

Null-field integral equation approach for boundary value problems with circular boundaries

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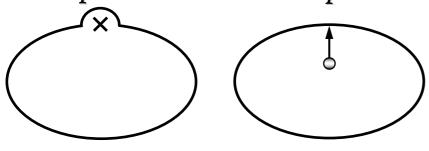
- Motivation and literature review
- Mathematical formulation
- Expansions of fundamental solution and boundary density
- Adaptive observer system
- Vector decomposition technique
- Linear algebraic equation
- Numerical examples
- Conclusions



Motivation and literature review

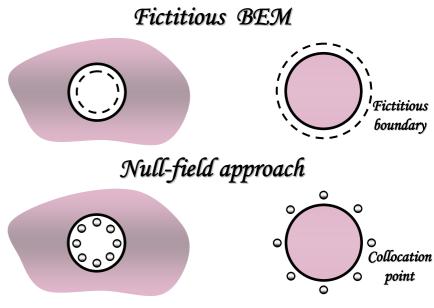
BEM/BIEM Improper integral Singular and hypersingular Regular Limit process

Bump contour



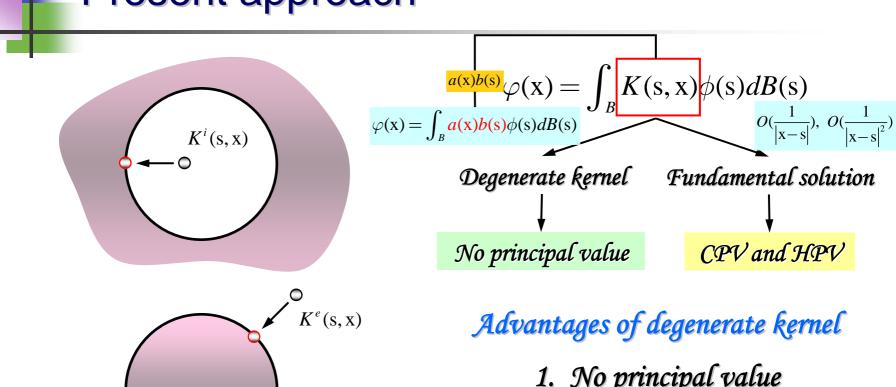
CPV and HPV





Present approach

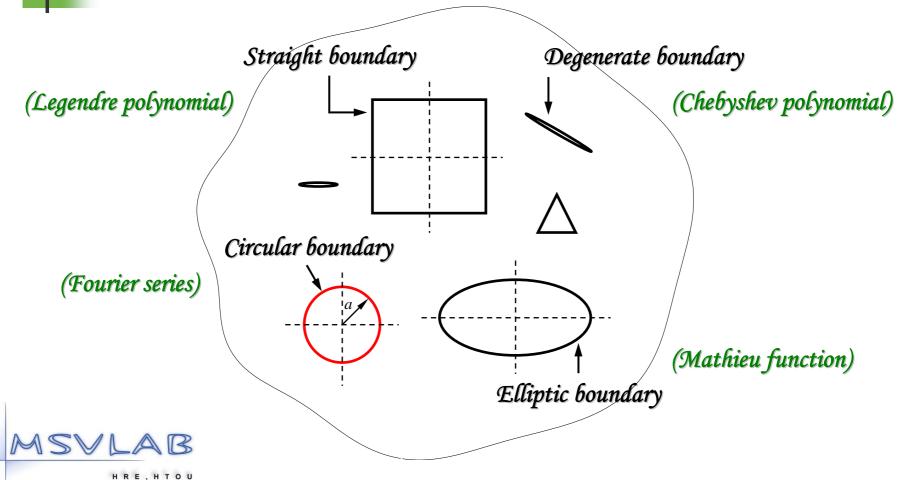
HRE, HTOU



- 1. No principal value
- 2. Well-posed
- 3. No boundary-layer effect
- 4. Exponetial convergence



Engineering problem with arbitrary geometries





Motivation and literature review

Analytical methods for solving Laplace problems with circular holes

Conformal mapping

Chen and Weng, 2001, "Torsion of a circular compound bar with imperfect interface", ASME Journal of Applied Mechanics

Bipolar coordinate

Lebedev, Skalskaya and Uyand, 1979, "Work problem in applied mathematics", Dover Publications

Special solution

Honein, Honein and Hermann, 1992, "On two circular inclusions in harmonic problem", Quarterly of Applied Mathematics



Limited to doubly connected domain



Fourier series approximation

- Ling (1943) torsion of a circular tube
- Caulk et al. (1983) steady heat conduction with circular holes
- Bird and Steele (1992) harmonic and biharmonic problems with circular holes
- Mogilevskaya et al. (2002) elasticity problems with circular boundaries





Contribution and goal

- However, they didn't employ the null-field integral equation and degenerate kernels to fully capture the circular boundary, although they all employed Fourier series expansion.
- To develop a systematic approach for solving Laplace problems with multiple holes is our goal.

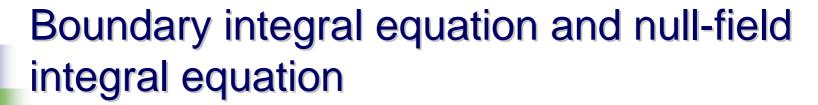




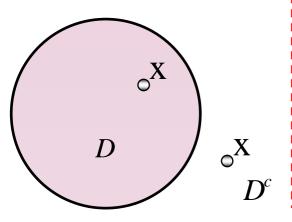
Outlines (Direct problem)

- Motivation and literature review
- Mathematical formulation
- Expansions of fundamental solution and boundary density
- Adaptive observer system
- Vector decomposition technique
- Linear algebraic equation
- Numerical examples
- Conclusions

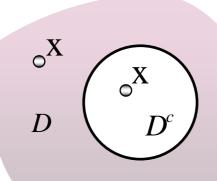




Interior case



Exterior case



$$U(s,x) = \ln|x-s| = \ln r$$

$$T(s,x) = \frac{\partial U(s,x)}{\partial \mathbf{n}_{s}}$$

$$t(s) = \frac{\partial u(s)}{\partial \mathbf{n}_{s}}$$

$$2\pi u(\mathbf{x}) = \int_{B} T(\mathbf{s}, \mathbf{x}) u(\mathbf{s}) dB(\mathbf{s}) - \int_{B} U(\mathbf{s}, \mathbf{x}) t(\mathbf{s}) dB(\mathbf{s}), \ \mathbf{x} \in D$$

$$0 = \int_{B} T(s, x)u(s)dB(s) - \int_{B} U(s, x)t(s)dB(s), x \in D^{c}$$

MSVLAB Null-field integral equation



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- Linear algebraic equation
- Numerical examples
- Degenerate scale
- Conclusions





