(\lambda\rho) + (-1)^\ell I_\ell(\lambda\rho)I_\ell(\lambda\rho)]$$

$$\mu_\ell = \frac{N}{4\lambda} [J_\ell(\lambda\rho)J'_\ell(\lambda\rho) + (-1)^\ell I_\ell(\lambda\rho)I'_\ell(\lambda\rho)]$$

$$\nu_\ell = \frac{N}{4\lambda} [J'_\ell(\lambda\rho)J_\ell(\lambda\rho) + (-1)^\ell I'_\ell(\lambda\rho)I_\ell(\lambda\rho)]$$

$$\delta_\ell = \frac{N}{4} [J'_\ell(\lambda\rho)J_\ell(\lambda\rho) + (-1)^\ell I'_\ell(\lambda\rho)I_\ell(\lambda\rho)]$$



M

S

V

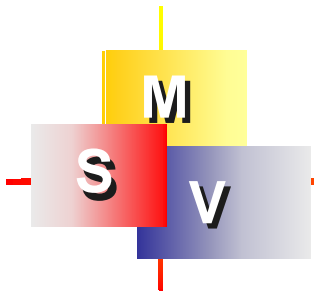
# The eigenvalues of matrices

$$[W] = \Phi \Sigma_W \Phi^T$$

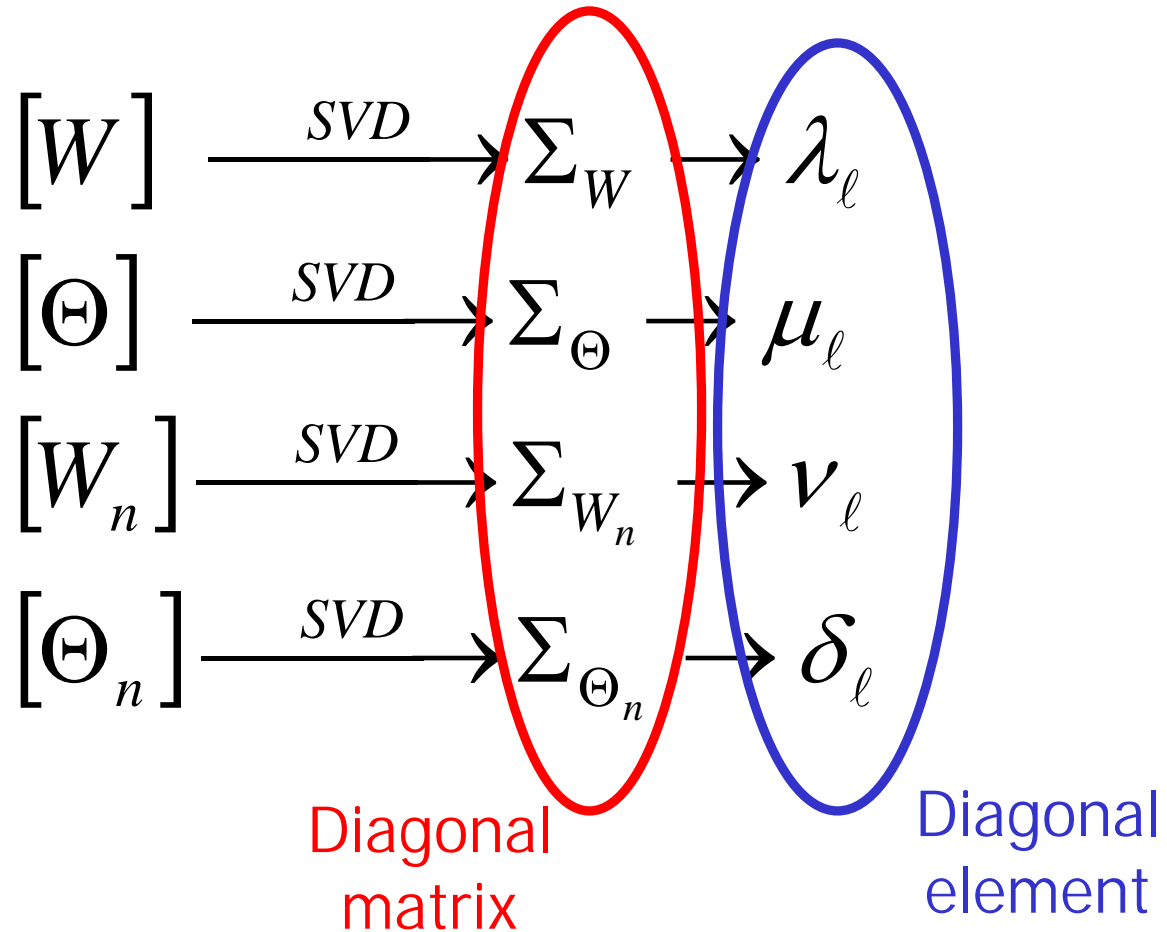
$$= \Phi \begin{bmatrix} \lambda_0 & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & \lambda_1 & 0 & \cdots & 0 & 0 & 0 \\ 0 & 0 & \lambda_{-1} & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda_{(N-1)} & 0 & 0 \\ 0 & 0 & 0 & \cdots & 0 & \lambda_{-(N-1)} & 0 \\ 0 & 0 & 0 & \cdots & 0 & 0 & \lambda_N \end{bmatrix} \Phi^T$$

