

Derivation of the Green's function for Laplace and Helmholtz problems with circular boundaries by using the null-field integral equation approach

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Committee members :

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Outlines

- **Motivation and literature review**

- **Derivation of the Green's function**

- Expansions of fundamental solution and boundary density
- Adaptive observer system
- Vector decomposition technique
- Linear algebraic equation
- Take free body
- Image technique for solving half-plane problems

- **Numerical examples**

- Green's function for Laplace problems
- Green's function for Helmholtz problems

- **Conclusions**





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Motivation

Numerical methods for engineering problems

FDM / FEM / BEM / BIEM / Meshless method

BEM / BIEM

Treatment of
singularity and
hypersingularity

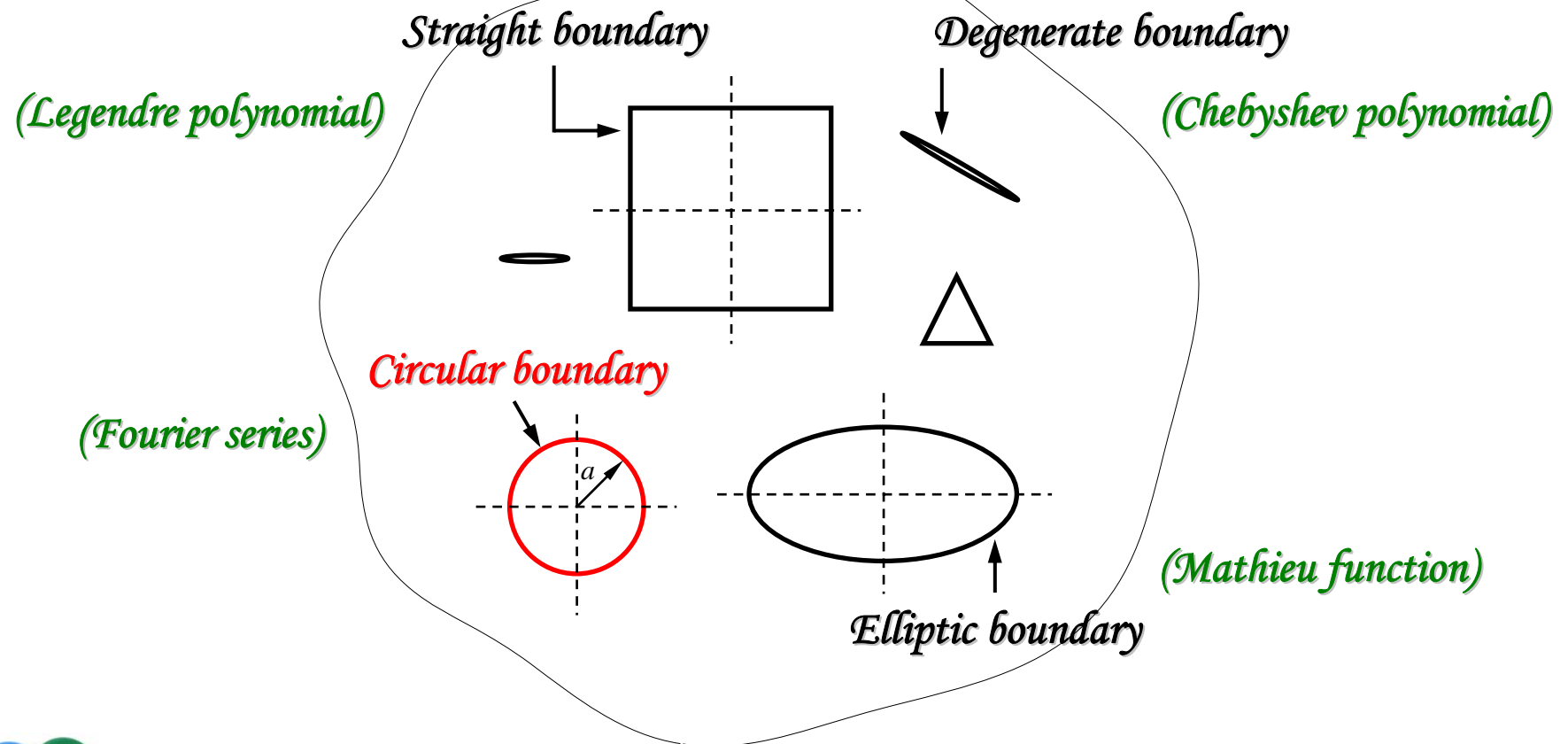
Boundary-layer
effect

Convergence
rate

Ill-posed model



Engineering problem with arbitrary geometries





Literature review

Derivation of the Green's function

Successive iteration method

Boley, 1956, “*A method for the construction of Green's functions*,”
Quarterly of Applied Mathematics

Modified potential method

Melnikov, 2001, “*Modified potential as a tool for computing Green's functions in continuum mechanics*,”
Computer Modeling in Engineering Science

Trefftz bases

Wang and Sudak, 2007, “*Antiplane time-harmonic Green's functions for a circular inhomogeneity with an imperfect interface*,” *Mechanics Research Communications*





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- **Numerical examples**

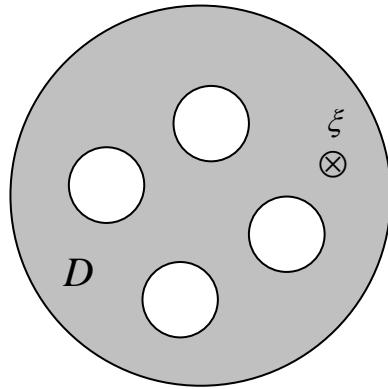
- Green's function for Laplace problems
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Null-field integral approach to construct the Green's function

Original Problem



Governing equation: $\nabla^2 G(x, \xi) = \delta(x - \xi), x \in D$

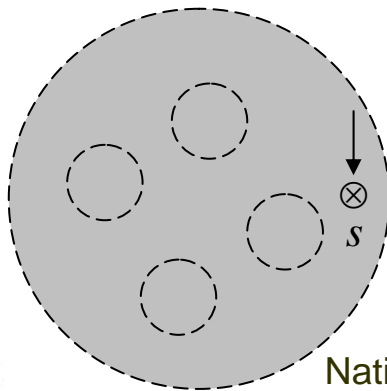
Boundary condition: Subjected to given B. C.

Green's third identity

BIE for Green's function

$$\begin{aligned} \iint_D [u(x) \nabla^2 v(x) - v(x) \nabla^2 u(x)] dD(x) &= 2\pi G(x, \xi) = \int_B \frac{\partial U(s, x)}{\partial n_s} G(s, \xi) dB(s) \\ &= \int_B [(u(x) \frac{\partial v(x)}{\partial n} - v(x) \frac{\partial u(x)}{\partial n})] dB(x) & - \int_B U(s, x) \frac{\partial G(s, \xi)}{\partial n_s} dB(s) + U(\xi, x) \end{aligned}$$

Auxiliary system



Governing equation: $\nabla^2 U(x, s) = 2\pi \delta(x - s)$

$v(x) = U(s, x)$ Fundamental solution

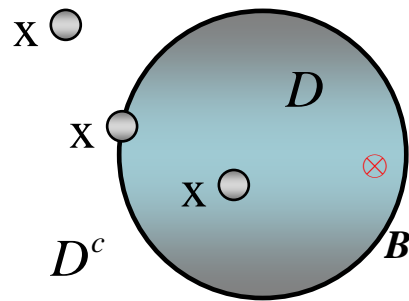
$u(x) = G(x, \xi)$



National Taiwan Ocean University
Department of Harbor and River Engineering

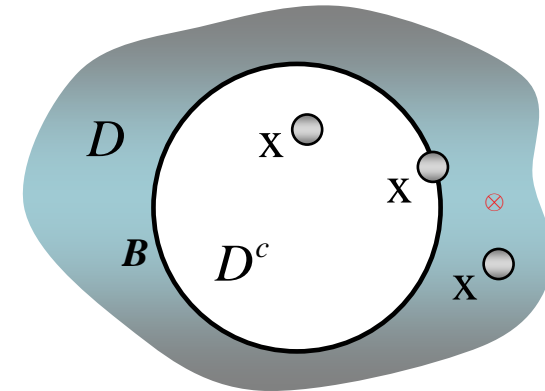
Boundary integral equation and null-field integral equation

Interior case



$$T(s, x) = \frac{\partial U(s, x)}{\partial n_s}$$

Exterior case



$$2\pi G(x, \xi) = \int_B T(s, x) G(s, \xi) dB(s) - \int_B U(s, x) \frac{\partial G(s, \xi)}{\partial n_s} dB(s) + U(\xi, x), \quad x \in D \cup B$$

$$\pi G(x, \xi) = C.P.V. \int_B T(s, x) G(s, \xi) dB(s) - P.P.V. \int_B U(s, x) \frac{\partial G(s, \xi)}{\partial n_s} dB(s) + U(\xi, x), \quad x \in B$$

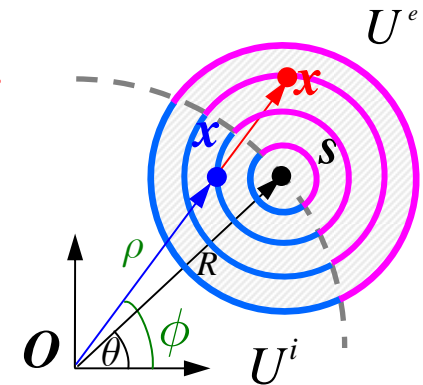
Degenerate (separate) form

$$0 \equiv \int_B T(s, x) G(s, \xi) dB(s) - \int_B U(s, x) \frac{\partial G(s, \xi)}{\partial n_s} dB(s) + U(\xi, x), \quad x \in D^c \cup B$$

Expansions of fundamental solution (2D)

Laplace problem-- $U(s, x) = \ln |x - s| = \ln r$

$$U(s, x) = \begin{cases} U^i(R, \theta; \rho, \phi) = \ln R - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R}\right)^m \cos m(\theta - \phi), & R \geq \rho \\ U^e(R, \theta; \rho, \phi) = \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R}{\rho}\right)^m \cos m(\theta - \phi), & \rho > R \end{cases}$$



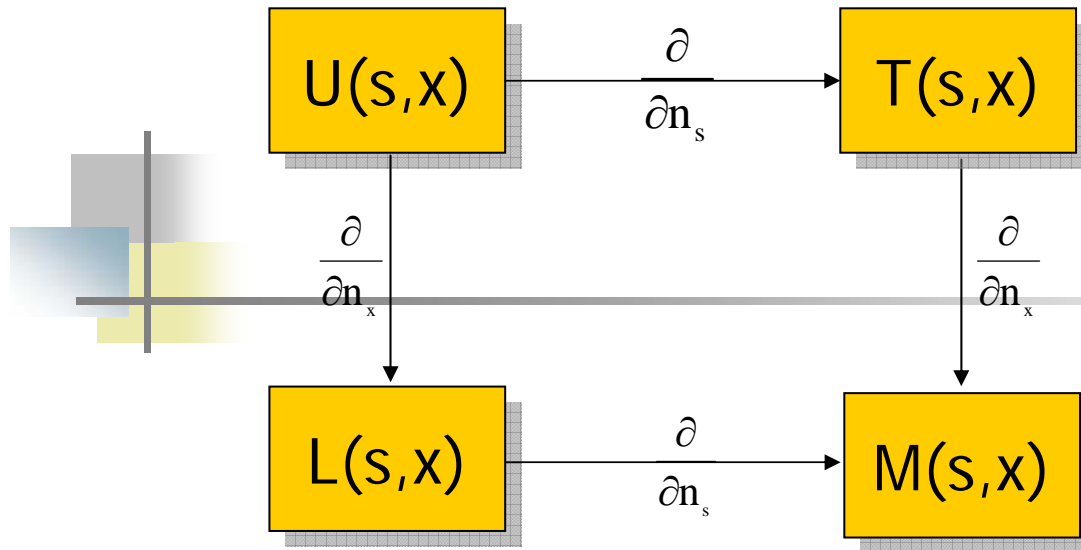
Helmholtz problem-- $U(s, x) = -i\pi H_0^{(1)}(kr)/2$

$$U(s, x) = \begin{cases} U^i(R, \theta; \rho, \phi) = \frac{-\pi i}{2} \sum_{m=0}^{\infty} \varepsilon_m J_m(k\rho) H_m^{(1)}(kR) \cos(m(\theta - \phi)), & R \geq \rho \\ U^e(R, \theta; \rho, \phi) = \frac{-\pi i}{2} \sum_{m=0}^{\infty} \varepsilon_m H_m^{(1)}(k\rho) J_m(kR) \cos(m(\theta - \phi)), & \rho > R \end{cases}$$

Neumann factor

$$\varepsilon_m = \begin{cases} 1, & m = 0 \\ 2, & m = 1, 2, \dots \end{cases}$$



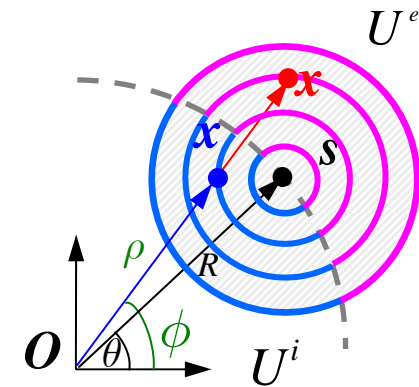


Laplace problem--

$$T(s, x) = \begin{cases} T^i(R, \theta; \rho, \phi) = \frac{1}{R} + \sum_{m=1}^{\infty} \left(\frac{\rho^m}{R^{m+1}} \right) \cos m(\theta - \phi), & R > \rho \\ T^e(R, \theta; \rho, \phi) = -\sum_{m=1}^{\infty} \left(\frac{R^{m-1}}{\rho^m} \right) \cos m(\theta - \phi), & \rho > R \end{cases}$$

Helmholtz problem--

$$T(s, x) = \begin{cases} T^i(R, \theta; \rho, \phi) = \frac{-\pi k i}{2} \sum_{m=0}^{\infty} \varepsilon_m J_m(k\rho) H_m^{(1)}(kR) \cos(m(\theta - \phi)), & R > \rho \\ T^e(R, \theta; \rho, \phi) = \frac{-\pi k i}{2} \sum_{m=0}^{\infty} \varepsilon_m J'_m(kR) H_m^{(1)}(k\rho) \cos(m(\theta - \phi)), & \rho > R \end{cases}$$

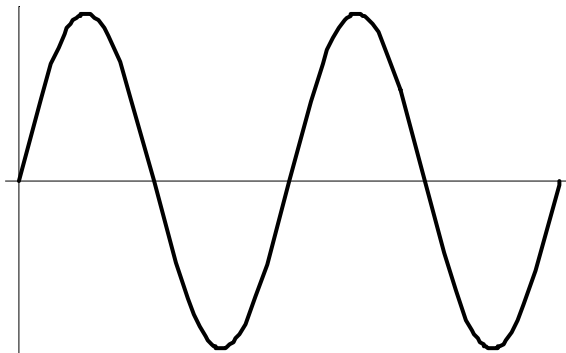


Boundary density discretization

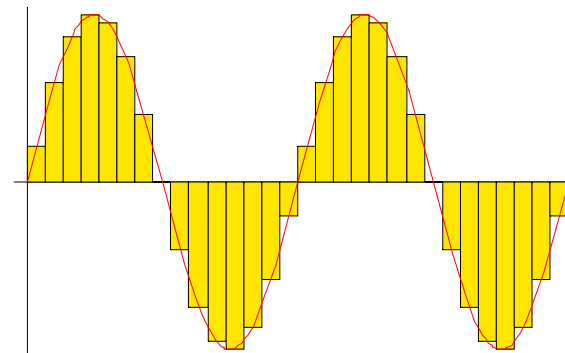
Fourier series expansions - boundary density

$$u(s) = a_0 + \sum_{n=1}^{\infty} (a_n \cos n\theta + b_n \sin n\theta), \quad s \in B$$

$$t(s) = p_0 + \sum_{n=1}^{\infty} (p_n \cos n\theta + q_n \sin n\theta), \quad s \in B$$