Expansions of fundamental solution and boundary density

Degenerate kernel - fundamental solution

$$U(\mathbf{s}, \mathbf{x}) = \begin{cases} U^{i}(R, \theta; \rho, \phi) = \ln R - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R}\right)^{m} \cos m(\theta - \phi), & R \ge \rho \\ U^{e}(R, \theta; \rho, \phi) = \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R}{\rho}\right)^{m} \cos m(\theta - \phi), & \rho > R \end{cases}$$

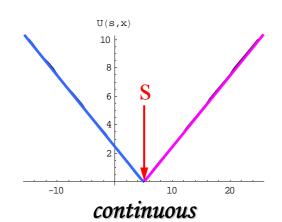
Fourier series expansions - boundary density

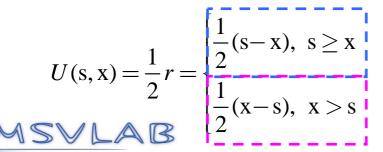
$$u(s) = a_0 + \sum_{n=1}^{M} (a_n \cos n\theta + b_n \sin n\theta), \ s \in B$$

$$t(s) = p_0 + \sum_{n=1}^{M} (p_n \cos n\theta + q_n \sin n\theta), \ s \in B$$

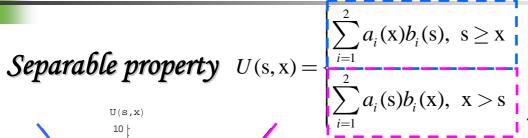


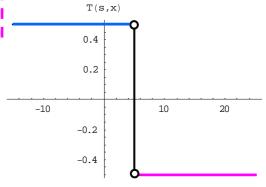
Separable form of fundamental solution





HRE, HTOU





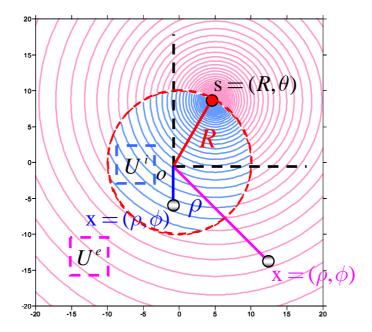
discontinuous

$$T(s, x) = \begin{cases} \frac{1}{2}, & s > x \\ \frac{-1}{2}, & x > s \end{cases}$$



Separable form of fundamental solution (2D)

$$U(s,x) = \begin{cases} U^{i}(R,\theta;\rho,\phi) = \ln R - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{\rho}{R}\right)^{m} \cos m(\theta - \phi), & R \ge \rho \\ U^{e}(R,\theta;\rho,\phi) = \ln \rho - \sum_{m=1}^{\infty} \frac{1}{m} \left(\frac{R}{\rho}\right)^{m} \cos m(\theta - \phi), & \rho > R \end{cases}$$



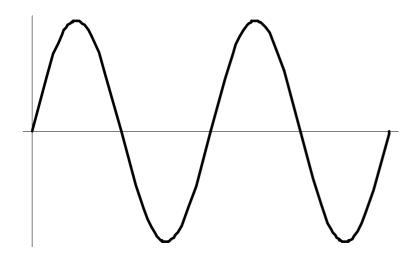




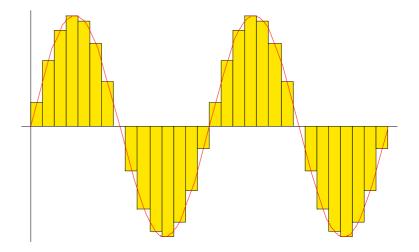
Boundary density discretization

Fourier series

Ex. constant element



Present method



Conventional BEM



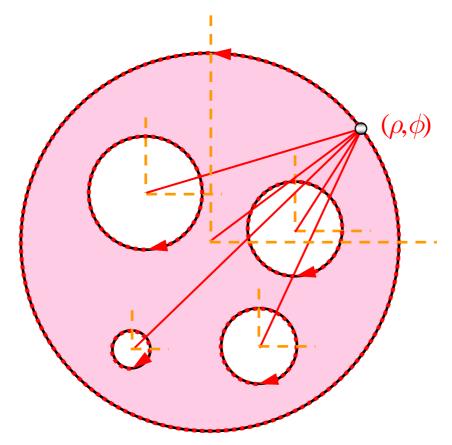
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Adaptive observer system





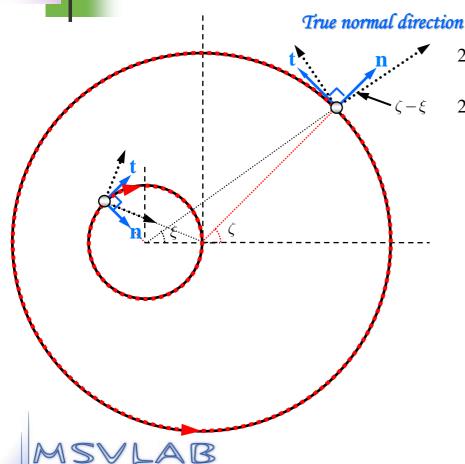
 \circ collocation point

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Vector decomposition technique for potential gradient



$$2\pi \frac{\partial u(\mathbf{x})}{\partial \mathbf{n}} = \int_{B} M_{\rho}(\mathbf{s}, \mathbf{x}) u(\mathbf{s}) dB(\mathbf{s}) - \int_{B} L_{\rho}(\mathbf{s}, \mathbf{x}) t(\mathbf{s}) dB(\mathbf{s}), \ \mathbf{x} \in D$$

$$\zeta - \xi \qquad 2\pi \frac{\partial u(\mathbf{x})}{\partial \mathbf{t}} = \int_{B} M_{\phi}(\mathbf{s}, \mathbf{x}) u(\mathbf{s}) dB(\mathbf{s}) - \int_{B} L_{\phi}(\mathbf{s}, \mathbf{x}) t(\mathbf{s}) dB(\mathbf{s}), \ \mathbf{x} \in D$$

$$2\pi \frac{\partial u(\mathbf{x})}{\partial \mathbf{t}} = \int_{B} M_{\phi}(\mathbf{s}, \mathbf{x}) u(\mathbf{s}) dB(\mathbf{s}) - \int_{B} L_{\phi}(\mathbf{s}, \mathbf{x}) t(\mathbf{s}) dB(\mathbf{s}), \ \mathbf{x} \in L$$