$_{2N \times 2N}$





# Singular value of influence matrices



M

S

V

# Determinant for clamped plate

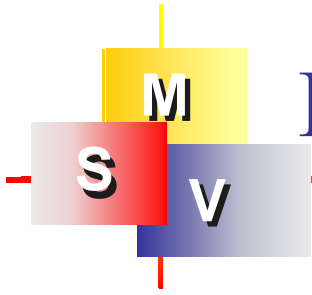
$$[SM] = \begin{bmatrix} \Phi \Sigma_W \Phi^T & \Phi \Sigma_{\Theta} \Phi^T \\ \Phi \Sigma_{W_n} \Phi^T & \Phi \Sigma_{\Theta_n} \Phi^T \end{bmatrix}_{4N \times 4N}$$

$$= \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_W & \Sigma_{\Theta} \\ \Sigma_{W_n} & \Sigma_{\Theta_n} \end{bmatrix} \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix}^T$$

$$\det[SM] = \sigma_0 (\sigma_1 \sigma_2 \cdots \sigma_{N-1})^2 \sigma_N = 0$$

$$\sigma_l = \lambda_l \delta_l - \mu_l \nu_l$$





# Eigenequation for clamped boundary

$$\sigma_l = \lambda_l \delta_l - \mu_l \nu_l$$

$$= \frac{N \left[ J_l(\lambda\rho) I_{l+1}(\lambda\rho) + I_l(\lambda\rho) J_{l+1}(\lambda\rho) \right]^2}{4 J_l(\lambda\rho) J_l(\lambda\rho) - (-1)^l I_l(\lambda\rho) I_l(\lambda\rho)}$$
$$= 0, \quad l = 0, \pm 1, \pm 2, \dots, \pm(N-1), N$$

$$J_l(\lambda\rho) I_{l+1}(\lambda\rho) + I_l(\lambda\rho) J_{l+1}(\lambda\rho) = 0$$

Exact eigensolution



M

S

V

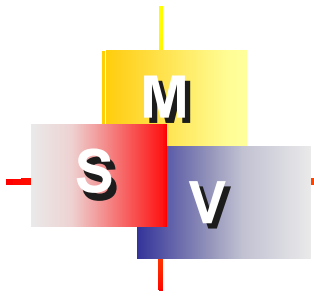
# Determinant for simply-supported plate

$$[SM] = \begin{bmatrix} \Phi \Sigma_w \Phi^T & \Phi \Sigma_{\Theta} \Phi^T \\ \Phi \Sigma_{w_m} \Phi^T & \Phi \Sigma_{\Theta_m} \Phi^T \end{bmatrix}_{4N \times 4N}$$