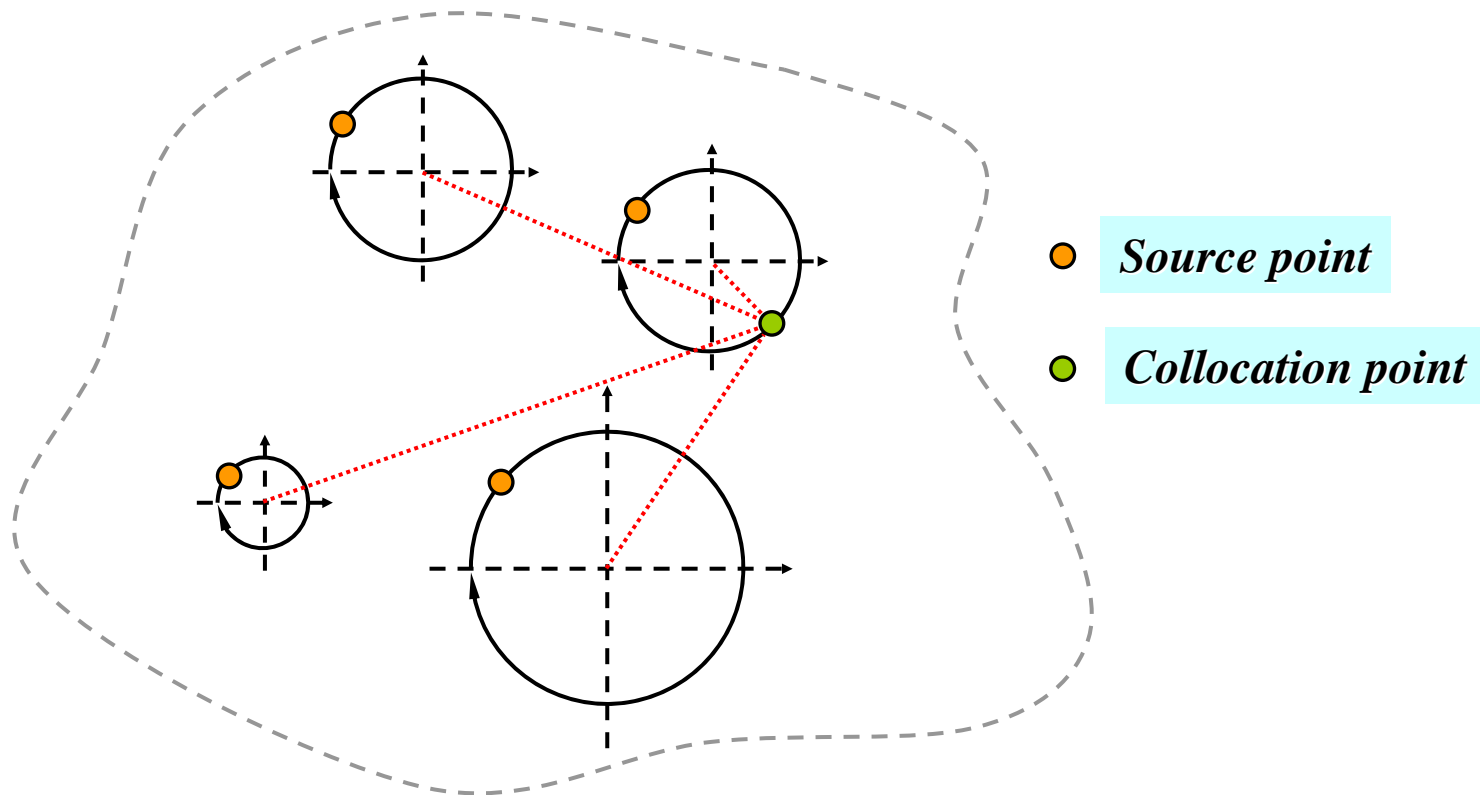


Fourier series

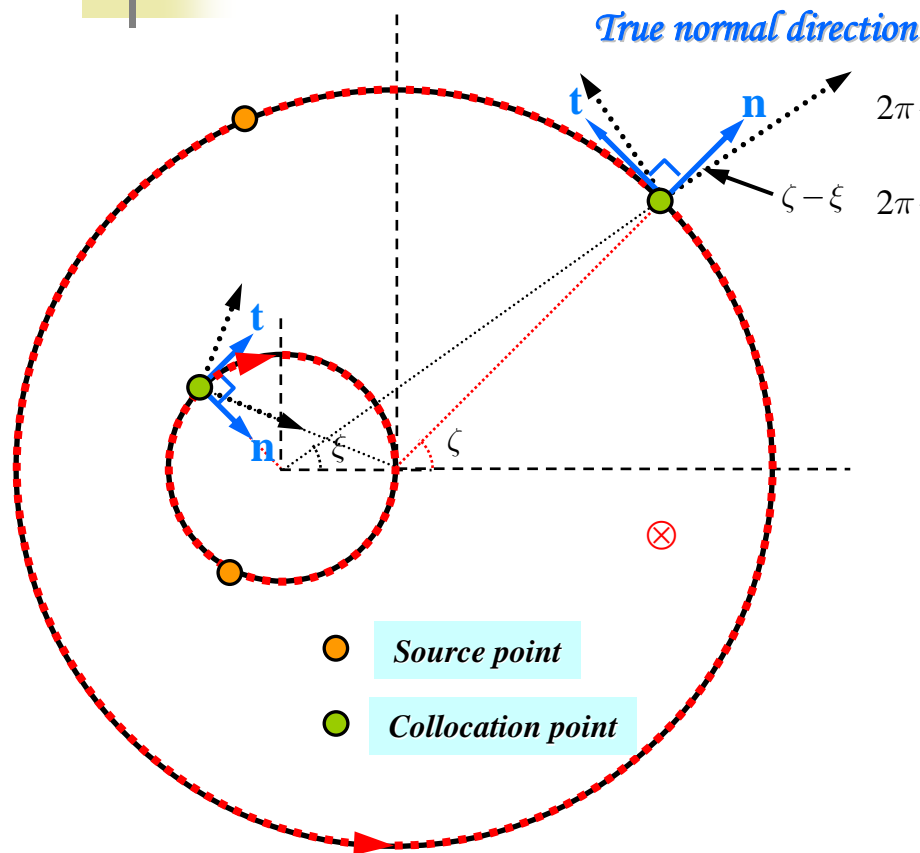


Ex. constant element

Adaptive observer system



Vector decomposition technique for potential gradient



$$2\pi \frac{\partial G(x, \xi)}{\partial \mathbf{n}} = \int_B M_\rho(s, x) G(s) dB(s) - \int_B L_\rho(s, x) \frac{\partial G(s)}{\partial \mathbf{n}} dB(s) + L_\rho(\xi, x)$$

$$2\pi \frac{\partial G(x, \xi)}{\partial \mathbf{t}} = \int_B M_\phi(s, x) G(s) dB(s) - \int_B L_\phi(s, x) \frac{\partial G(s)}{\partial \mathbf{n}} dB(s) + L_\phi(\xi, x)$$

Non-concentric case:

$$L_\rho(s, x) = \frac{\partial U(s, x)}{\partial \rho} \cos(\zeta - \xi) + \frac{1}{\rho} \frac{\partial U(s, x)}{\partial \phi} \cos\left(\frac{\pi}{2} - \zeta + \xi\right)$$

$$M_\rho(s, x) = \frac{\partial T(s, x)}{\partial \rho} \cos(\zeta - \xi) + \frac{1}{\rho} \frac{\partial T(s, x)}{\partial \phi} \cos\left(\frac{\pi}{2} - \zeta + \xi\right)$$

Concentric case (special case): $\zeta = \xi$

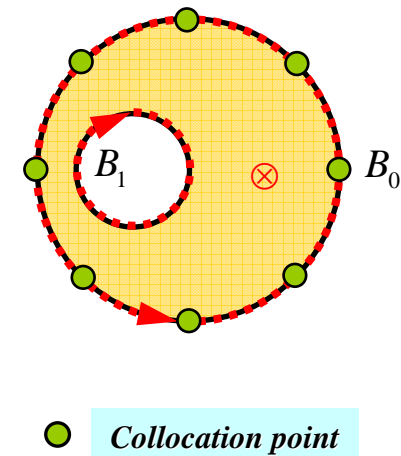
$$L_\rho(s, x) = \frac{\partial U(s, x)}{\partial \rho} \quad M_\rho(s, x) = \frac{\partial T(s, x)}{\partial \rho}$$

Linear algebraic equation

$$0 = \int_B T(s, \mathbf{x}) G(s, \xi) dB(s) - \int_B U(s, \mathbf{x}) \frac{\partial G(s, \xi)}{\partial n_s} dB(s) + U(\xi, \mathbf{x})$$

$$\Rightarrow [\mathbf{U}]\{\mathbf{t}\} = [\mathbf{T}]\{\mathbf{u}\} + \{\mathbf{b}\}$$

$$[\mathbf{U}] = \begin{bmatrix} \mathbf{U}_{00} & \mathbf{U}_{01} & \cdots & \mathbf{U}_{0N} \\ \mathbf{U}_{10} & \mathbf{U}_{11} & \cdots & \mathbf{U}_{1N} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{U}_{N0} & \mathbf{U}_{N1} & \cdots & \mathbf{U}_{NN} \end{bmatrix} \quad \{\mathbf{t}\} = \begin{bmatrix} \mathbf{t}_0 \\ \mathbf{t}_1 \\ \mathbf{t}_2 \\ \vdots \\ \mathbf{t}_N \end{bmatrix} \quad \{\mathbf{b}\} = \begin{bmatrix} \mathbf{b}_0 \\ \mathbf{b}_1 \\ \mathbf{b}_2 \\ \vdots \\ \mathbf{b}_N \end{bmatrix}$$



Take free body

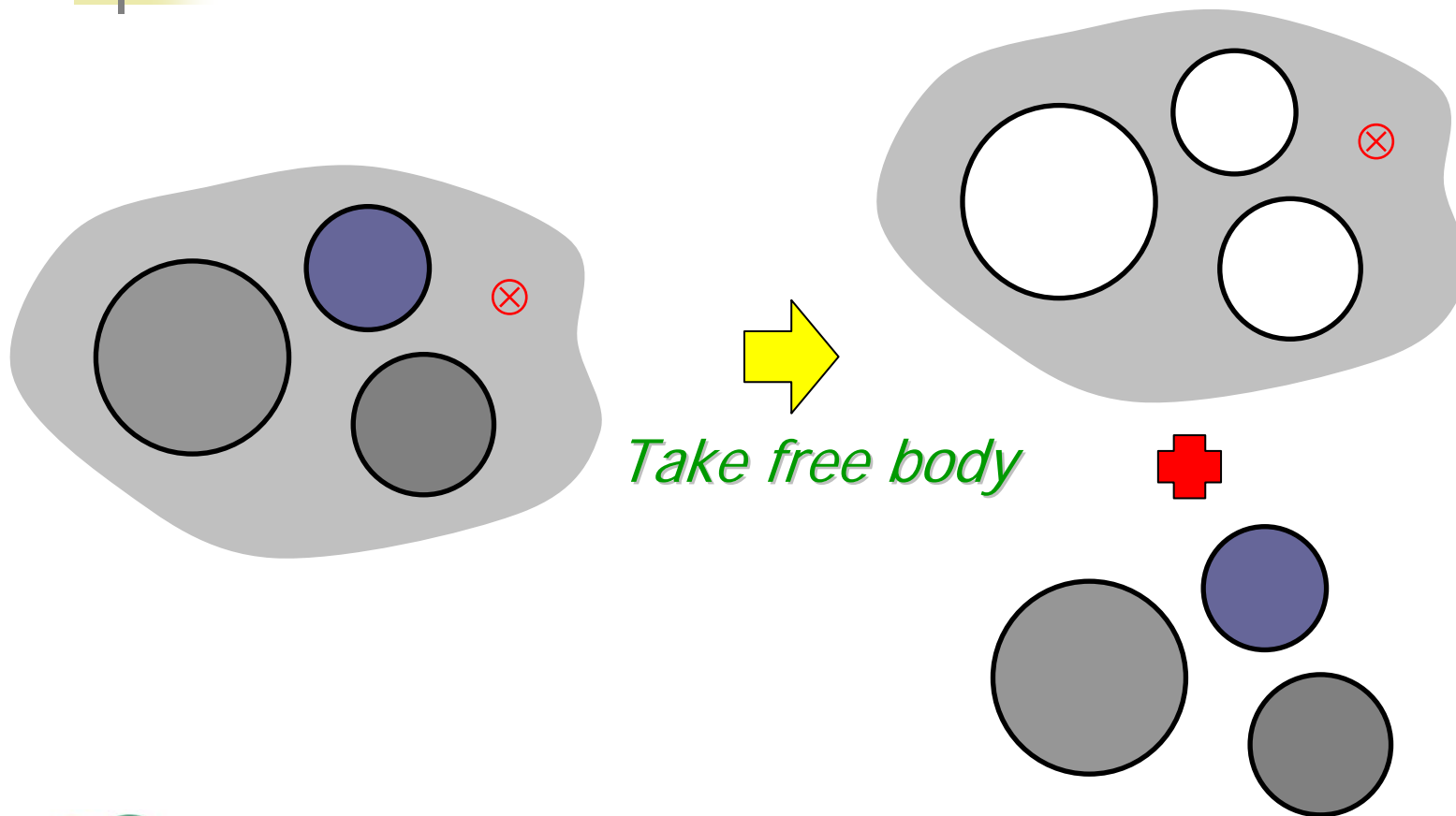
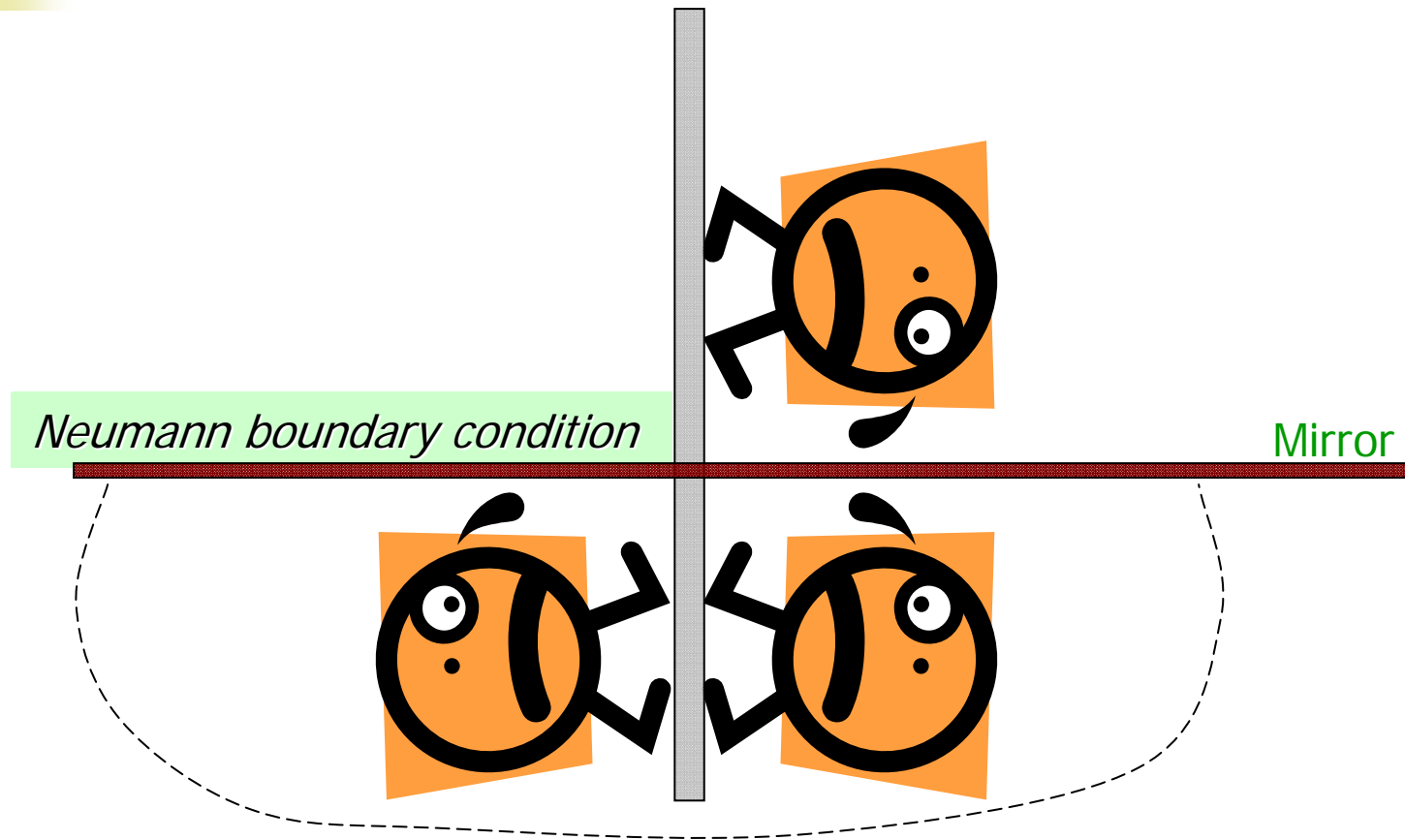
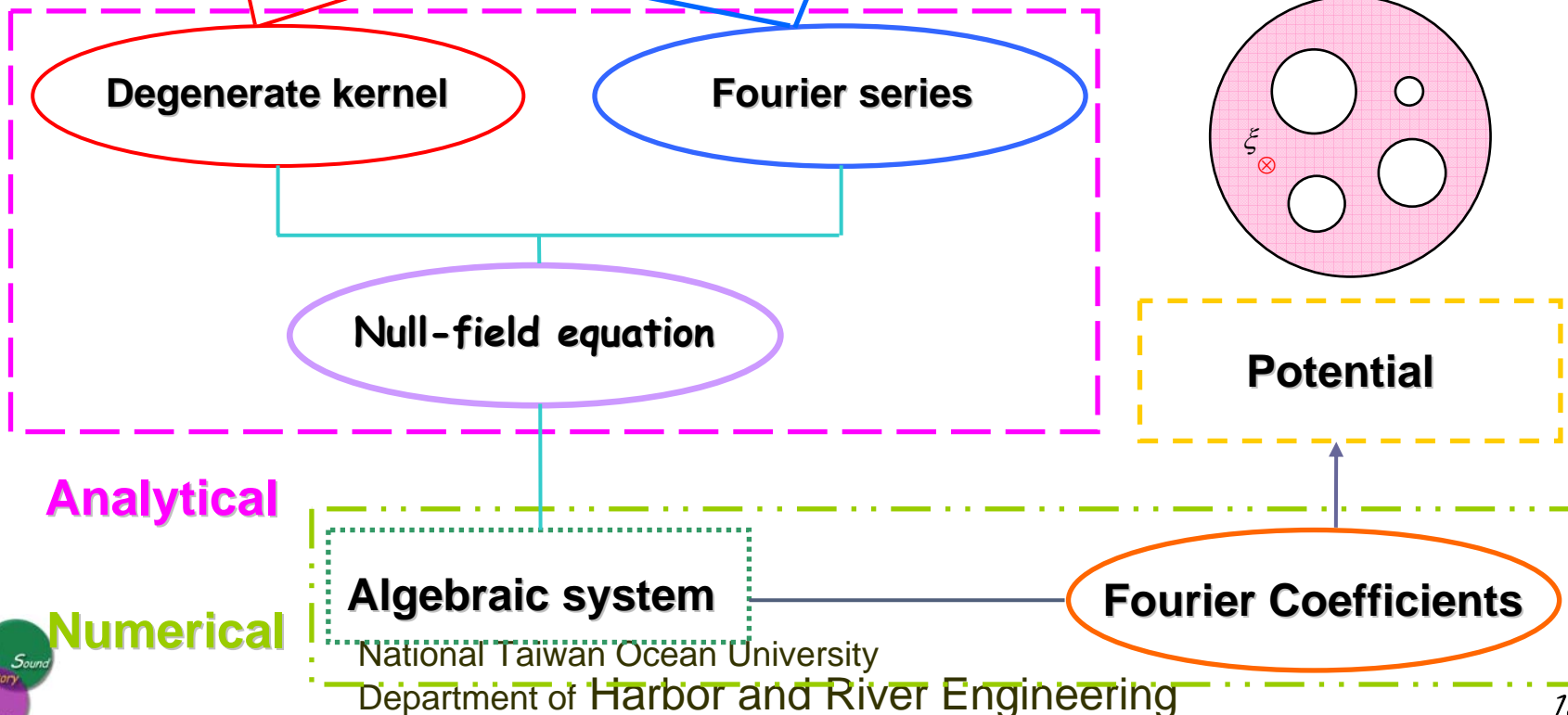