Non-concentric case:

$$L_{\rho}(\mathbf{s}, \mathbf{x}) = \frac{\partial U(\mathbf{s}, \mathbf{x})}{\partial \rho} \cos(\zeta - \xi) + \frac{1}{\rho} \frac{\partial U(\mathbf{s}, \mathbf{x})}{\partial \phi} \cos(\frac{\pi}{2} - \zeta + \xi)$$

$$M_{\rho}(\mathbf{s}, \mathbf{x}) = \frac{\partial T(\mathbf{s}, \mathbf{x})}{\partial \rho} \cos(\zeta - \xi) + \frac{1}{\rho} \frac{\partial T(\mathbf{s}, \mathbf{x})}{\partial \phi} \cos(\frac{\pi}{2} - \zeta + \xi)$$

Special case (concentric case): $\zeta = \xi$

$$L_{\rho}(\mathbf{s}, \mathbf{x}) = \frac{\partial U(\mathbf{s}, \mathbf{x})}{\partial \rho} \qquad M_{\rho}(\mathbf{s}, \mathbf{x}) = \frac{\partial T(\mathbf{s}, \mathbf{x})}{\partial \rho}$$

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Linear algebraic equation

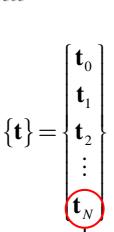
$$[U]\{t\}\!=\![T]\{u\}$$

where

Index of collocation circle

$$\begin{bmatrix} \mathbf{U}_{00} & \mathbf{U}_{01} & \cdots & \mathbf{U}_{0N} \\ \mathbf{U}_{10} & \mathbf{U}_{11} & \cdots & \mathbf{U}_{1N} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{U}_{N0} & \mathbf{U}_{N1} & \cdots & \mathbf{U}_{NN} \end{bmatrix}$$

Index of routing circle -

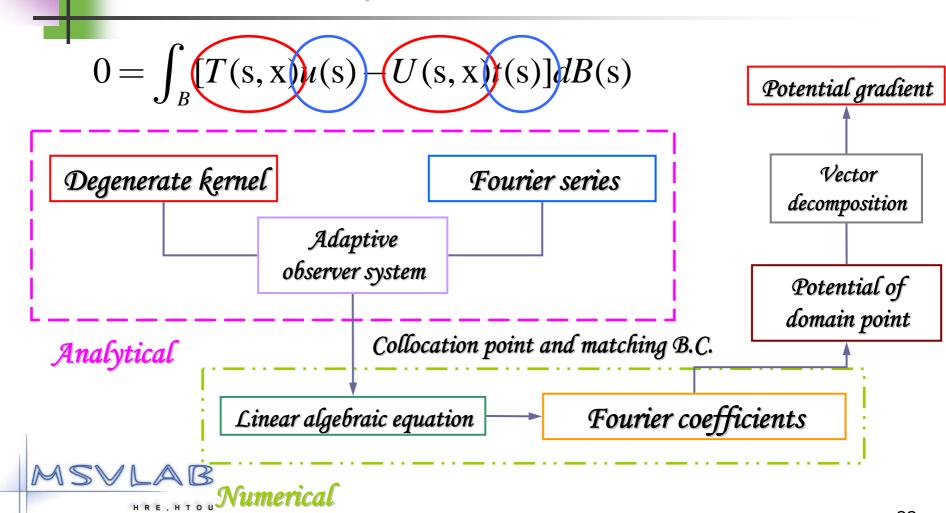


Column vector of Fourier coefficients
(Nth routing circle)



HRE, HTOU

Flowchart of present method



Comparisons of conventional BEM and the present method

	Boundary				
	density	Auxiliary	Formulation	Observer	Singularity
	discretization	system		system	
	Constant,		Boundary	Fixed	
Conventional	Linear,	Fundamental	integral	observer	CPV, RPV
BEM	(Algebraic	solution	equation	system	and HPV
	Convergence)				
	Fourier series		Null-field	Adaptive	No
Present	Expansion	Degenerate	integral	observer	principal
method	Exponential	kernel	equation	system	value
н к в , н	.Convergence)				2

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Numerical examples

- Laplace equation (EABE 2005, CMES 2005)
- Eigen problem
- Exterior acoustics
- Biharmonic equation (JAM, ASME 2005)



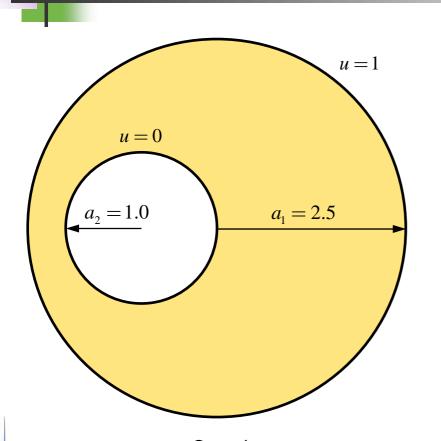


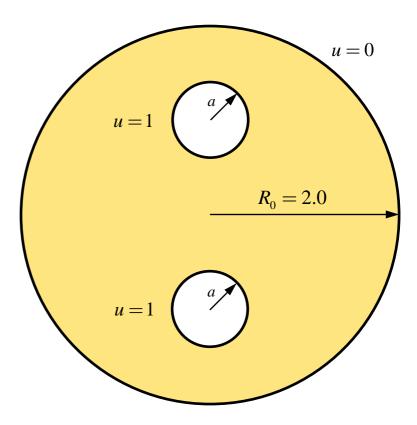
Laplace equation

- Steady state heat conduction problems
- Electrostatic potential of wires
- Flow of an ideal fluid pass cylinders
- A circular bar under torque
- An infinite medium under antiplane shear
- Half-plane problems