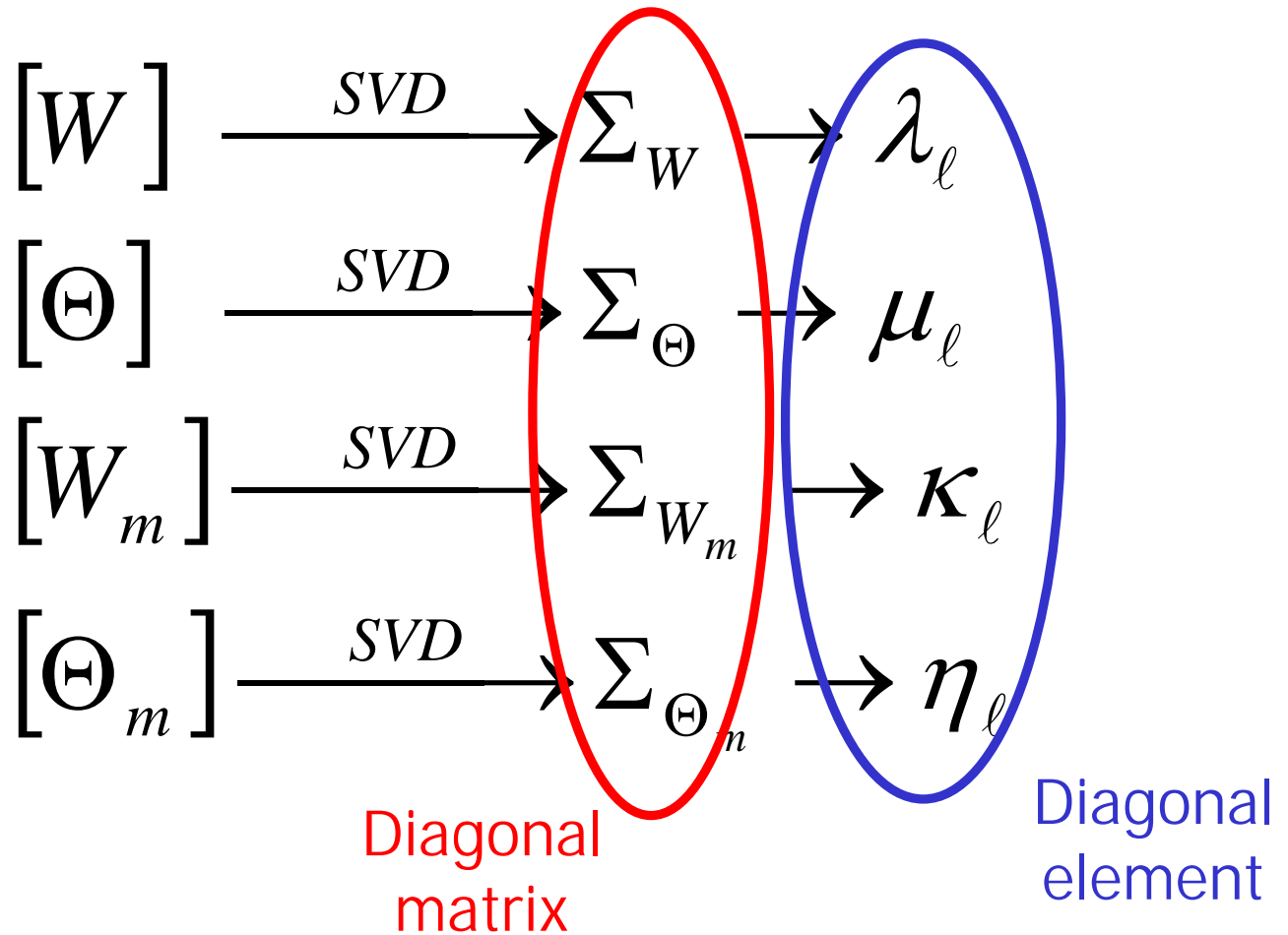
$$= \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix} \begin{bmatrix} \Sigma_w & \Sigma_{\Theta} \\ \Sigma_{w_m} & \Sigma_{\Theta_m} \end{bmatrix} \begin{bmatrix} \Phi & 0 \\ 0 & \Phi \end{bmatrix}^T$$

$$\det[SM] = \sigma_0 (\sigma_1 \sigma_2 \cdots \sigma_{N-1})^2 \sigma_N = 0$$

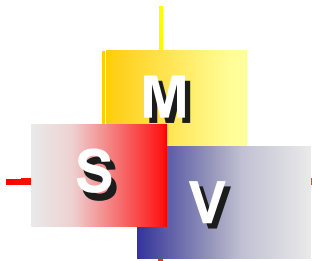




# Singular value of influence matrices



# Eigenequation for simply-supported boundary



$$\sigma_l = \lambda_l \eta_l - \mu_l \kappa_l$$

Exact eigenequation of clamped plates

$$\Rightarrow (J_l(\lambda\rho)I_{l+1}(\lambda\rho) + I_l(\lambda\rho)J_{l+1}(\lambda\rho))$$

$$\times \left( \frac{I_{l+1}(\lambda\rho)}{I_l(\lambda\rho)} + \frac{J_{l+1}(\lambda\rho)}{J_l(\lambda\rho)} - \frac{2\lambda\rho}{(1-\nu)} \right) = 0$$