Image technique for solving half-plane problems



Flowchart of present method

$$0 = \int_B [T(s, x) G(s, \xi) - U(s, x) \frac{\partial G(s, \xi)}{\partial n_s}] dB(s) + U(\xi, x)$$





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- Green's function for Helmholtz problems

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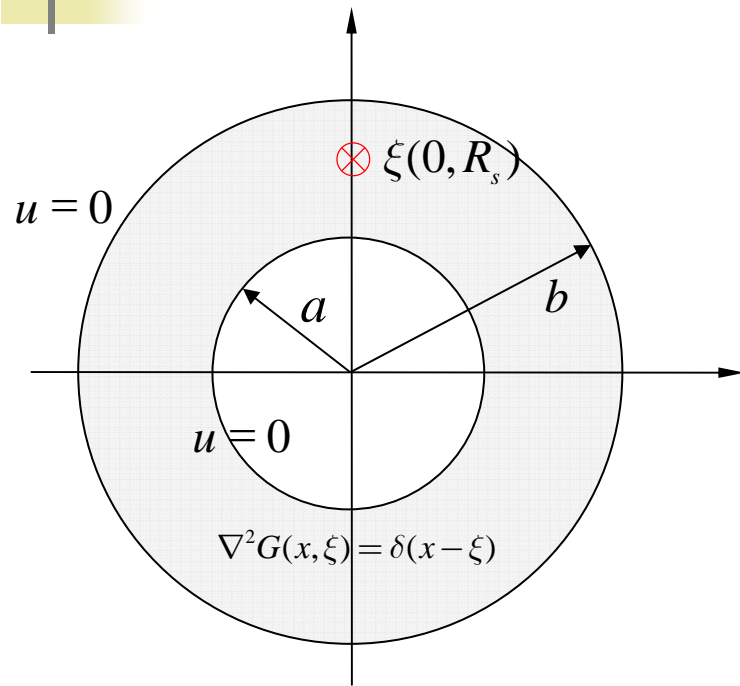




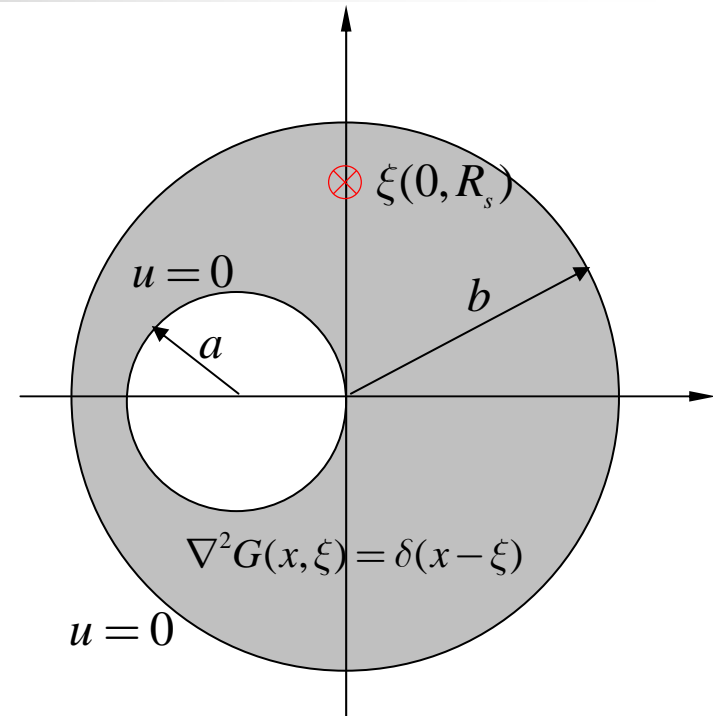
Numerical examples

- Laplace problems
 - Eccentric ring
 - A half-plane with an aperture
 - (1) Dirichlet boundary condition
 - (2) Robin boundary condition
 - A half-plane problem with a circular hole and a half-circular inclusion
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Present study for Laplace equation



Analytical Green's function



Semi-Analytical
Green's function

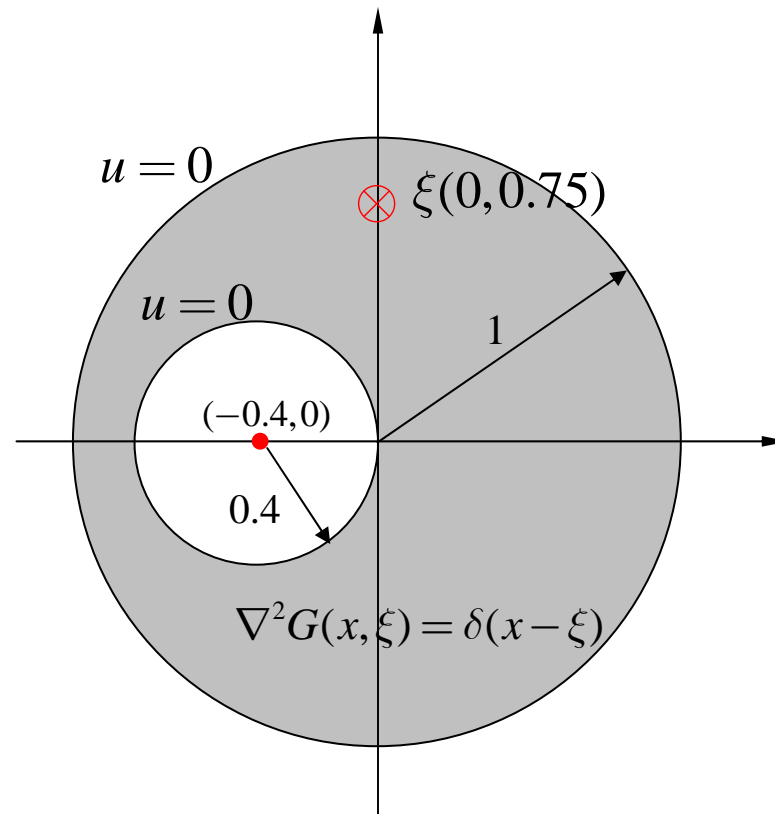




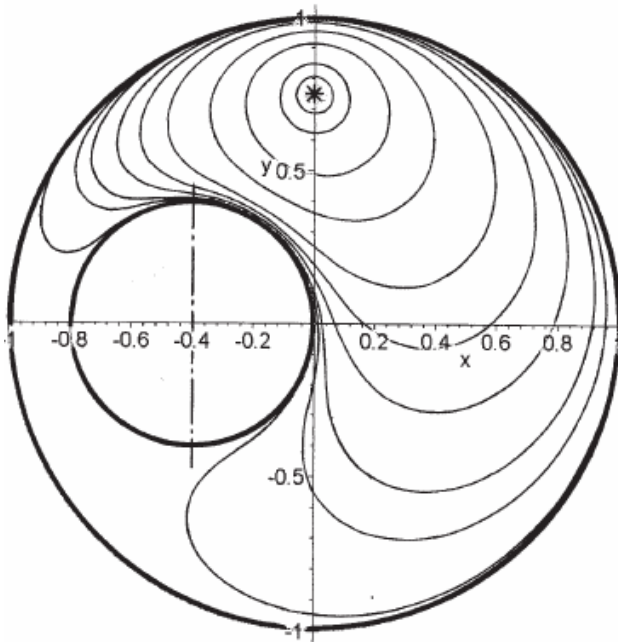
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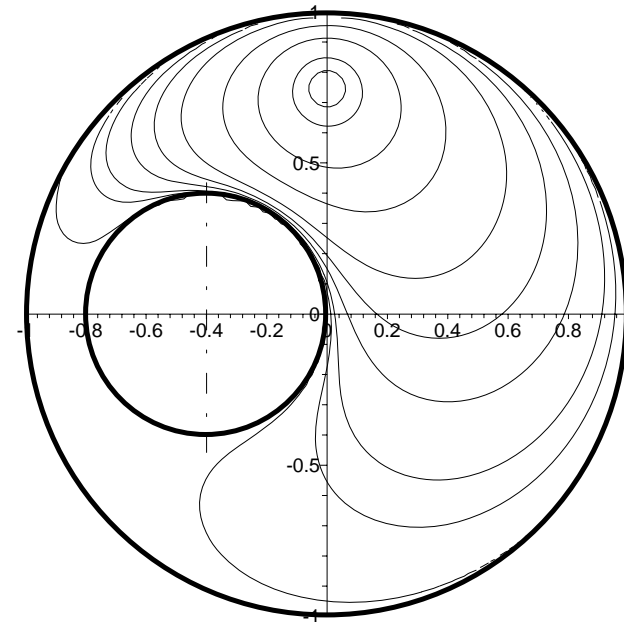
Eccentric ring



Eccentric ring



Potential contour using the Melnikov's method



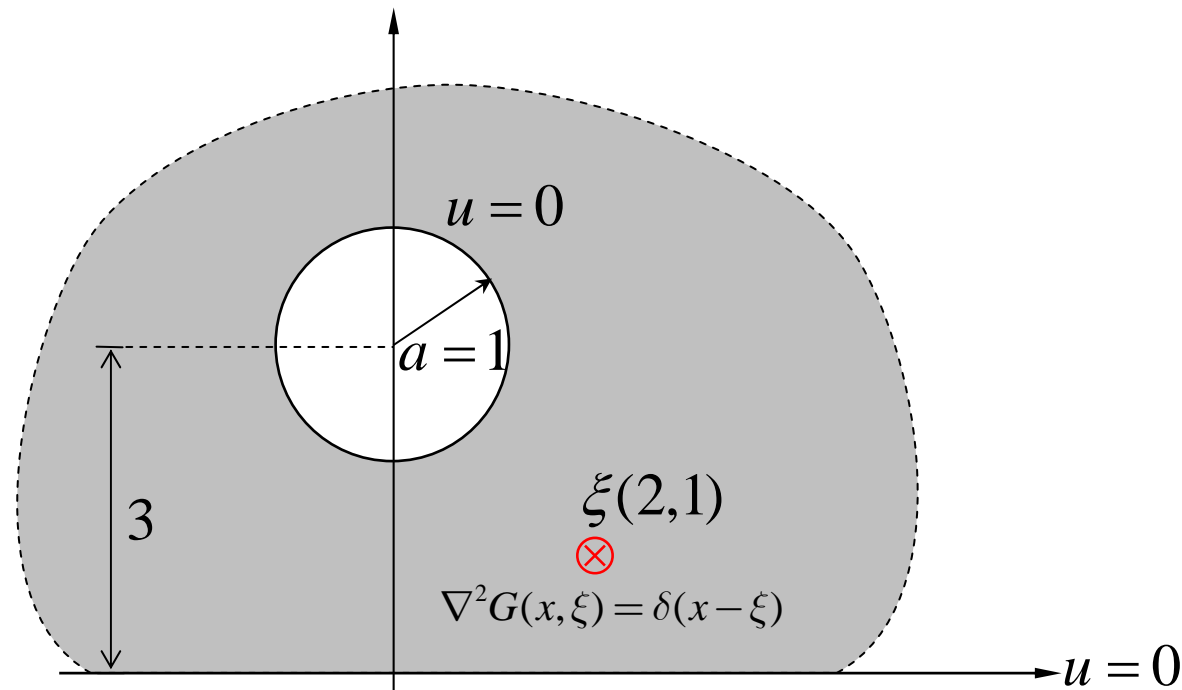
Potential contour using the present method ($M=50$)



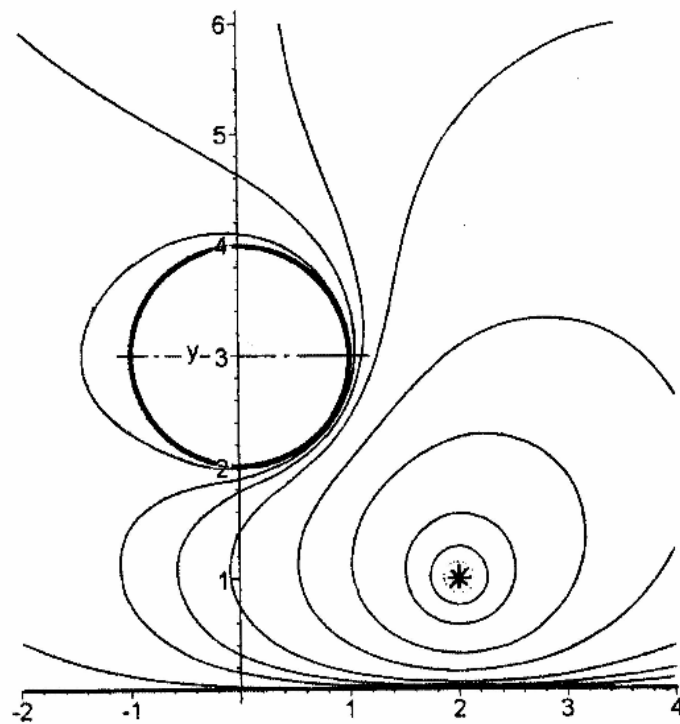
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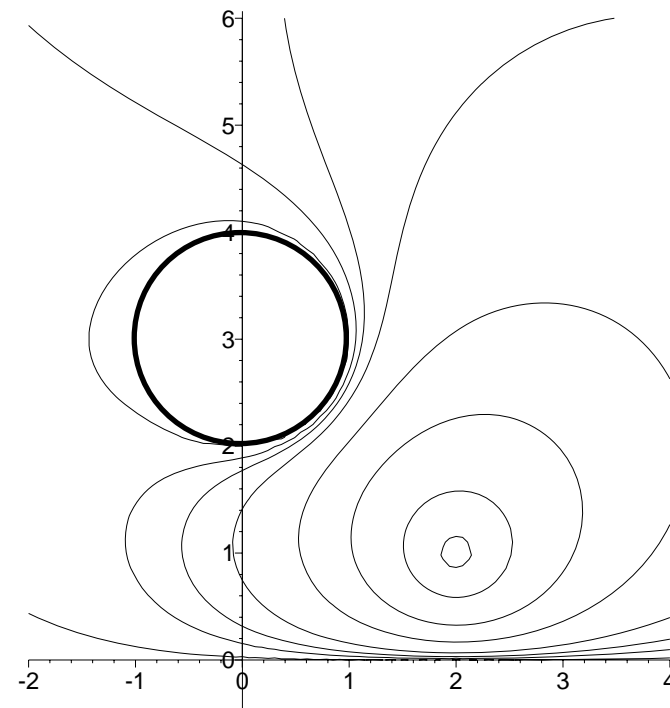
A half plane with an aperture subjected to Dirichlet boundary condition



Result of a half-plane problem with an aperture subjected to **Dirichlet boundary condition**

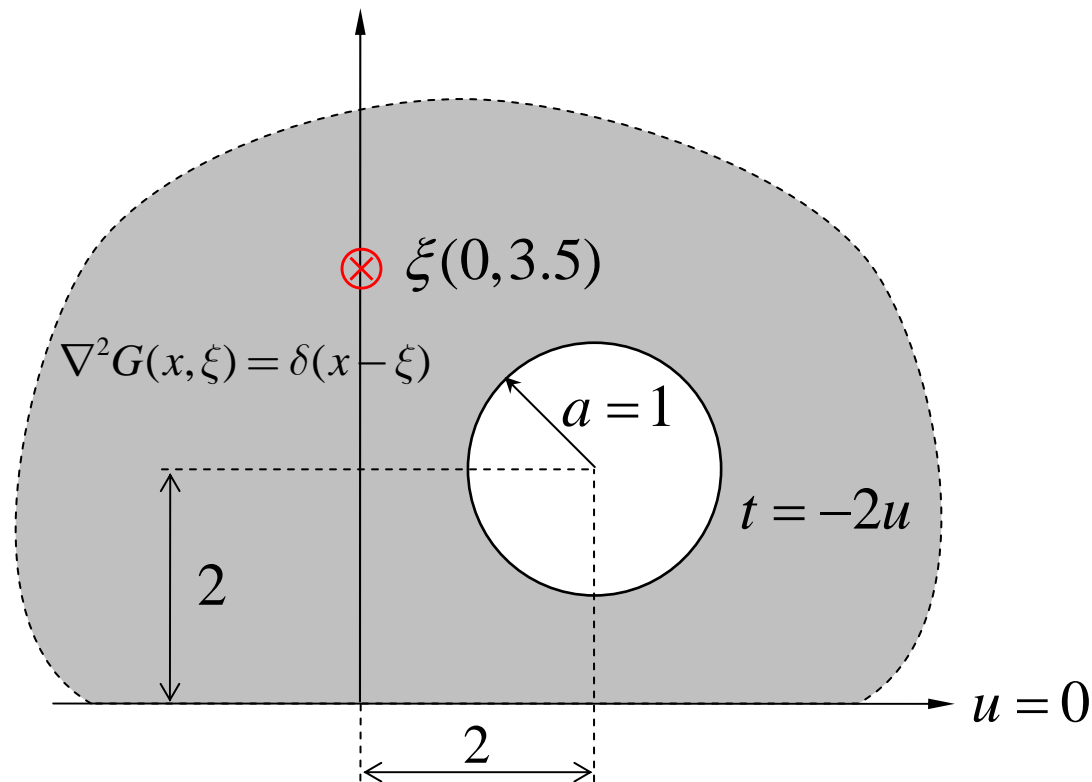


Potential contour using the Melnikov's method

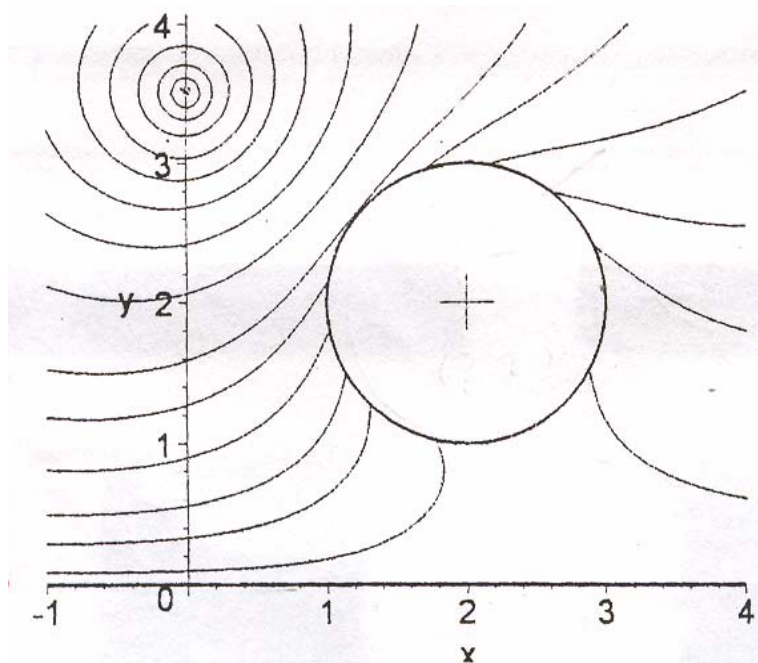


Potential contour using the present method (M=50)