Steady state heat conduction problems

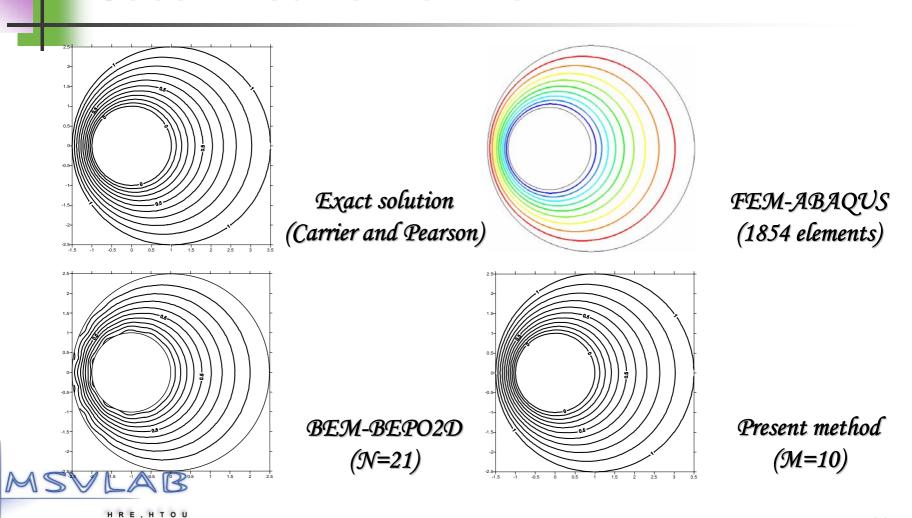




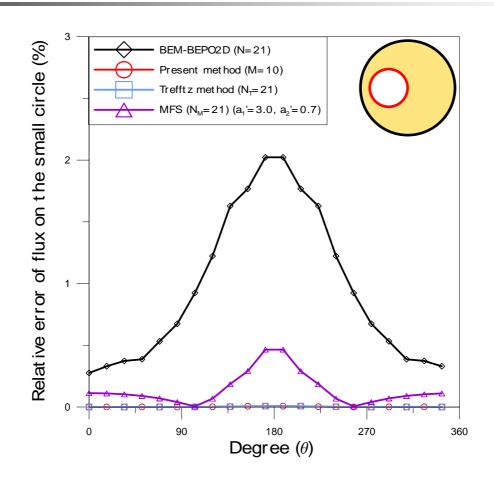
Case 2

HRE, HTOU

Case 1: Isothermal line

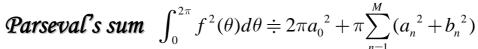


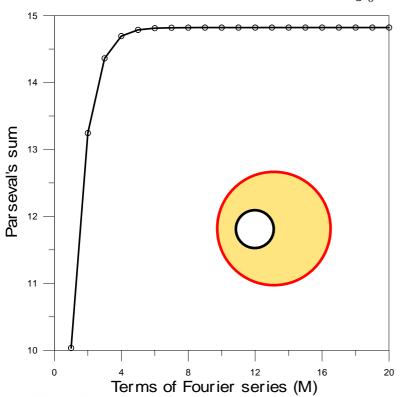
Relative error of flux on the small circle

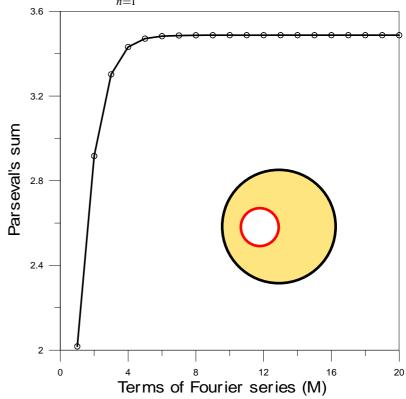




Convergence test - Parseval's sum for Fourier coefficients









HRE, HTOU

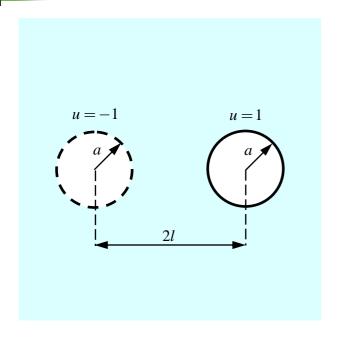


Laplace equation

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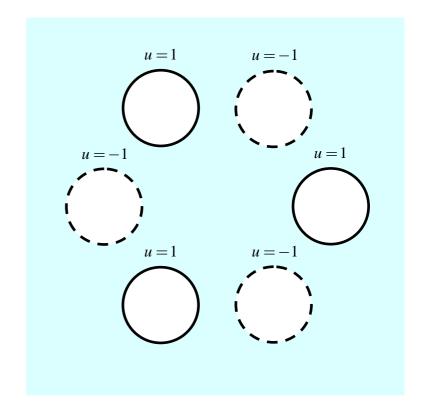


Electrostatic potential of wires



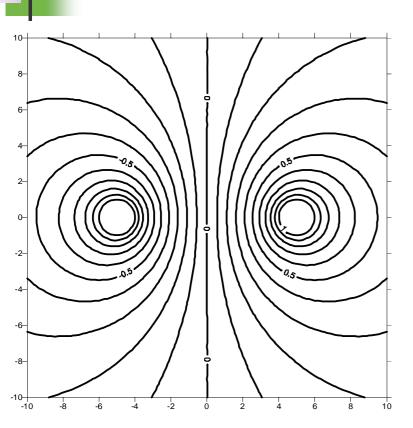
Two parallel cylinders held positive and negative potentials

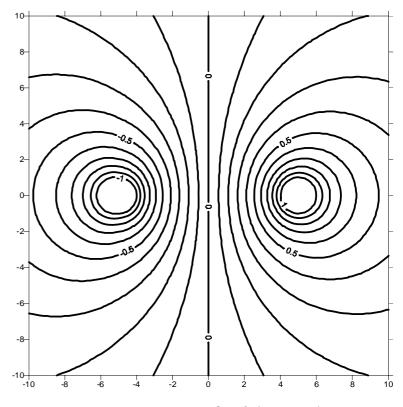




Hexagonal electrostatic potential

Contour plot of potential





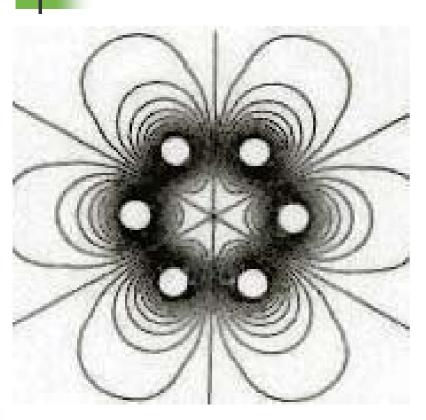
Exact solution (Lebedev et al.)