Spurious

True

$$l = 0, \pm 1, \pm 2, \dots, \pm (N-1), N$$

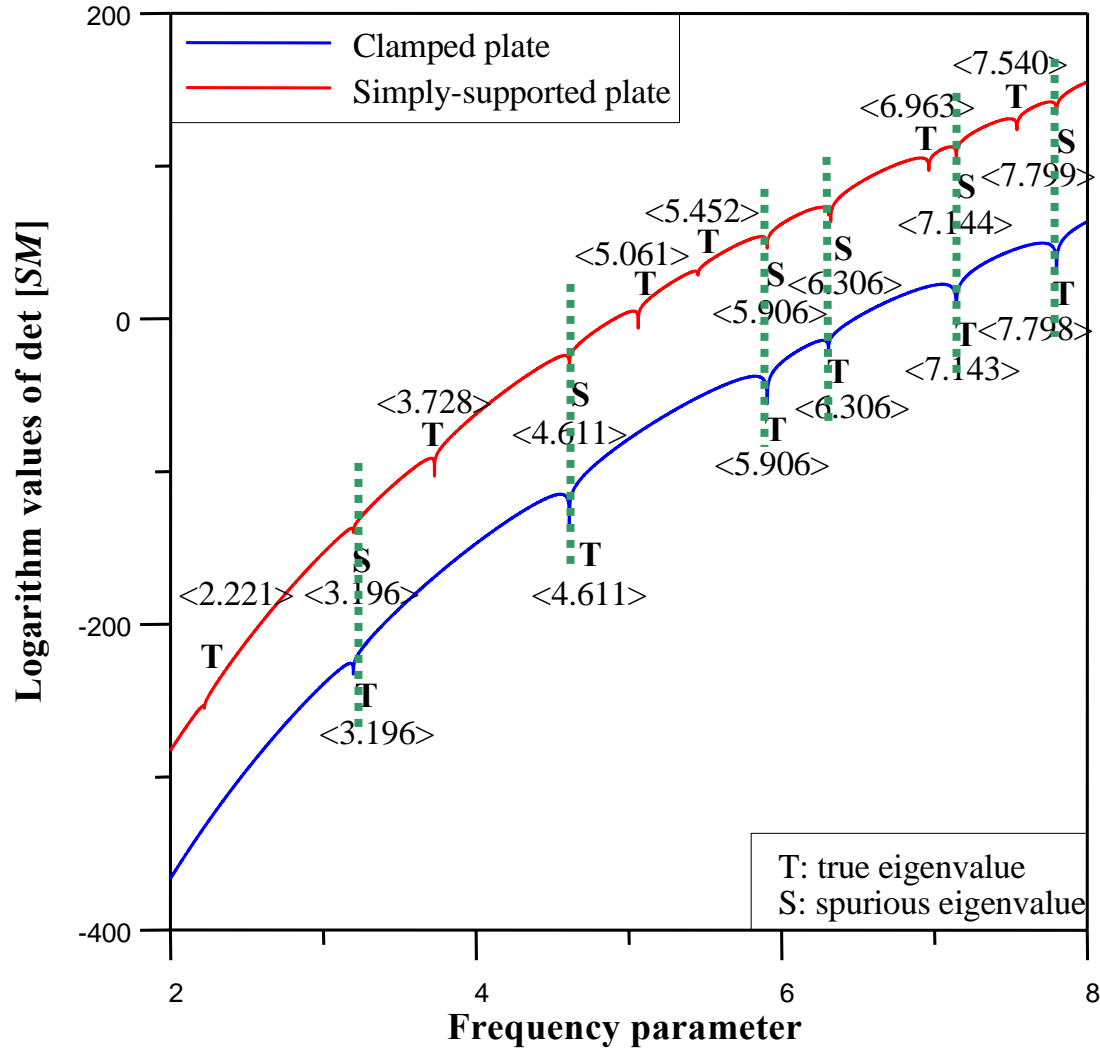
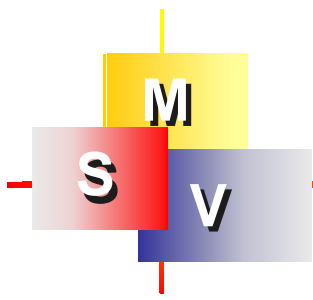
$$\frac{I_{l+1}(\lambda\rho)}{I_l(\lambda\rho)} + \frac{J_{l+1}(\lambda\rho)}{J_l(\lambda\rho)} = \frac{2\lambda\rho}{(1-\nu)}$$