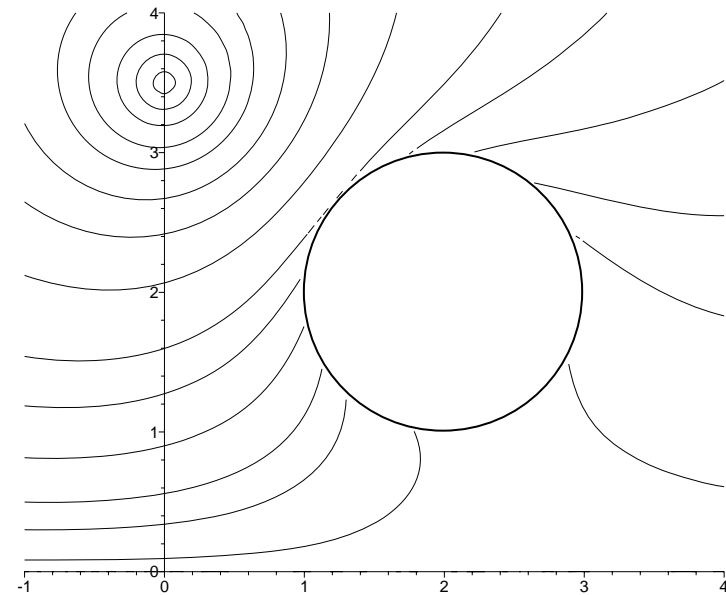
A half plane with an aperture subjected to Robin boundary condition



Result of a half-plane problem with an aperture subjected to Robin boundary condition



Potential contour using the Melnikov's method



Potential contour using the present method (M=50)

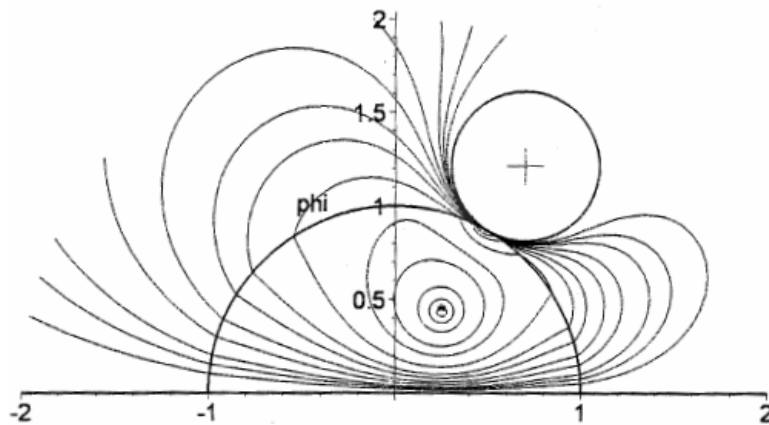


Numerical examples

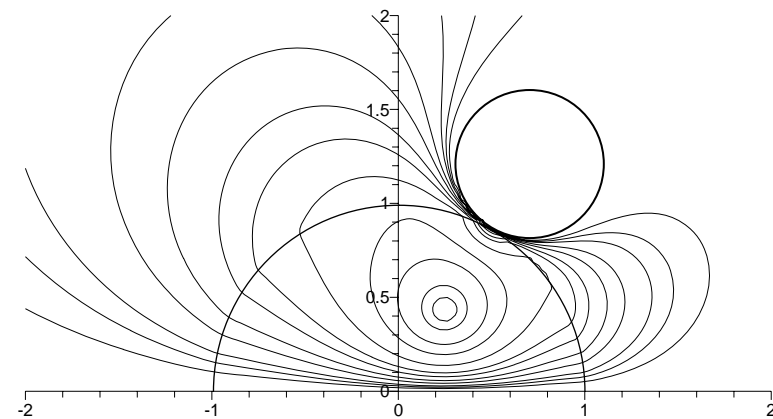
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Result of a half-plane problem with a circular hole and a half-circular inclusion



Contour plot by using the Melikov's approach (2006)



Contour plot by using the null-field integral equation approach



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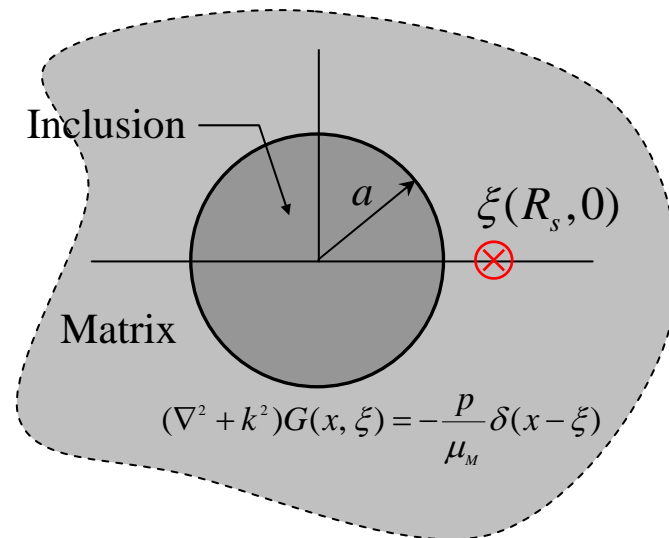
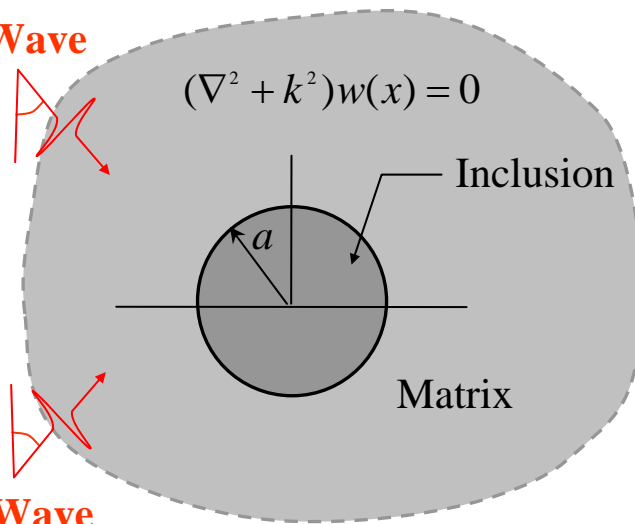
Present study for Helmholtz equation

Perfect interface boundary



Imperfect interface boundary

SH-Wave



SH-wave problem (Chen P. Y.)

Green's function problem (Ke J. N.)

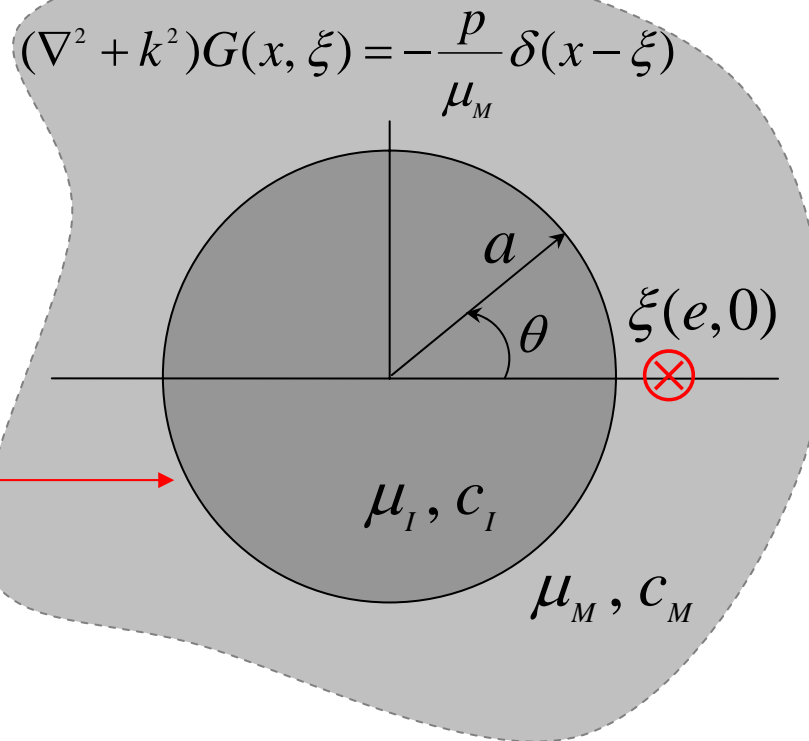
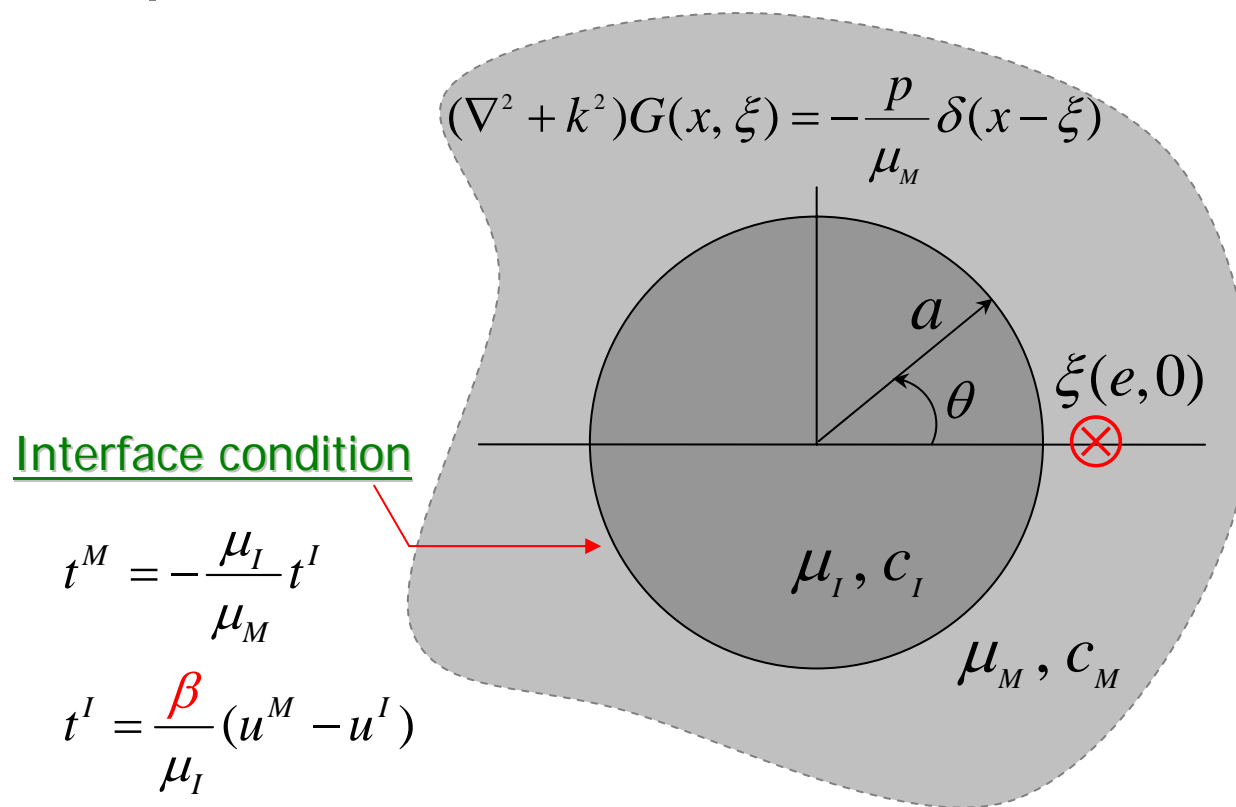




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An infinite matrix containing a circular inclusion with
a concentrated force at ξ in the matrix



$$e = 1.1a$$

$$\mu_I = 4\mu_M \quad c_I = 2c_M$$

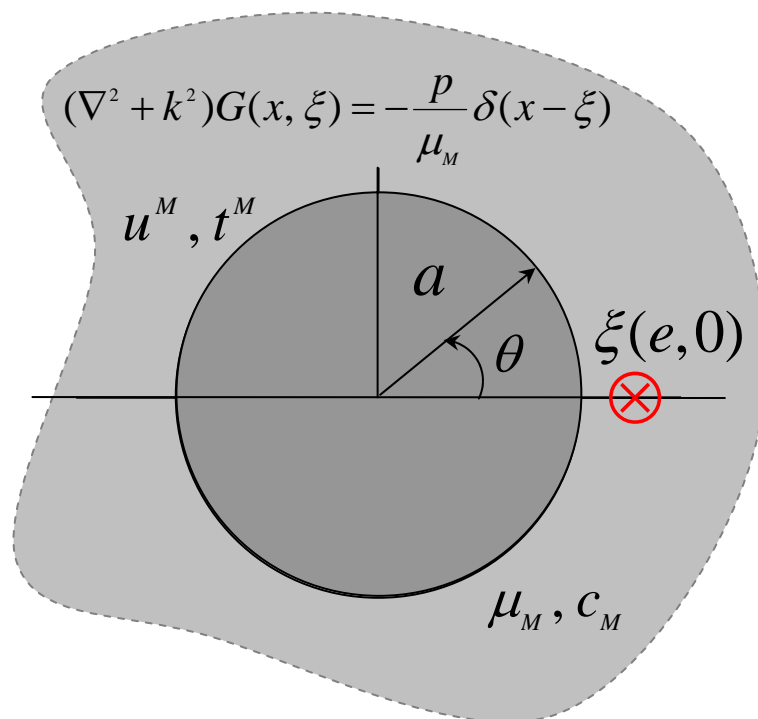
μ is the shear modulus

c is the wave speed

β is the imperfect
interface parameter



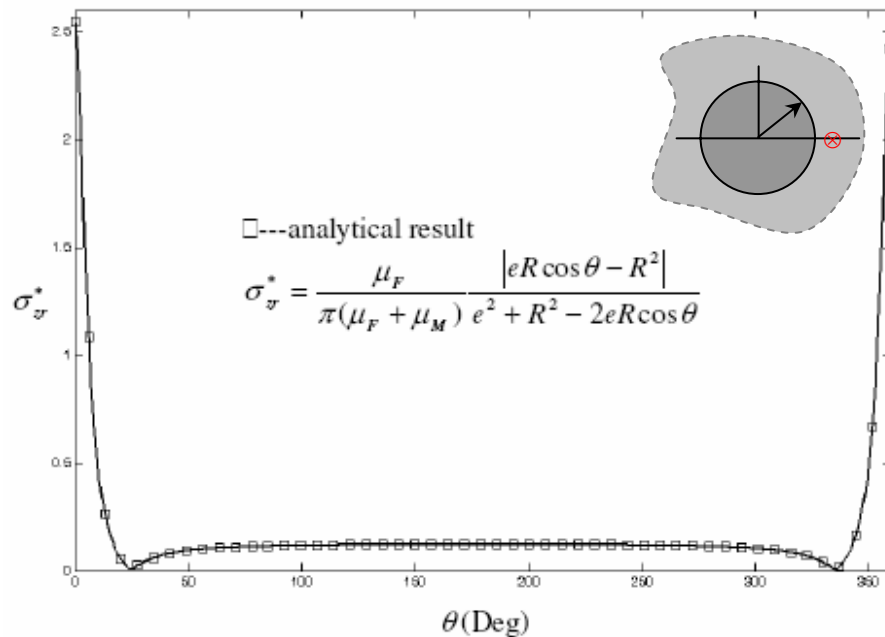
Take free body



u^I, t^I
 a
 θ
 μ_I, c_I
 $t^M = -\frac{\mu_I}{\mu_M} t^I$
 $t^I = \frac{\beta}{\mu_I} (u^M - u^I)$