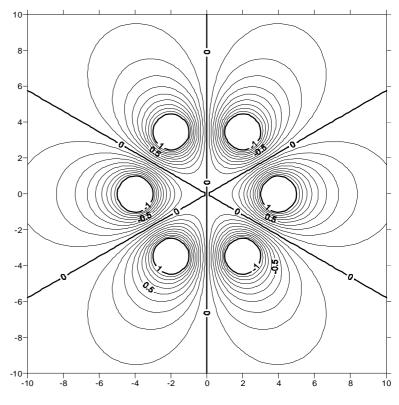
Present method (M=10)

HRE, HTOU



Contour plot of potential





Present method (M=10)

MSV Onishi's data (1991)

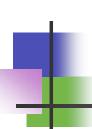
HRE, HTOU



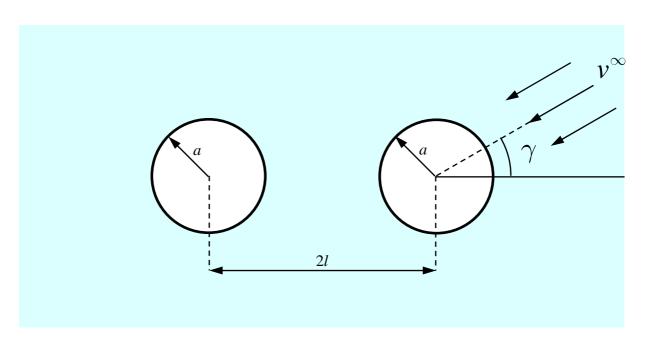
Laplace equation

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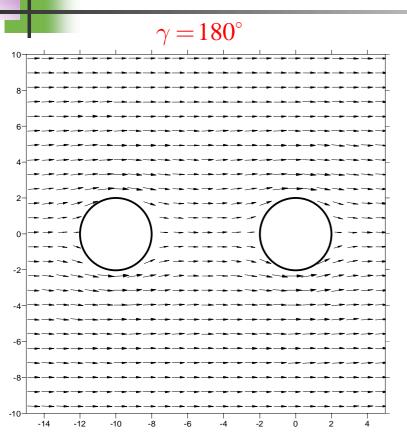
Flow of an ideal fluid pass two parallel cylinders

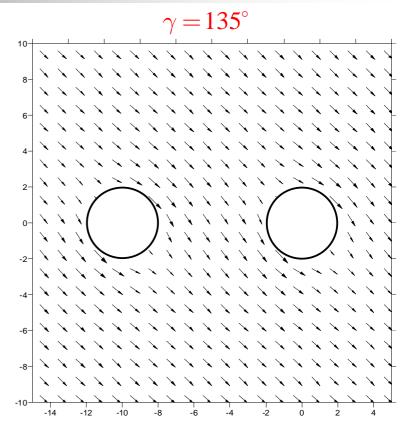


 v^{∞} is the velocity of flow far from the cylinders γ is the incident angle



Velocity field in different incident angle





Present method (M=10)

Present method (M=10)

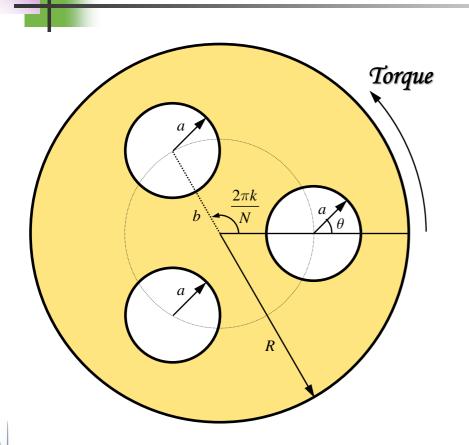


Laplace equation

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The warping function φ

$$\nabla^2 \varphi(x) = 0, \ x \in D$$

Boundary condition

$$\frac{\partial \varphi}{\partial n} = x_k \sin \theta_k - y_k \cos \theta_k \quad on \quad B_k$$

where

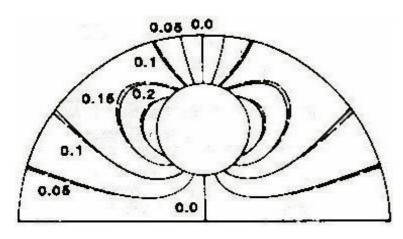
$$x_i = b\cos\frac{2\pi i}{N}, \ y_i = b\sin\frac{2\pi i}{N}$$



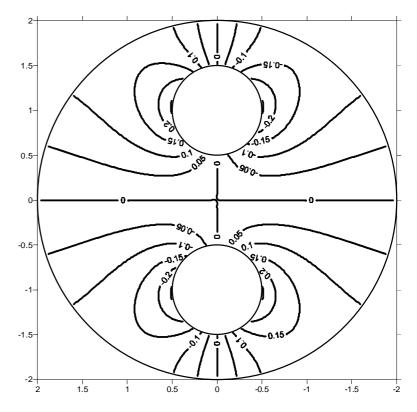


Axial displacement with two circular holes

Dashed line: exact solution Solid line: first-order solution



Caulk's data (1983)
ASME Journal of Applied Mechanics



Present method (M=10)



Torsional rigidity

	Case			
		N = 2, c/R = 0 a/R = 2/7, b/R = 3/7	N = 2, c/R = 1/5 a/R = 1/5, b/R = 3/5	N = 6, c/R = 1/5 a/R = 1/5, b/R = 3/5
$\frac{2G}{\left(\mu\pi R^4\right)}$	Caulk(First-order approximate)	0.8739	0.8741	0.7261
	Exact BIE formulation	0.8713	0.8732	0.7261
	Ling's results	0.8809	0.8093	0.7305
	The present method	0.8712	0.8732	0.7245



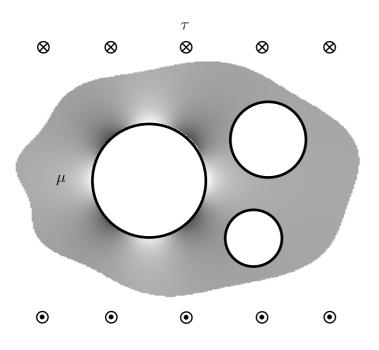


Laplace equation

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Infinite medium under antiplane shear



The displacement w^s

$$\nabla^2 w^s(x) = 0, \ x \in D$$

Boundary condition

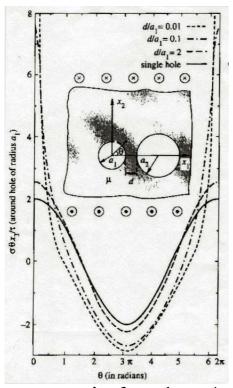
$$\frac{\partial w^{s}(x)}{\partial n} = \frac{\tau}{\mu} \sin \theta \quad \mathbf{on} \quad \mathbf{B}_{k}$$