Exact eigenequation of simply-supported plate





# Circular clamped and simply-supported plate using the present method



M

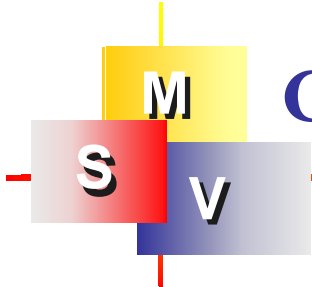
S

V

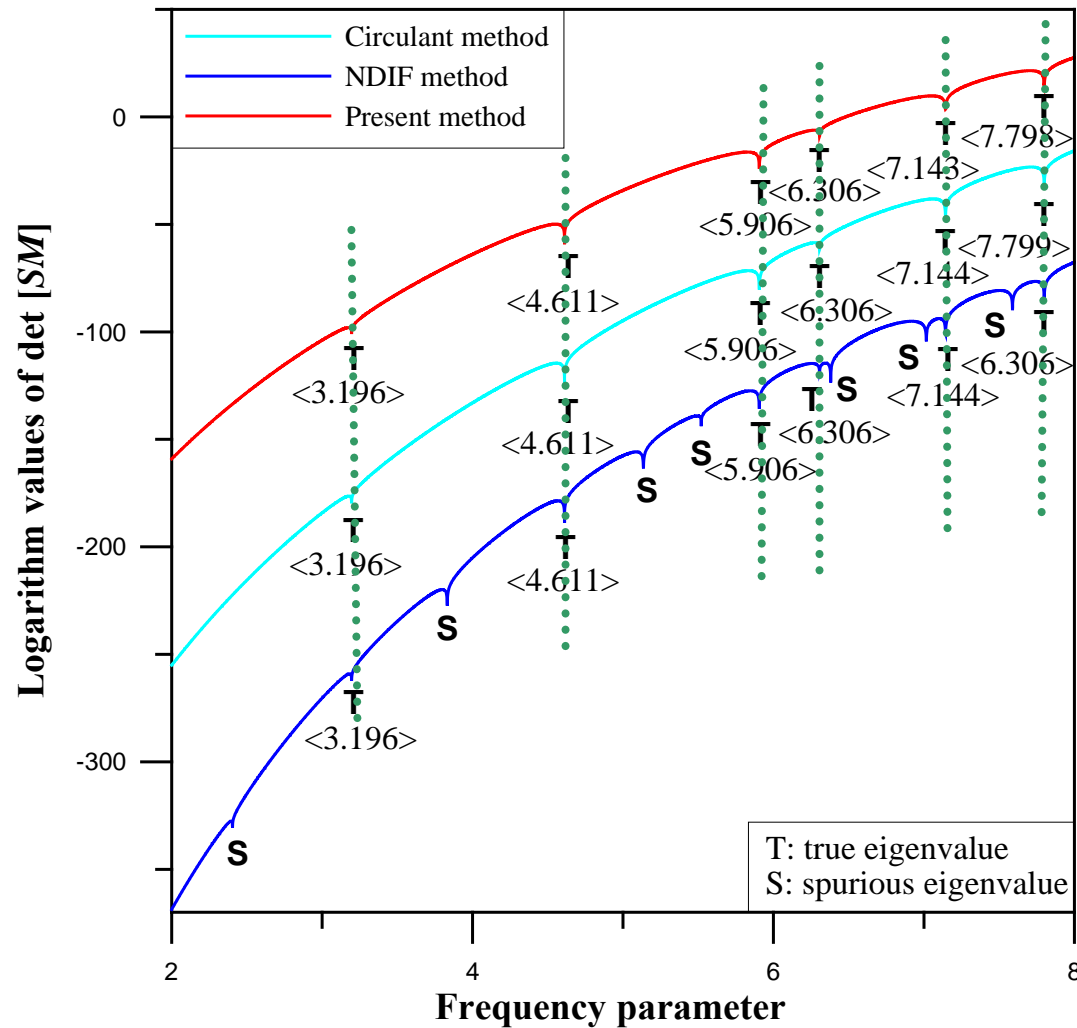
# Comparisons of the NDIF and present method