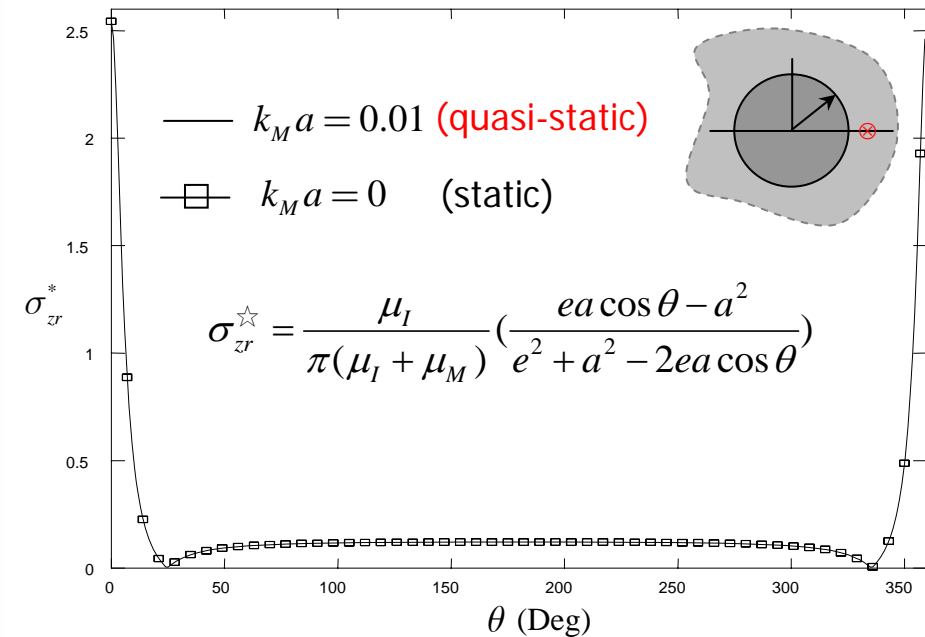
Distribution of σ_{zr}^* for the **quasi-static** ($k_M a = 0.01$) solution along the circular boundary

$$\sigma_{zr}^* = a |\sigma_{zr}^I| / p = a |\sigma_{zr}^M| / p$$



Wang and Sudak's solution

$$\sigma_{zr}^\star = a \sigma_{zr}^I / p = a \sigma_{zr}^M / p$$

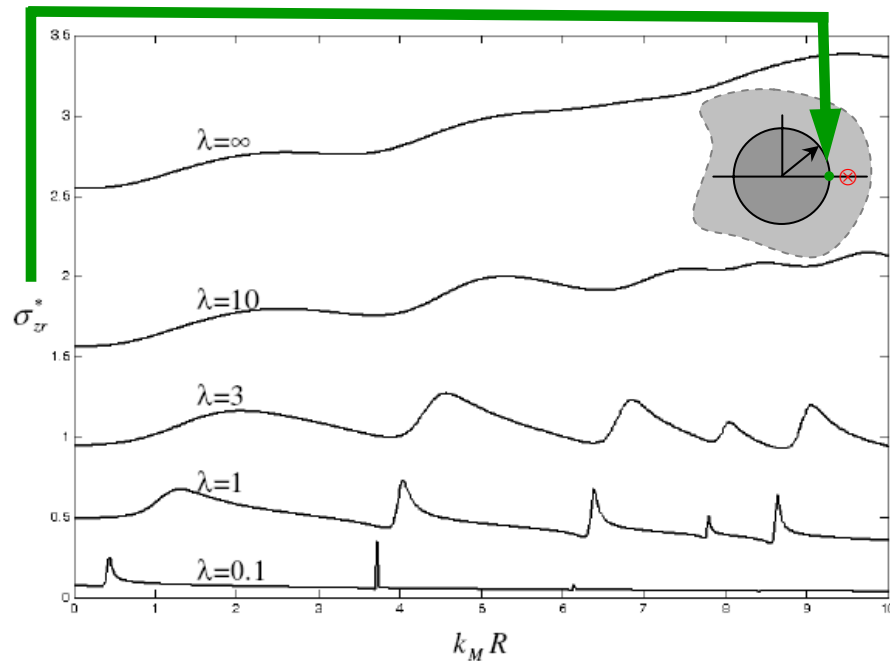


The present solution

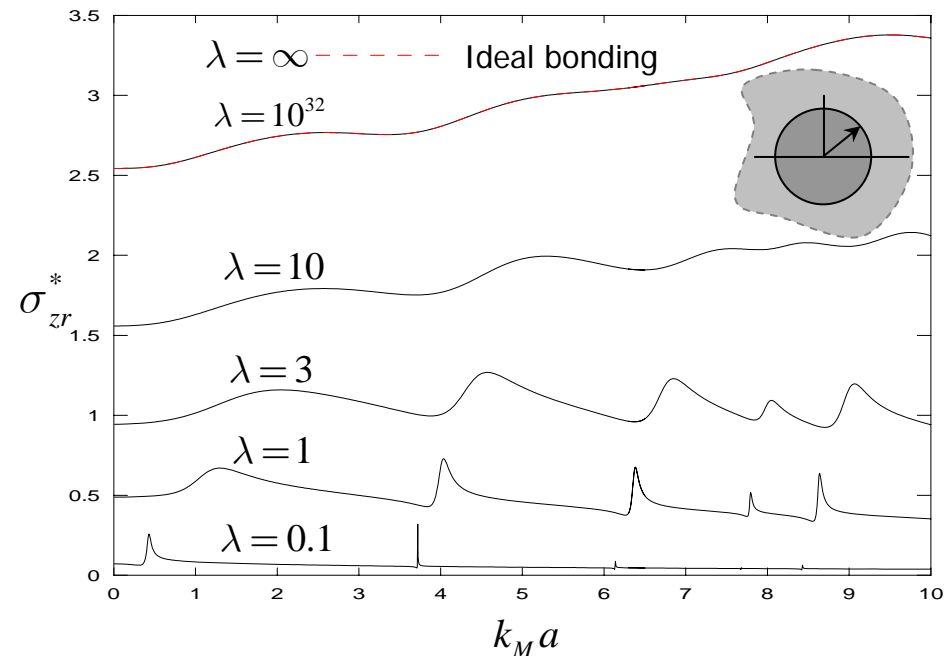
Parameter study of $\lambda = a\beta / \mu_M$ for the stress response

$$\sigma_{zr}^* = a |\sigma_{zr}^I| / p = a |\sigma_{zr}^M| / p$$

Bonding behavior



Wang and Sudak's solution



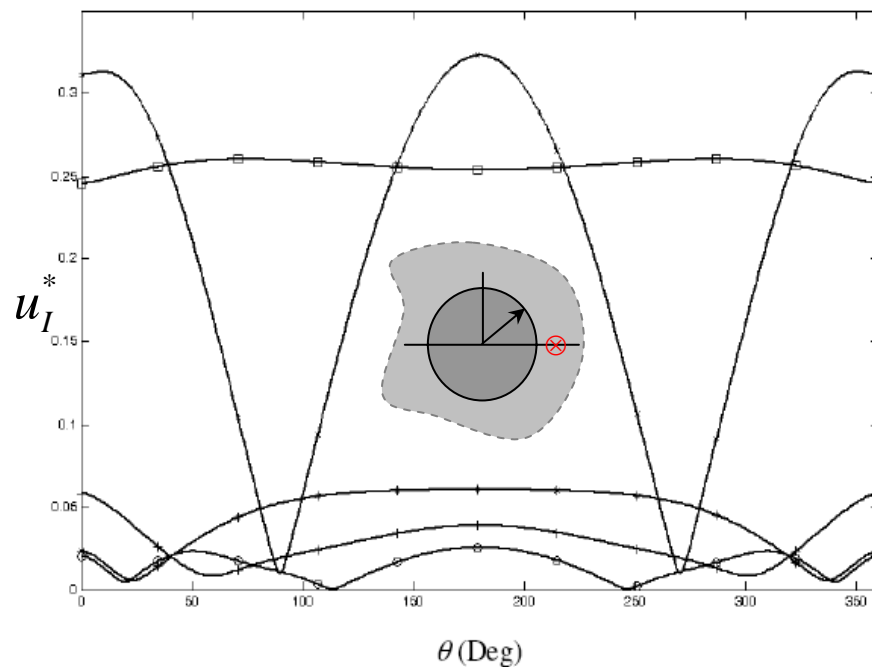
The present solution



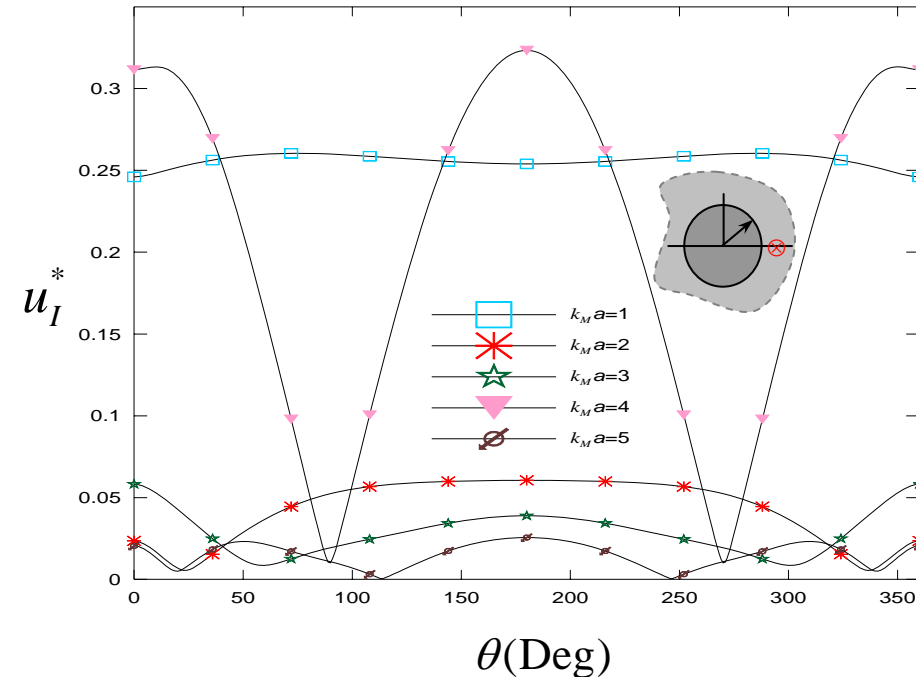
The distribution of displacement u_I^* along the circular boundary for the case $(k_M a = 1, 2, 3, 4, 5)$

$$u_I^* = \mu_M |u_I| / p$$

Dynamic effect



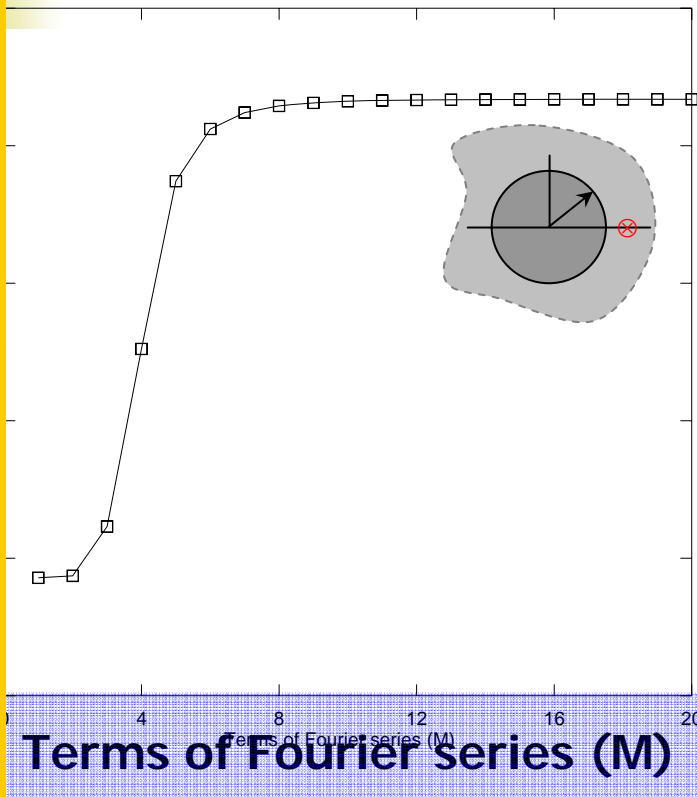
Wang and Sudak's solution



The present solution

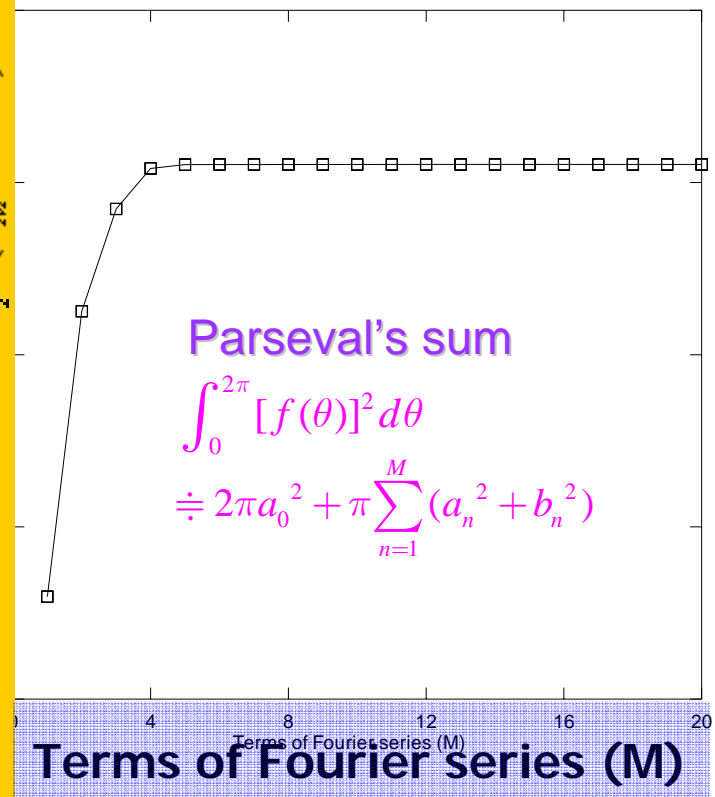
Test of convergence for the Fourier series with a concentrated force in the inclusion

Parseval's sum of real solution
for u_I^* ($k_M a = 4$)



real part

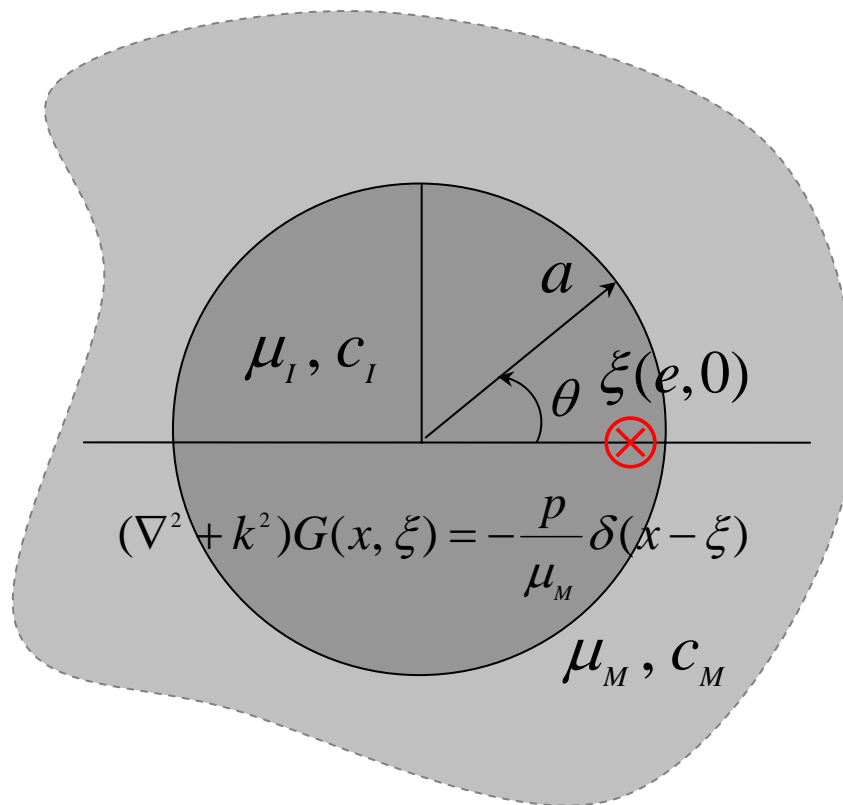
Parseval's sum of imaginary part
for u_I^* ($k_M a = 4$)



imaginary part



An infinite matrix containing a circular inclusion with a concentrated force at ξ in the inclusion



$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$t^I = \frac{\beta}{\mu_I} (u^M - u^I)$$

$$e = 0.9a$$

$$\mu_I = 4\mu_M, \quad c_I = 2c_M$$

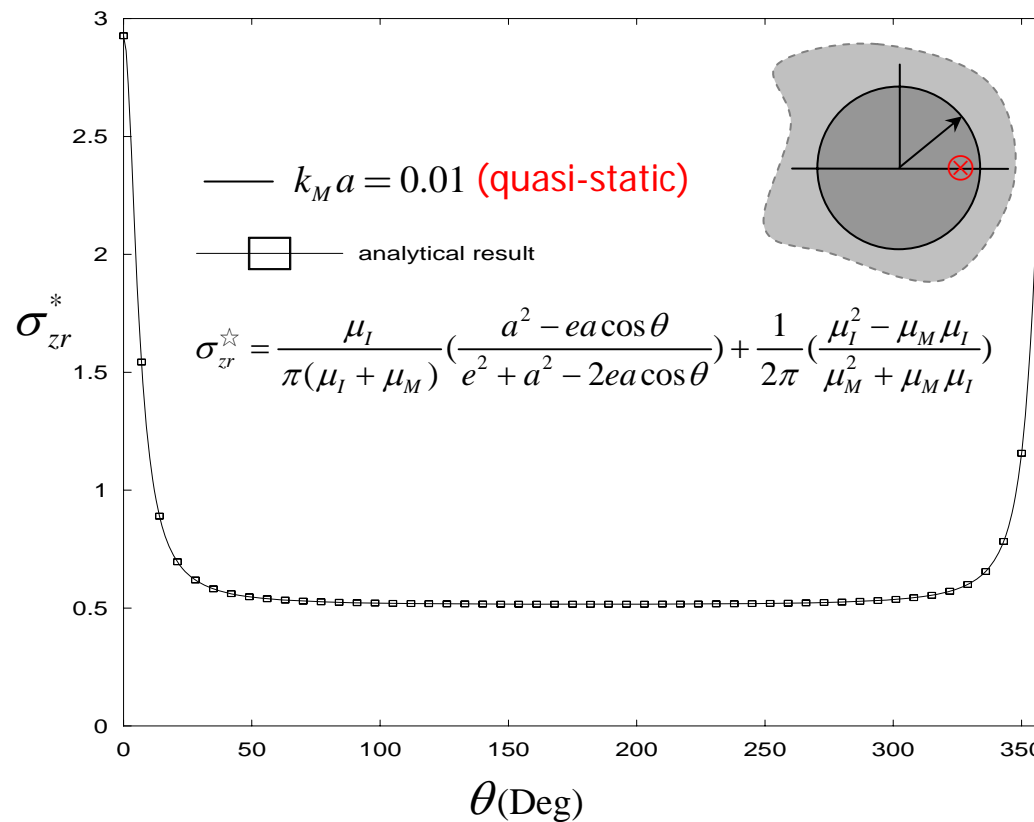
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c is the wave speed