Total displacement

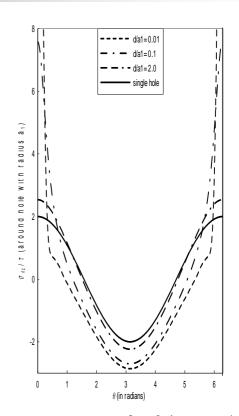
$$w = w^s + w^{\infty}$$







Honein's data (1992)
Quarterly of Applied Mathematics



Present method (M=20)

Ĺ

Shear stress $\sigma_{z\theta}$ around the hole of radius a_1

Stress approach

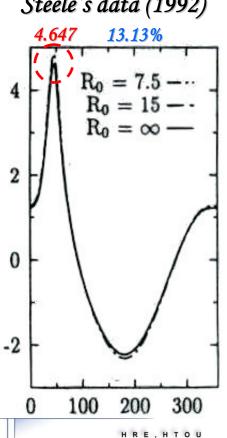
Analytical

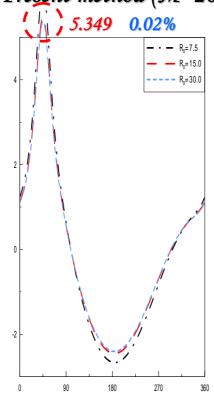
Displacement approach

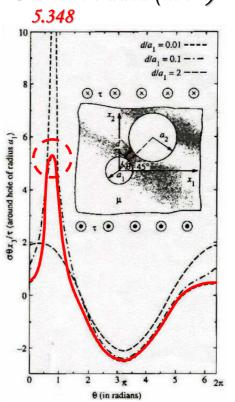
Steele's data (1992) Present method (M=20)

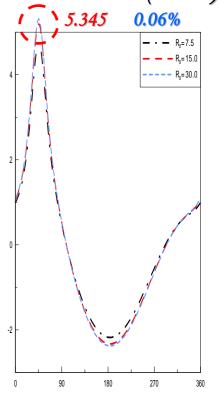
Honein's data (1992)

Present method (M=20)









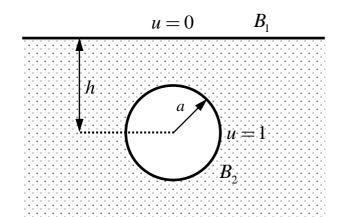


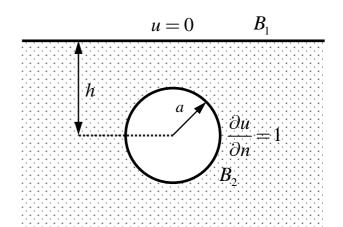
Laplace equation

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Half-plane problems





Dirichlet boundary condition (Lebedev et al.)

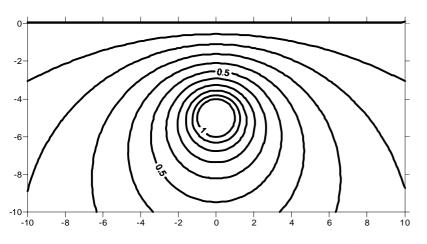
Mixed-type boundary condition (Lebedev et al.)



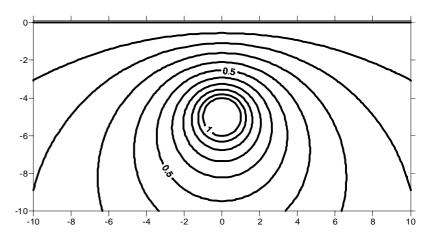


Dirichlet problem

Isothermal line



Exact solution (Lebedev et al.)



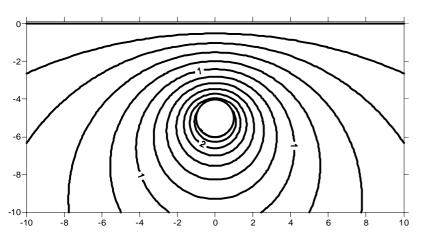
Present method (M=10)



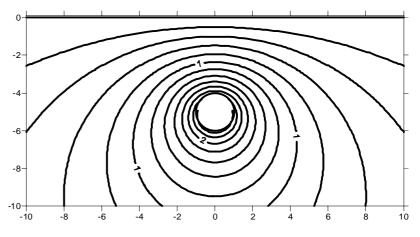


Mixed-type problem

Isothermal line



Exact solution (Lebedev et al.)



Present method (M=10)





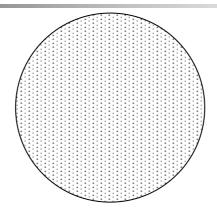
Numerical examples

- Laplace equation
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- Exterior acoustics
- Biharmonic equation