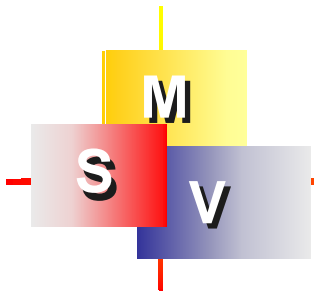
	<b>Kang</b>	<b>Present method</b>
<b>RBF</b>	$W(s, x) = J_0(\lambda r)$ $\Theta(s, x) = I_0(\lambda r)$	$W(s, x) = \frac{1}{8\lambda^2}(J_0(\lambda r) + I_0(\lambda r))$ $\Theta(s, x) = \frac{\partial W(s, x)}{\partial n_s}$
<b>Clamped plate</b>	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
	$J_\ell(\lambda r) = 0$	<b>No</b>
<b>Simply-supported plate</b>	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$	$\frac{I_{\ell+1}(\lambda r)}{I_\ell(\lambda r)} + \frac{J_{\ell+1}(\lambda r)}{J_\ell(\lambda r)} = \frac{2\lambda r}{(1-\nu)}$
	$J_\ell(\lambda r) = 0$	$J_\ell(\lambda r)I_{\ell+1}(\lambda r) + J_{\ell+1}(\lambda r)I_\ell(\lambda r) = 0$
<b>Treatment</b>	<b>Net approach</b>	<b>CHEEF method</b> <b>Dual formulation with SVD updating</b>





# Circular clamped plate using different methods





# Outlines

---

1. Introduction
2. Methods of solution
3. Illustrated examples
4. Discussion
5. Conclusions





M

S

V

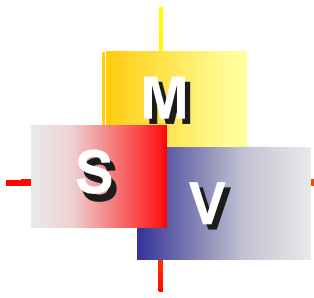
# Conclusions

---

1. Field solution can be **superimposed** by using the **two-point function (RBF)**.
2. **Diagonal terms** in the influence matrices can be derived by **L'Hôpital's rule** or **invariant method**.
3. The eigensolutions for clamped plate **can be easily determined** using our approach.
4. The eigensolution of **simply-supported problem** is contaminated by the true eigensolution of **clamped problem**.



1. J. T. Chen, S. R. Kuo, K. H. Chen and Y. C. Cheng, 2000, Comments on “Vibration analysis of arbitrary shaped membranes using non-dimensional dynamic influence function”, Journal of Sound and Vibration, Vol.235, No.1, pp.156-171 (SCI and EI)
2. J. T. Chen, M. H. Chang, K. H. Chen and S. R. Lin, 2002, Boundary collocation method with meshless concept for acoustic eigenanalysis of two-dimensional cavities using radial basis function, Journal of Sound and Vibration, Vol.257, No.4, pp.667-711 (SCI and EI)
3. J. T. Chen, M. H. Chang, I. L. Chung and Y. C. Cheng, 2002, Comments on “Eigenmode analysis of arbitrarily shaped two-dimensional cavities by the method of point matching”, J. Acoust. Soc. Amer., Vol.111, No.1, pp.33-36. (SCI and EI)
4. J. T. Chen, M. H. Chang, K. H. Chen, I. L. Chen, 2002, Boundary collocation method for acoustic eigenanalysis of three-dimensional cavities using radial basis function, Computational Mechanics, Vol.29, pp.392-408. (SCI and EI)
5. J. T. Chen, I. L. Chen, K. H. Chen and Y. T. Lee, 2002, Comments on “Free vibration analysis of arbitrarily shaped plates with clamped edges using wave-type function.”, Journal of Sound and Vibration, Accepted. (SCI and EI)
6. J. T. Chen, I. L. Chen, K. H. Chen, Y. T. Yeh and Y. T. Lee, 2002, A meshless method for free vibration analysis of arbitrarily shaped plates with clamped boundaries using radial basis function, Engineering Analysis with Boundary Elements, Accepted. (SCI and EI)

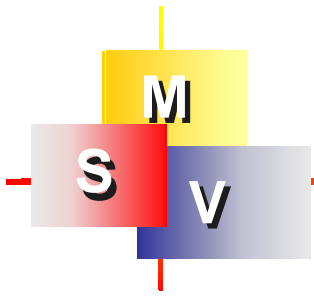


# 歡迎參觀海洋大學力學聲響振動實驗室 烘焙雞及捎來伊妹兒

<http://ind.ntou.edu.tw/~msvlab/>

**E-mail: M91520022@mail.ntou.edu.tw**





# The End

## Thanks for your kind attention