β is the imperfect interface parameter



Distribution of σ_{zr}^* for the **quasi-static** ($k_M a = 0.01$) solution along the circular boundary ($e = 0.9a$)

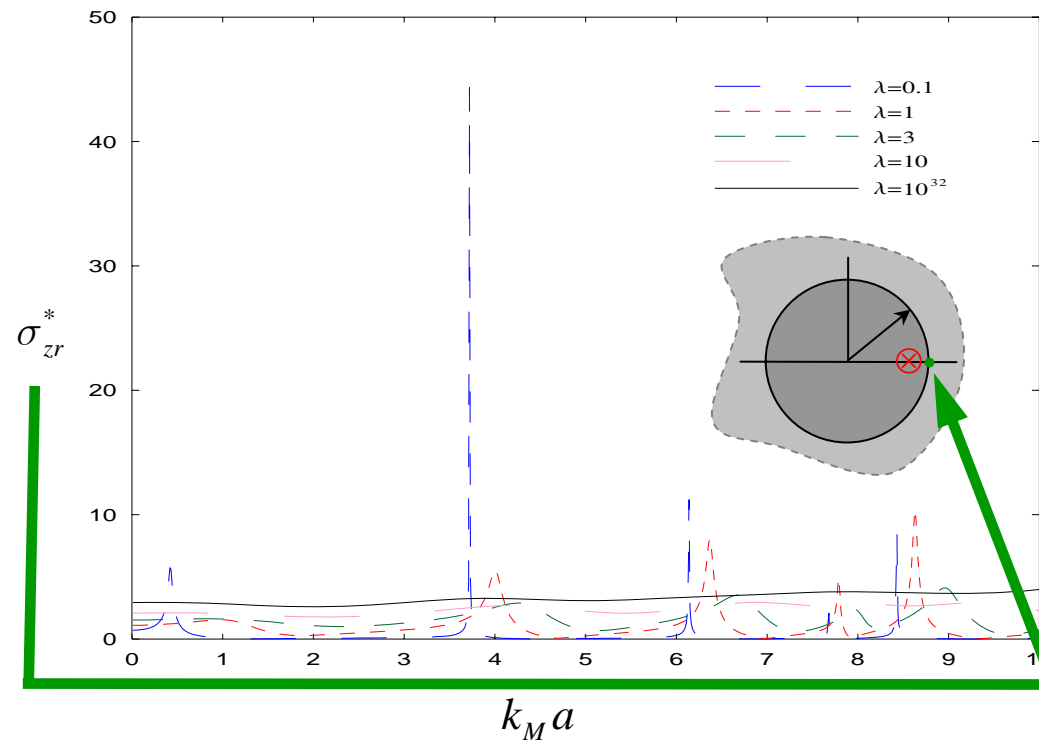


$$\sigma_{zr}^* = a |\sigma_{zr}^I| / p = a |\sigma_{zr}^M| / p$$

$$\sigma_{zr}^{\star} = a \sigma_{zr}^I / p = a \sigma_{zr}^M / p$$

Parameter study of $\lambda = a\beta / \mu_M$ for the stress response ($e = 0.9a$)

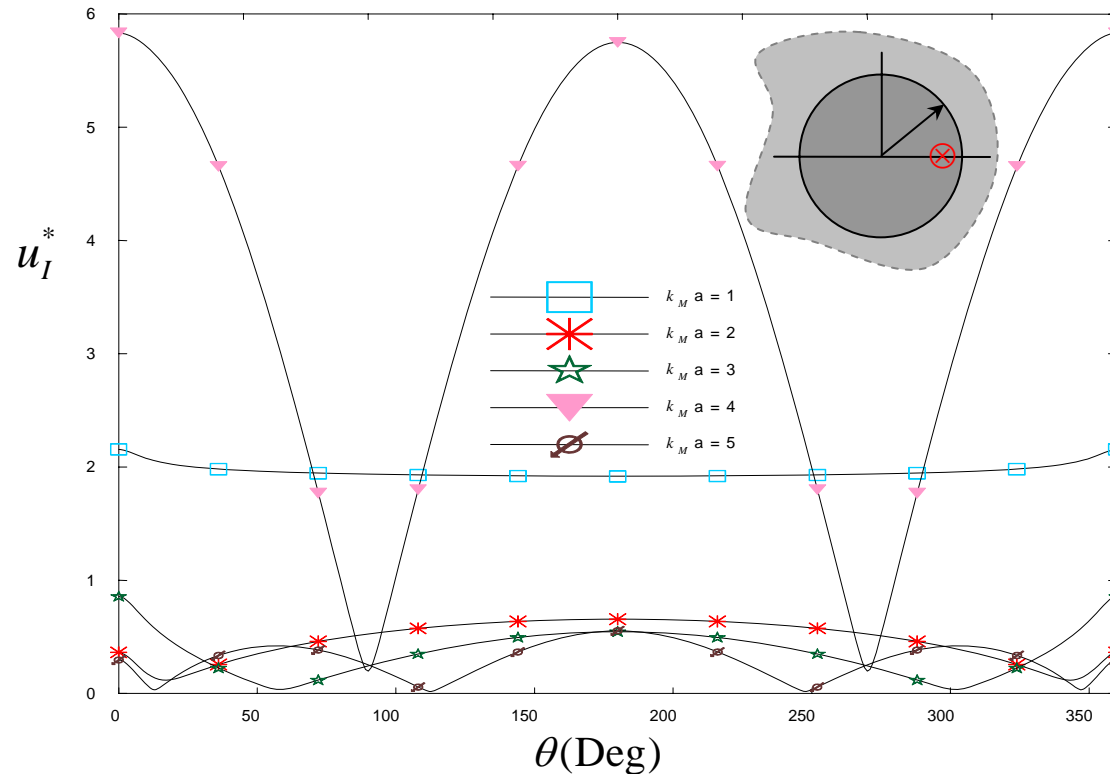
$$\sigma_{zr}^* = a |\sigma_{zr}^I| / p = a |\sigma_{zr}^M| / p$$



Bonding behavior

The distribution of displacement u_I^* along the circular boundary for the case of $\lambda=1$ ($e=0.9a$)

$$u_I^* = \mu_M |u_I| / p$$



Dynamic effect



Numerical examples

- Laplace problems
 - Eccentric ring
 - A half-plane with an aperture
 - (1) Dirichlet boundary condition
 - (2) Robin boundary condition
 - A half-plane problem with a circular hole and a half-circular inclusion
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Special case of an ideally bonded case ($\beta = \infty$)



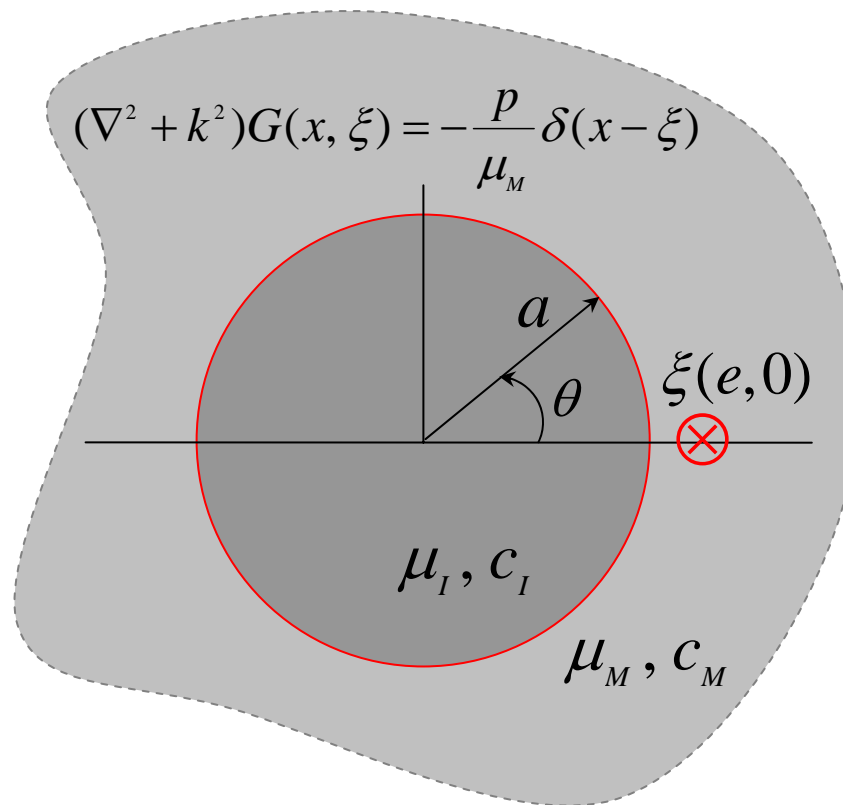
$$\mu_I = 4\mu_M$$

$$c_I = 2c_M$$

μ is the shear modulus

c is the wave speed

β is the imperfect interface parameter



$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

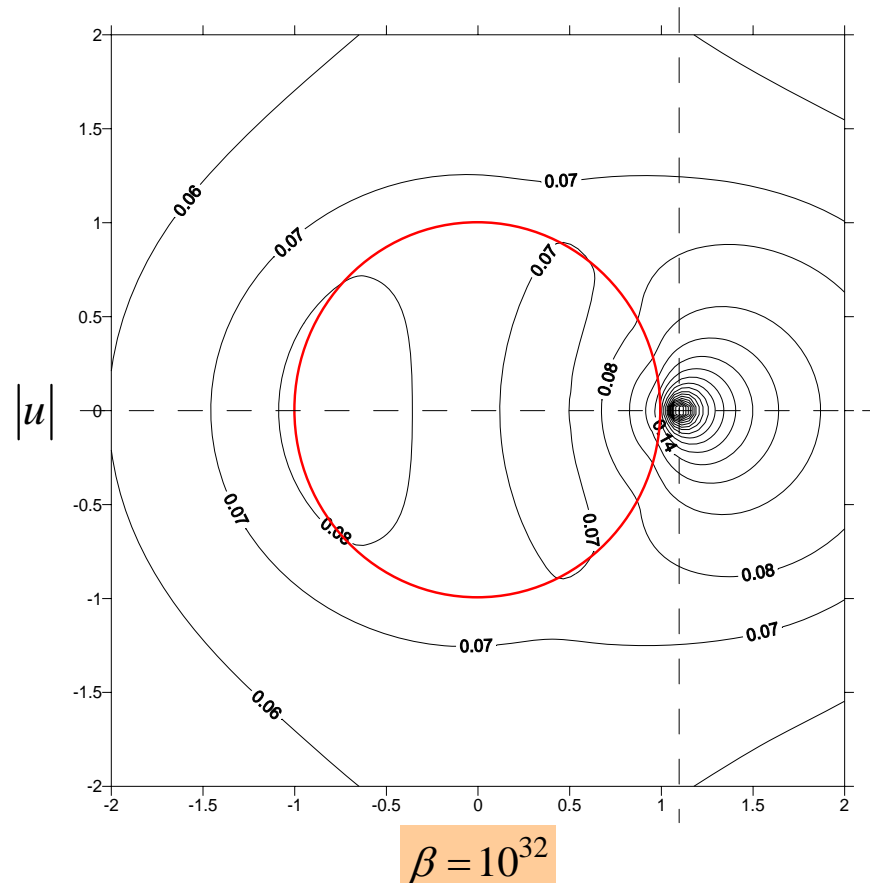
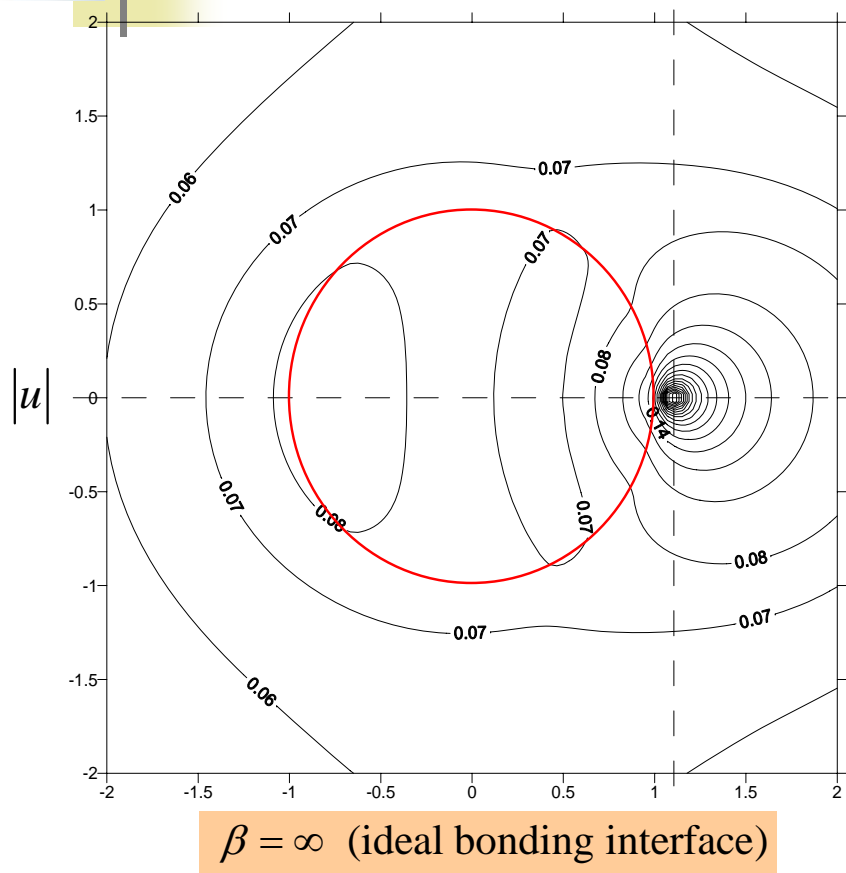
$$t^I = \frac{\beta}{\mu_I} (u^M - u^I)$$

Imperfect bonding
($\beta \rightarrow \infty$)
↓
Ideal bonding

$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$u^M = u^I$$

The absolute amplitude of displacement by the present method



Special case of cavity ($\beta = 0$)

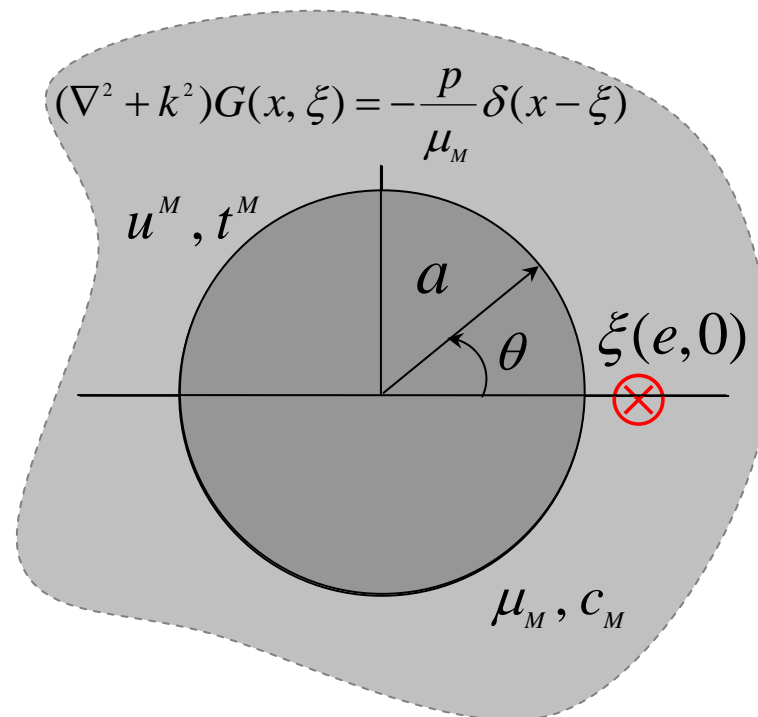
$$\mu_I = 4\mu_M$$

$$c_I = 2c_M$$

μ is shear modulus

c is wave speed

β is the imperfect interface parameter



$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$t^I = \frac{\beta}{\mu_I} (u^M - u^I)$$