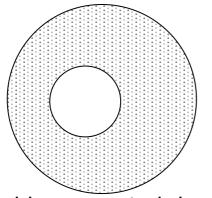


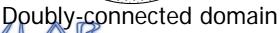


Problem statement

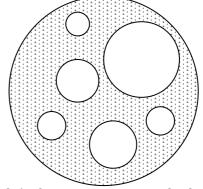


Simply-connected domain





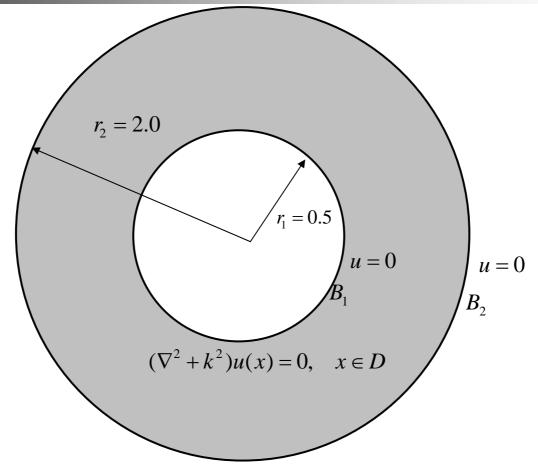
HRE, HTOU



Multiply-connected domain



Example 1

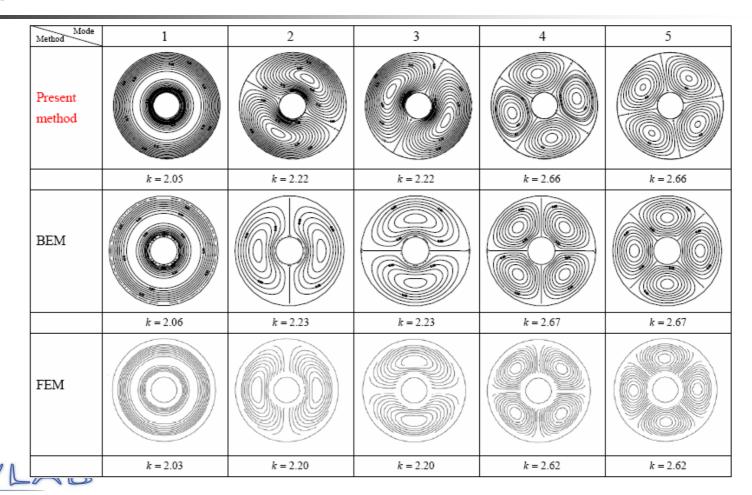




The former five true eigenvalues by using different approaches

	k_1	k_2	k_3	k_4	k_5
FEM (ABAQUS)	2.03	2.20	2.62	3.15	3.71
BEM (Burton & Miller)	2.06	2.23	2.67	3.22	3.81
BEM (CHIEF)	2.05	2,23	2.67	3.22	3.81
BEM (null-field)	2.04	2.20	2.65	3.21	3.80
BEM (fictitious)	2.04	2.21	2.66	3.21	3.80
Present method	2.05	2,22	2.66	3.21	3.80
Analytical solution[19]	2.05	2.23	2.66	3.21	3.80

The former five eigenmodes by using present method, FEM and BEM





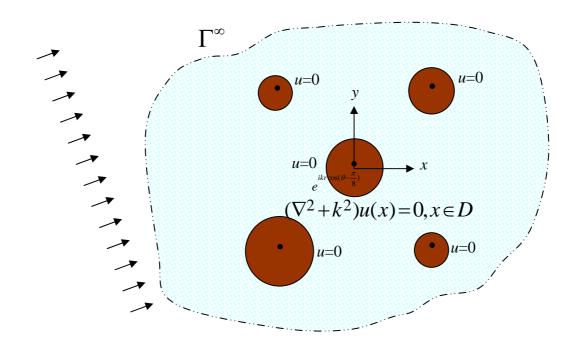
Numerical examples

- Laplace equation
- Eigen problem
- Exterior acoustics
- Biharmonic equation



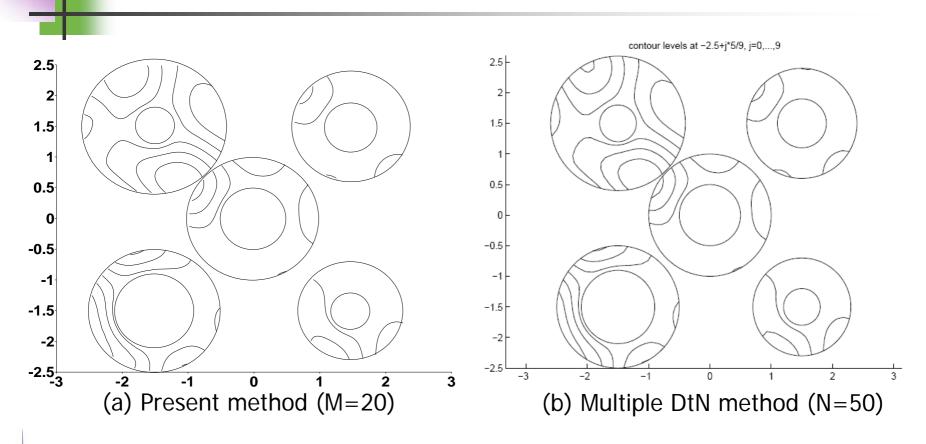


Sketch of the scattering problem (Dirichlet condition) for five cylinders



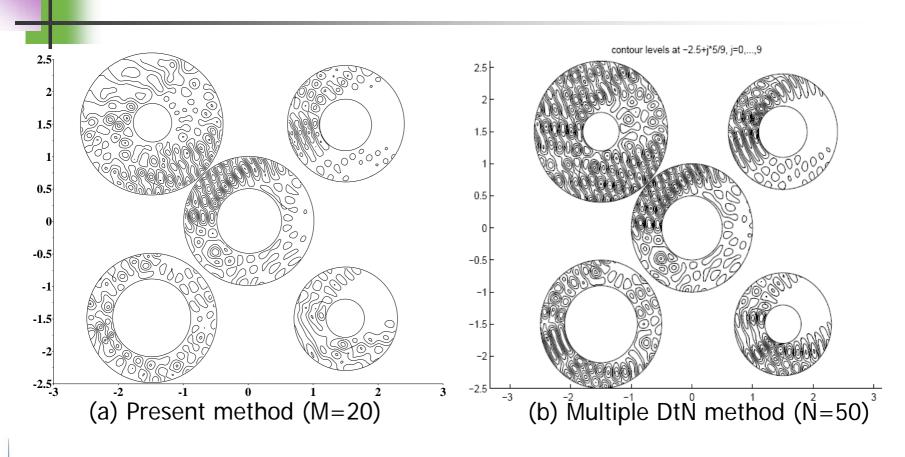


The contour plot of the real-part solutions of total field for $k = \pi$



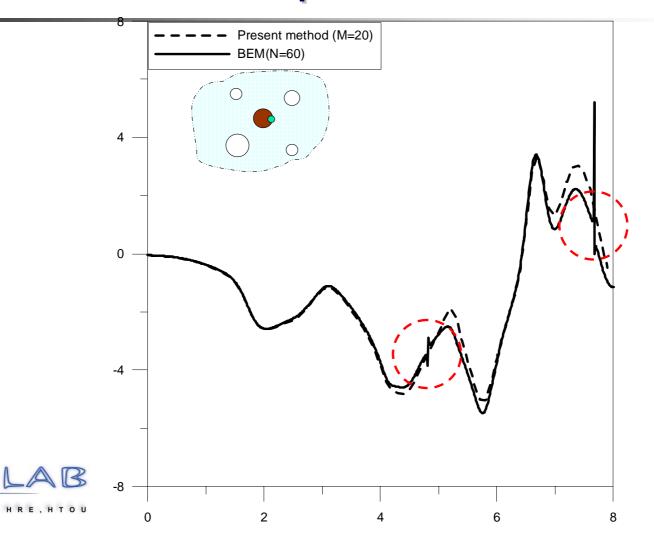


The contour plot of the real-part solutions of total field for $k = 8\pi$





Fictitious frequencies





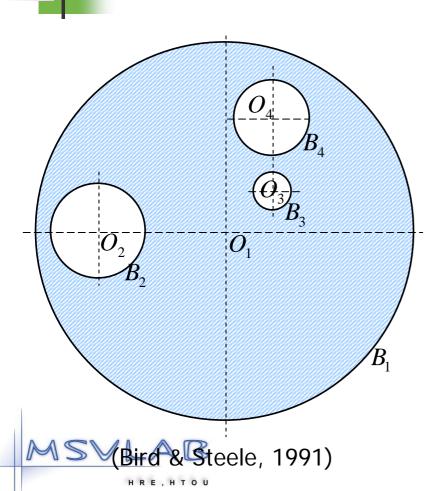
Numerical examples

- Laplace equation
- Eigen problem
- Exterior acoustics
- Biharmonic equation





Plate problems



Geometric data:

$$O_1 = (0,0), R_1 = 20; O_2 = (-14,0), R_2 = 5;$$

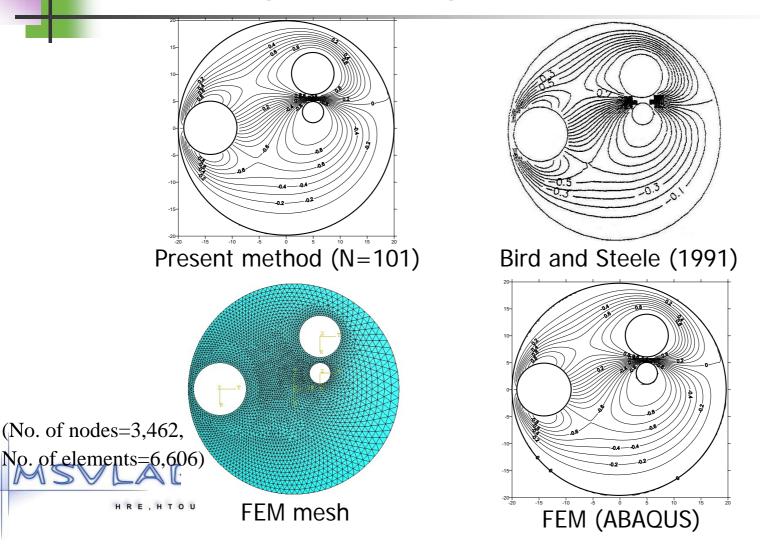
 $O_3 = (5,3), R_3 = 2; O_4 = (5,10), R_4 = 4.$

Essential boundary conditions:

$$u(s) = 0$$
 and $\theta(s) = 0$ on B_1
 $u(s) = \sin \theta$ and $\theta(s) = 0$ on B_2
 $u(s) = -1$ and $\theta(s) = 0$ on B_3

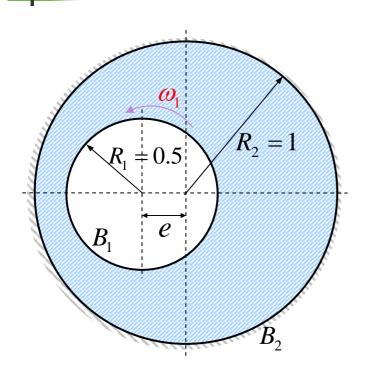
u(s) = 1 and $\theta(s) = 0$ on B_4

Contour plot of displacement





Stokes flow problem



Governing equation: $\nabla^4 u(x) = 0$, $x \in \Omega$

Angular velocity: $\omega_1 = 1$

Boundary conditions:

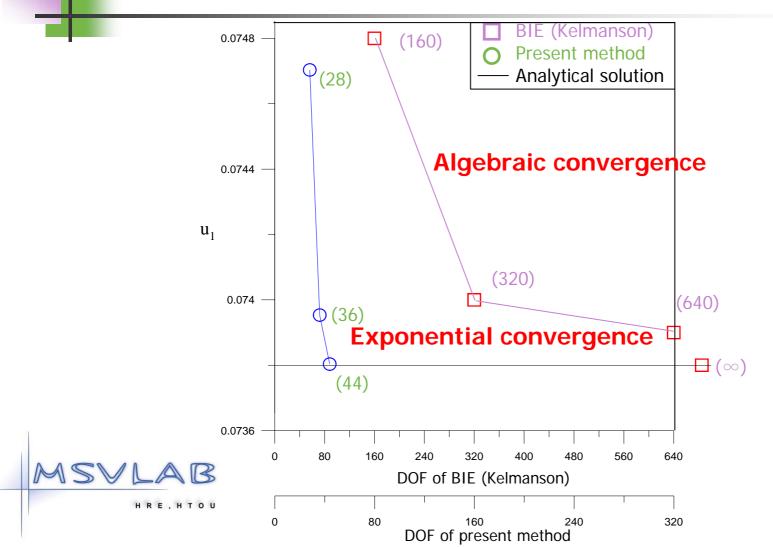
$$u(s) = u_1$$
 and $\theta(s) = 0.5$ on B_1

$$u(s) = 0$$
 and $\theta(s) = 0$ on B_2 (Stationary)

Eccentricity:
$$\varepsilon = \frac{e}{(R_2 - R_1)}$$

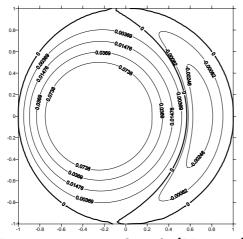


Comparison for $\varepsilon = 0.5$

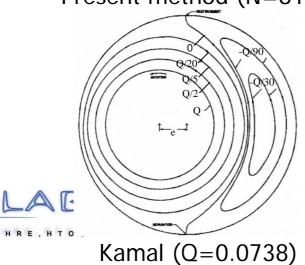


Contour plot of Streamline for

 $\varepsilon = 0.5$



Present method (N=81)



Kelmanson (Q=0.0740, n=160)

Outlines

- Motivation and literature review
- Mathematical formulation
- Expansions of fundamental solution and boundary density
- Adaptive observer system
- Vector decomposition technique
- Linear algebraic equation
- Numerical examples
- Conclusions





- A systematic approach using degenerate kernels, Fourier series and null-field integral equation has been successfully proposed to solve Laplace Helmholtz and Biharminic problems with circular boundaries.
- Numerical results agree well with available exact solutions, Caulk's data, Onishi's data and FEM (ABAQUS) for only few terms of Fourier series.



- Engineering problems with circular boundaries which satisfy the Laplace Helmholtz and Biharminic problems can be solved by using the proposed approach in a more efficient and accurate manner.
- Free of boundary-layer effect
- Free of singular integrals
- Well posed
- Exponetial convergence



The End

Thanks for your kind attentions.

Your comments will be highly appreciated.

URL: http://msvlab.hre.ntou.edu.tw/





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