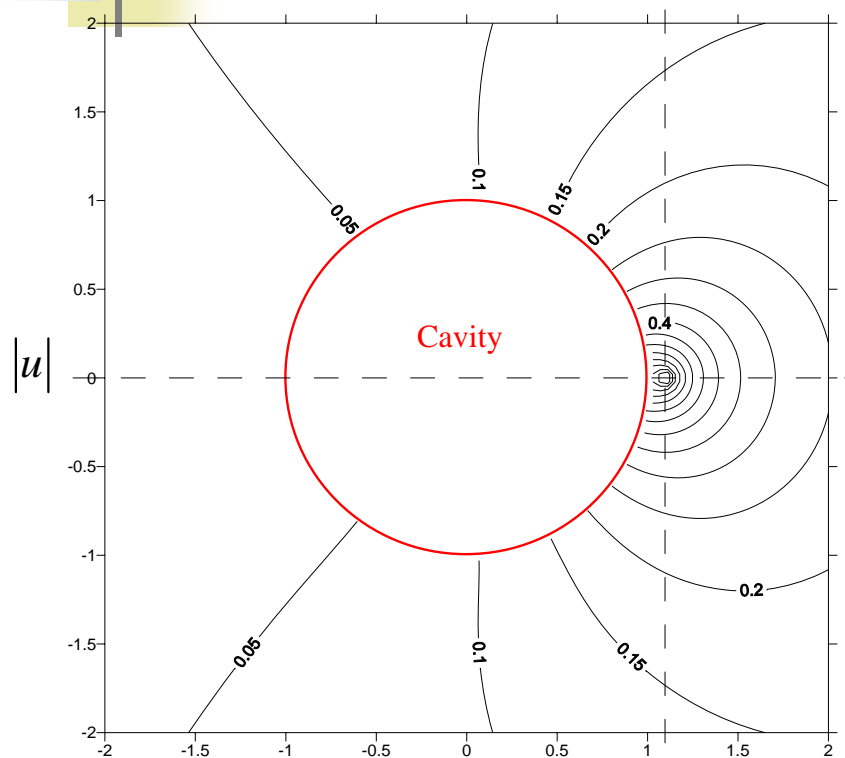
Imperfect bonding

Cavity

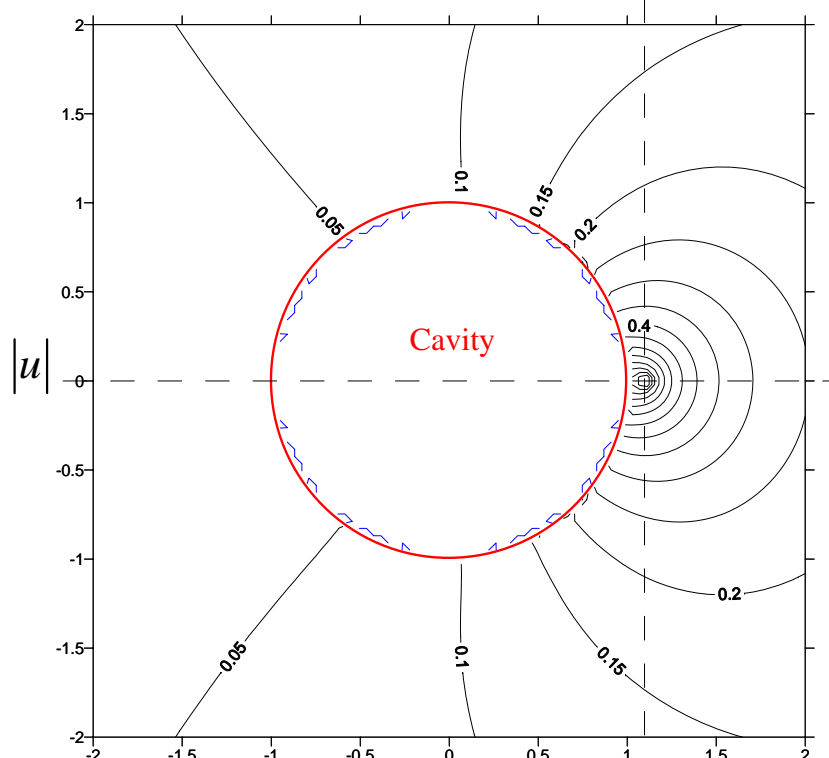
$$t^M = 0$$

$$u^M = ?$$

The absolute amplitude of displacement by the present method



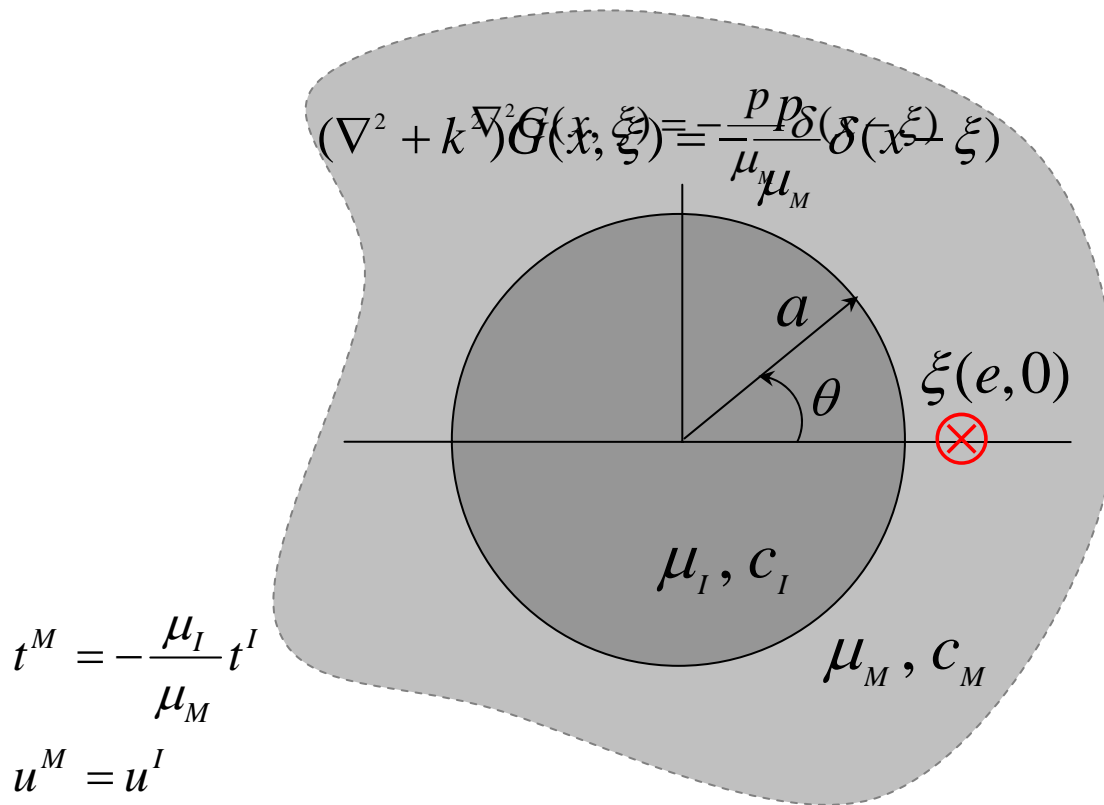
$\beta = 0$ (cavity)



$\beta = 10^{-32}$

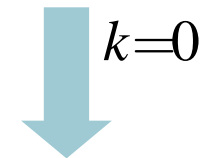


Parameter study ($k = 0$) for ideal bonding



Fundamental solution

$$U(s, x) = -i\pi H_0^{(1)}(kr)/2$$



$$U(s, x) = \ln|x - s| = \ln r$$

$$\mu_I = 4\mu_M$$

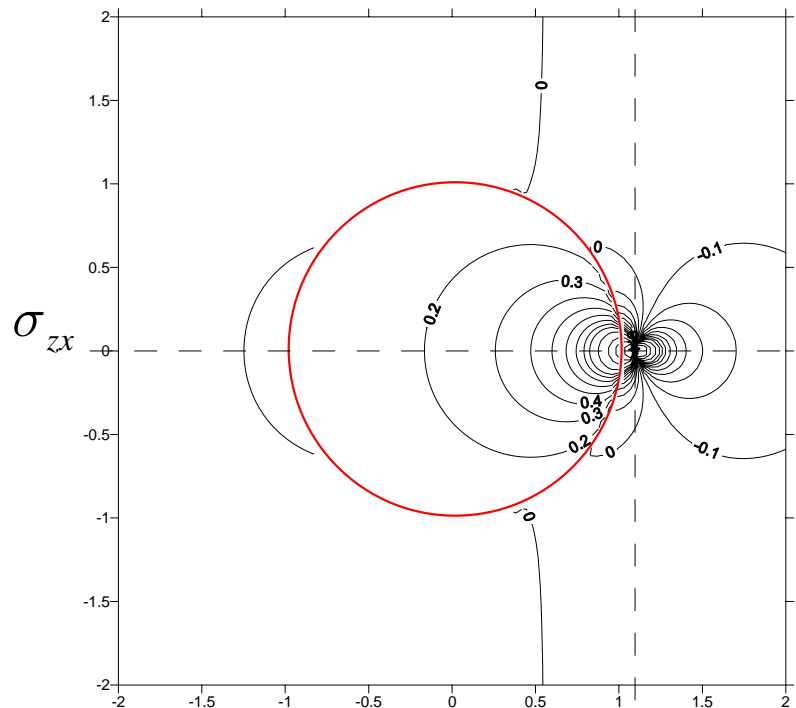
μ is the shear modulus

β is the imperfect interface parameter



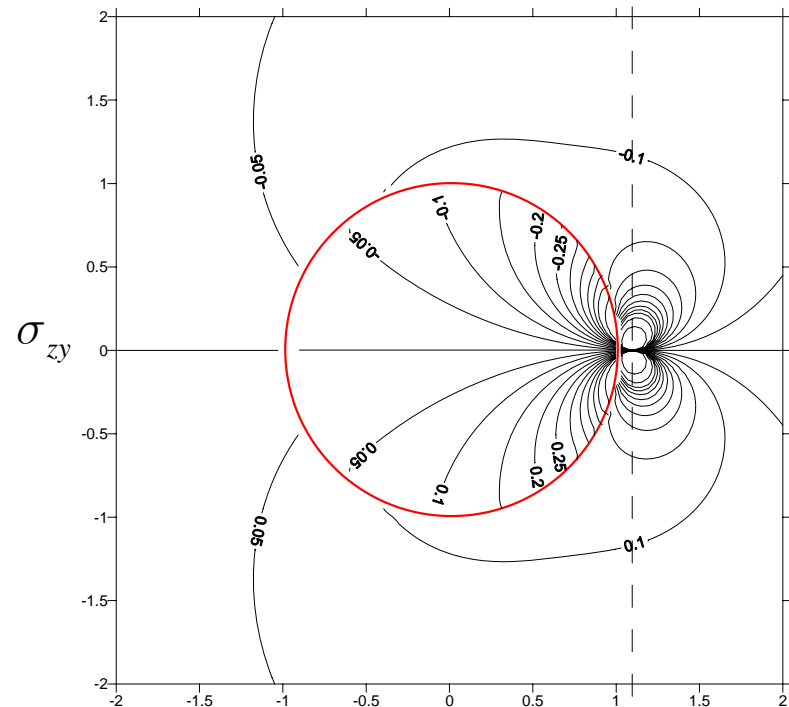
Stress contours of σ_{zx} and σ_{zy} for the static solutions (a concentrated force in the matrix)

$$\sigma_{zx} = \sigma_{zr} \cos \phi - \sigma_{z\theta} \sin \phi$$



$k = 0$, ideal bonding

$$\sigma_{zy} = \sigma_{zr} \sin \phi + \sigma_{z\theta} \cos \phi$$

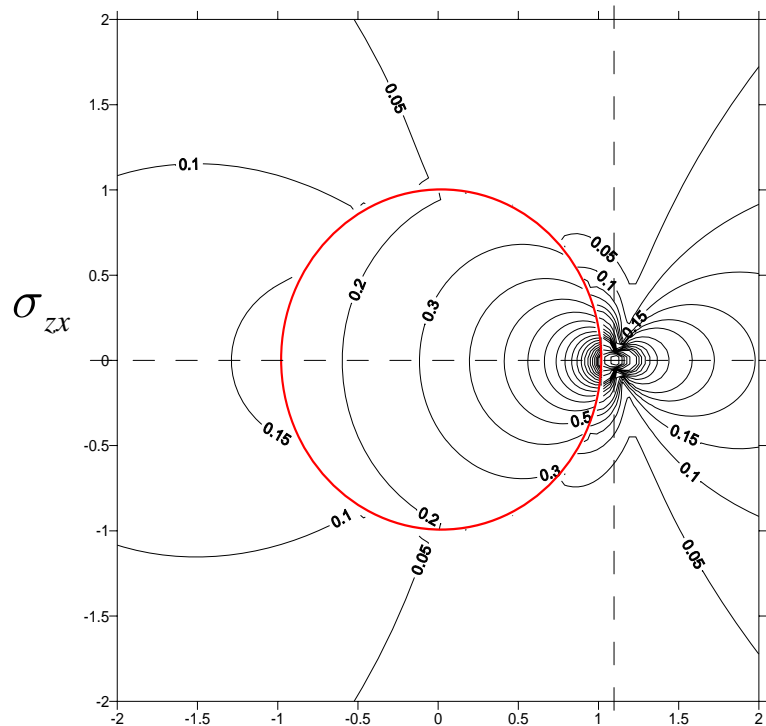


$k = 0$, ideal bonding



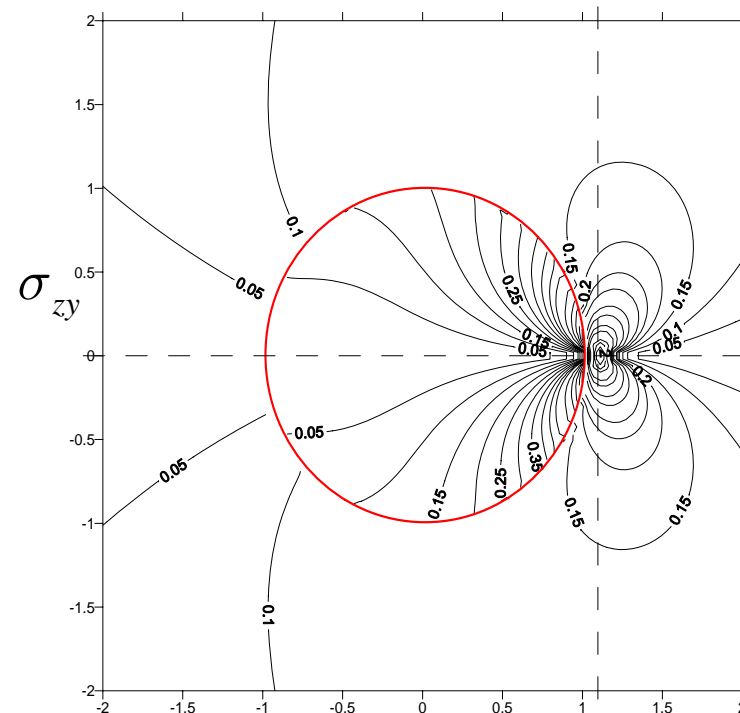
Stress contours of σ_{zx} and σ_{zy} for the dynamic solutions (a concentrated force in the matrix)

$$\sigma_{zx} = \sigma_{zr} \cos \phi - \sigma_{z\theta} \sin \phi$$



$$k_I = 1, k_M = 2, \beta = 10^{32} \text{ (ideal bonding)}$$

$$\sigma_{zy} = \sigma_{zr} \sin \phi + \sigma_{z\theta} \cos \phi$$

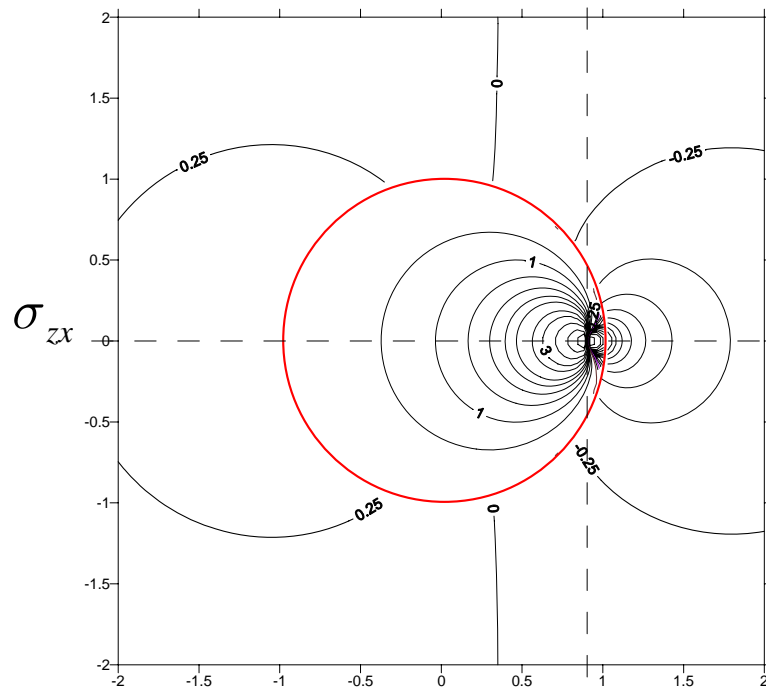


$$k_I = 1, k_M = 2, \beta = 10^{32} \text{ (ideal bonding)}$$



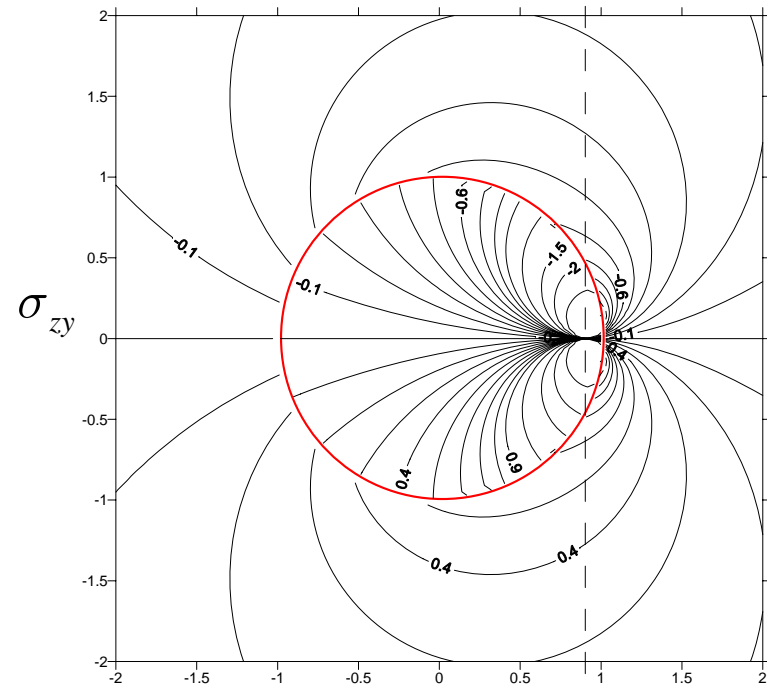
Stress contours of σ_{zx} and σ_{zy} for the static solutions (a concentrated force in the inclusion)

$$\sigma_{zx} = \sigma_{zr} \cos \phi - \sigma_{z\theta} \sin \phi$$



$k = 0$, ideal bonding

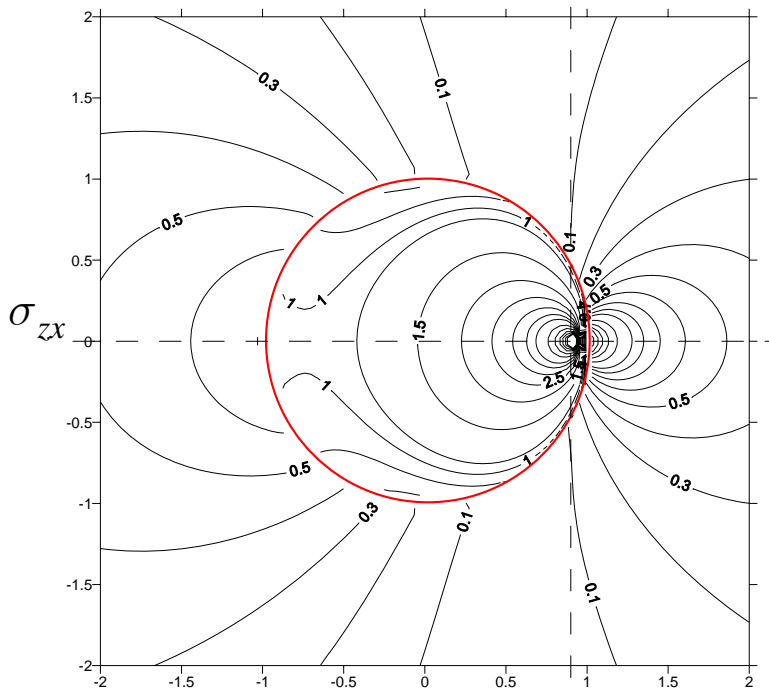
$$\sigma_{zy} = \sigma_{zr} \sin \phi + \sigma_{z\theta} \cos \phi$$



$k = 0$, ideal bonding

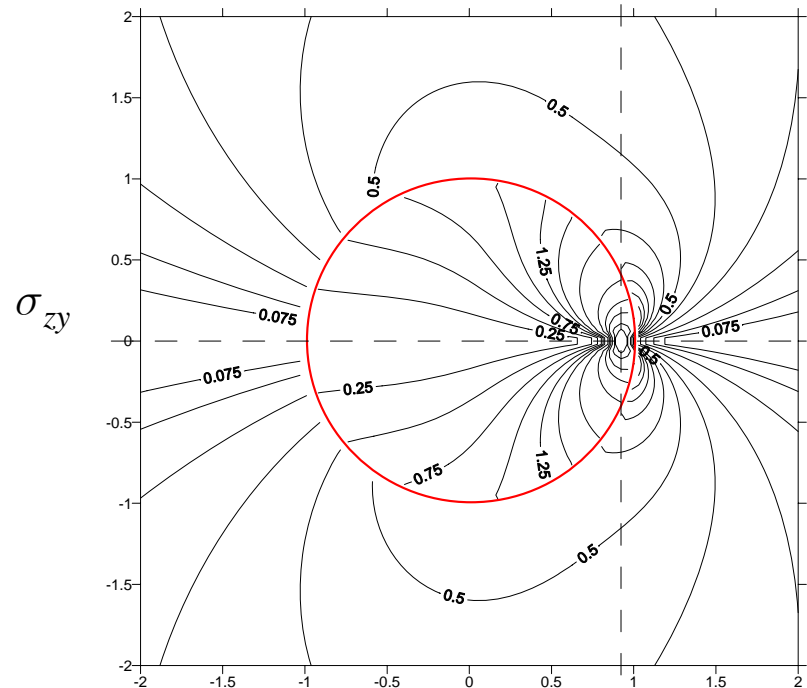
Stress contours of σ_{zx} and σ_{zy} for the **dynamic solutions** (a concentrated force in the inclusion)

$$\sigma_{zx} = \sigma_{zr} \cos \phi - \sigma_{z\theta} \sin \phi$$



$$k_I = 1, k_M = 2, \beta = 10^{32} \text{ (ideal bonding)}$$

$$\sigma_{zy} = \sigma_{zr} \sin \phi + \sigma_{z\theta} \cos \phi$$



$$k_I = 1, k_M = 2, \beta = 10^{32} \text{ (ideal bonding)}$$

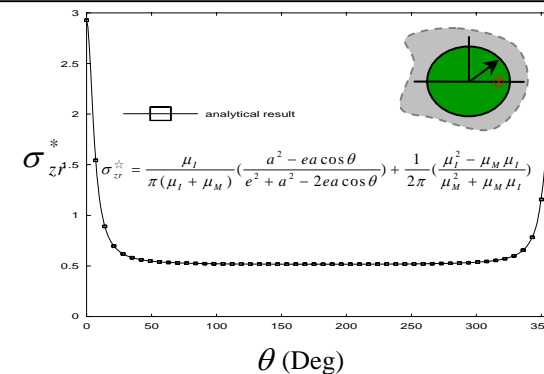
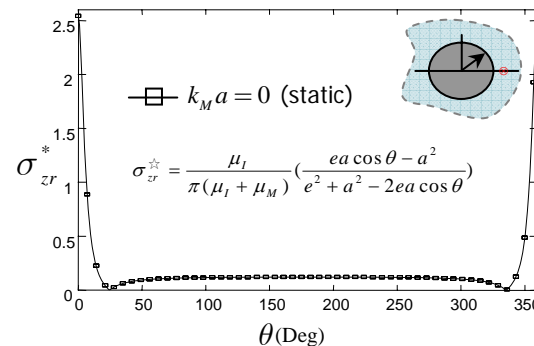
Series-form & closed-form solutions for the static case (ideally bonded interface)

$$\sigma_{zr}^{\star} = a\sigma_{zr}^I / p = a\sigma_{zr}^M / p$$

Concentrated force in the matrix

Concentrated force in the inclusion

Stress distribution along the interface



Closed-form solution

$$\sigma_{zr}^{\star} = \frac{\mu_I}{\pi(\mu_I + \mu_M)} \left(\frac{ea \cos \theta - a^2}{e^2 + a^2 - 2ea \cos \theta} \right)$$

$$\sigma_{zr}^{\star} = \frac{\mu_I}{\pi(\mu_I + \mu_M)} \left(\frac{a^2 - ea \cos \theta}{e^2 + a^2 - 2ea \cos \theta} \right) + \frac{1}{2\pi} \left(\frac{\mu_I^2 - \mu_M \mu_I}{\mu_M^2 + \mu_M \mu_I} \right)$$

Fourier series
(Poisson integral formula)

(easy)
↓
(not easy)

Series-form solution

$$\sigma_{zr}^{\star} = \frac{\mu_I}{\pi(\mu_I + \mu_M)} \sum_{m=1}^{\infty} \left(\frac{a}{e} \right)^m \cos m\theta$$

$$\sigma_{zr}^{\star} = \frac{\mu_I}{2\pi\mu_M} + \frac{\mu_I}{\pi(\mu_I + \mu_M)} \sum_{m=1}^{\infty} \left(\frac{e}{a} \right)^m \cos m\theta$$

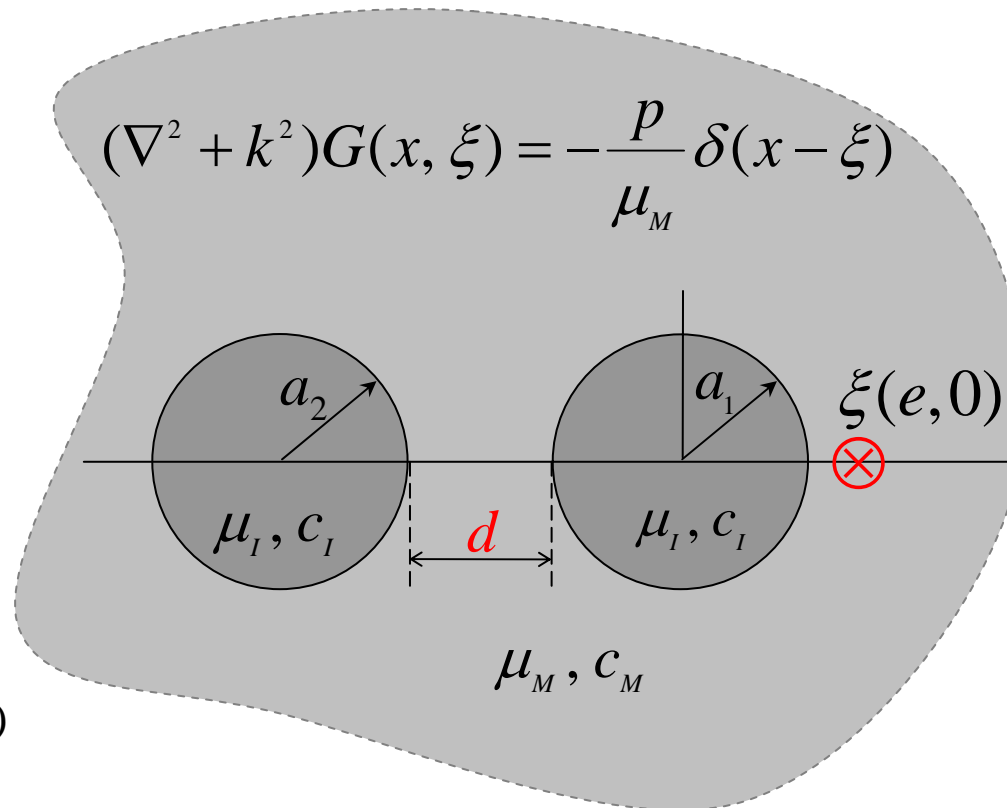




Numerical examples

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An infinite matrix containing **two circular inclusions** with a concentrated force at ξ in the matrix



$$t^M = -\frac{\mu_I}{\mu_M} t^I$$

$$t^I = \frac{\beta}{\mu_I} (u^M - u^I)$$

$$\mu_I = 4\mu_M \quad c_I = 2c_M$$

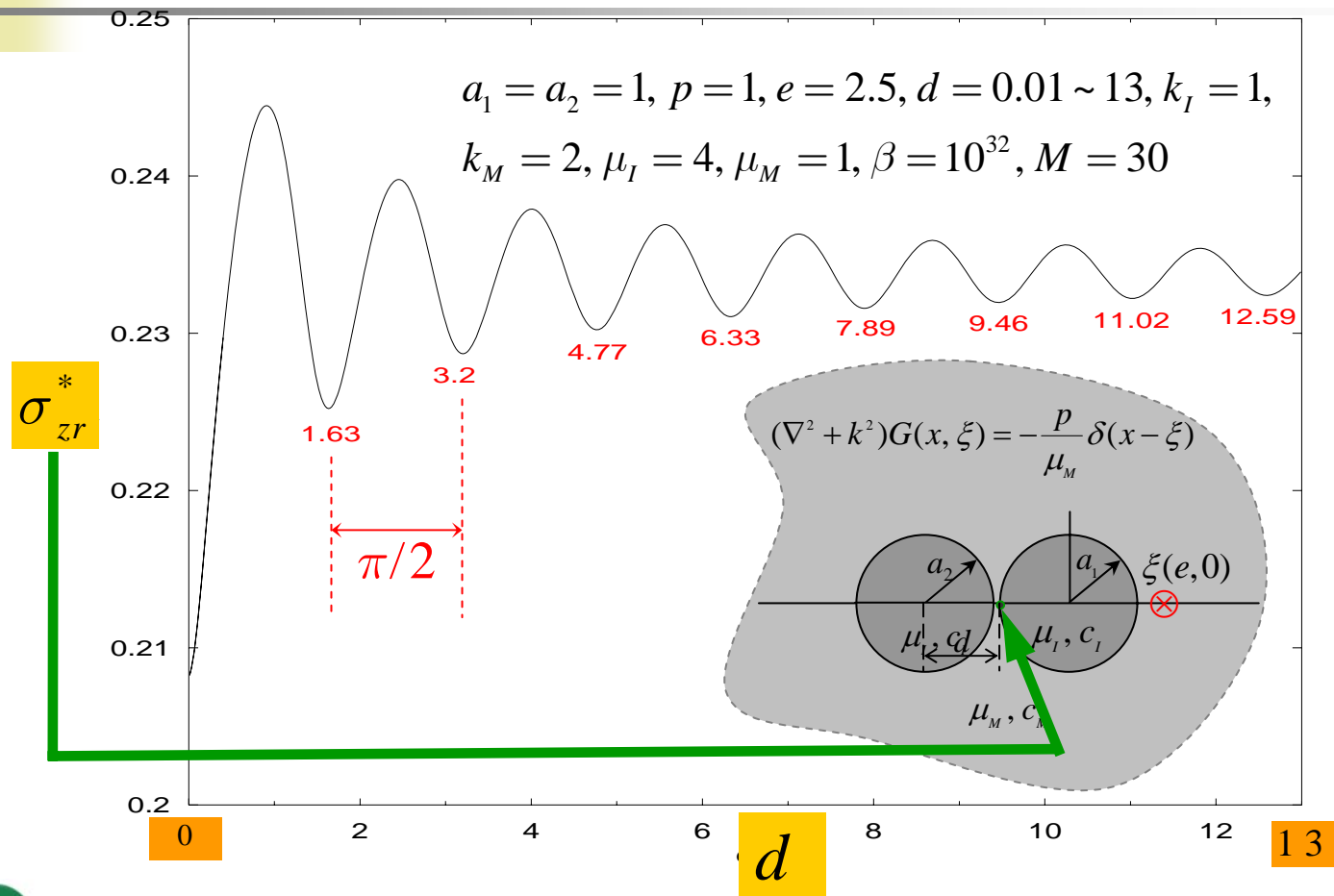
μ is the shear modulus

c is the wave speed

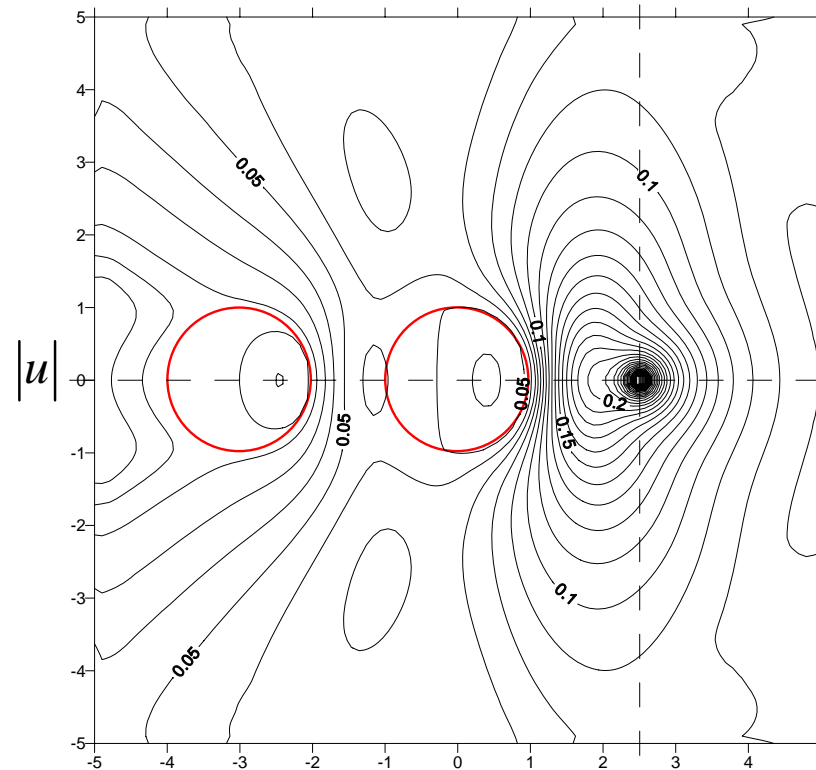
β is the imperfect interface parameter



Distribution of σ_{zr}^* of the matrix at the position of d various (a_1, π)



The contour of the displacement for an infinite matrix containing **two inclusions** with a concentrated force at ξ in the matrix for ideal bonding



Potential contour using the present method (M=30)

National Taiwan Ocean University
Department of Harbor and River Engineering





Outlines

- **Motivation and literature review**
- **Derivation of the Green's function**
 - Expansions of fundamental solution and boundary density
 - Adaptive observer system
 - Vector decomposition technique
 - Linear algebraic equation
 - Take free body
 - Image technique for solving half-plane problems
- **Numerical examples**
 - Green's function for Laplace problems
 - Green's function for Helmholtz problems
- **Conclusions**





Conclusions

- After introducing the degenerate kernel, the BIE is nothing more than the linear algebra.
- We derived the analytic Green's function for one inclusion problem by using the null-field integral equation. Also, the present approach can be utilized to construct semi-analytic Green's functions for several circular inclusions.




Conclusions

- Several examples, Laplace and Helmholtz problems were demonstrated to check the validity of the **present formulation** and **the results match well** with available solutions in the literature.
- A general-purpose program for deriving the Green's function of Laplace or Helmholtz problems **with arbitrary number of circular apertures and/or inclusions of arbitrary radii and various positions involving Dirichlet or Neumann or mixed** boundary condition was developed.



Further studies

- The imperfect circular interface is homogeneous  nonhomogeneous.
 $\beta \rightarrow \beta(\theta)$
- According to our successful experiences for half-plane problems, it is straightforward to quarter-plane problems.



The end

Thanks for your attentions.

You can get more information on our website.

<http://msvlab.hre.ntou.edu.tw>

